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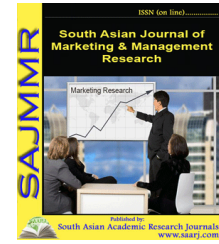
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The vision of the journals is to provide an academic platform to scholars all over the world to publish their novel, original, empirical and high quality research work. It propose to encourage research relating to latest trends and practices in international business, finance, banking, service marketing, human resource management, corporate governance, social responsibility and emerging paradigms in allied areas of management including social sciences , education and information & technology. It intends to reach the researcher's with plethora of knowledge to generate a pool of research content and propose problem solving models to address the current and emerging issues at the national and international level. Further, it aims to share and disseminate the empirical research findings with academia, industry, policy makers, and consultants with an approach to incorporate the research recommendations for the benefit of one and all.



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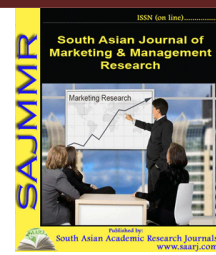
**SPECIAL ISSUE ON FUNDAMENTALS OF
TRANSFORMERS**

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AN ANALYSIS OF TRANSFORMER KEY FUNDAMENTALS

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ABSTRACT:

A transformer is a device that uses magnetic coupling to transmit electrical energy from one circuit to another without the need for relative motion between its components. It typically consists of two or more connected windings, and the core is almost always present to focus magnetic flux. An alternating voltage given to one winding produces a voltage in the other windings by producing a time-varying magnetic flux in the core. The ratio of the input and output voltages is changed by changing the relative number of turns between the primary and secondary windings, which changes the voltage by stepping it up or down between circuits. Faraday first proved the transformer idea in 1831, but it wasn't until the 1880s that a workable design could be made. The transformer played a crucial role in the "War of Current" that took place in less than ten years, helping alternating current systems defeat its direct current rivals and take control of the market ever since. The transformer dramatically lowers energy losses by converting electrical power into a high voltage, low current form, and back again, allowing for the cost-effective transmission of electricity over long distances.

KEYWORDS: Core Transformer, Ferrite Core, Power Transformer, Magnetic Coupling.

INTRODUCTION

A device that scales up or down voltage may be used to simply define the transformer. The output voltage is raised in a step-up transformer whereas it is lowered in a step-down transformer. To maintain an equal input and output power for the system, the step-up transformer will reduce the output current and the step-down transformer will raise the output current. The transformer, which is often employed in the distribution and transmission of alternating current electricity, is essentially a voltage control device. Michael Faraday originally broached the subject of a transformer in the year 1831, and many other eminent scientists continued his work after him. The fundamental goal of utilizing transformers, however, was to maintain equilibrium between energy produced at extremely high voltages and consumed at very low voltages. A transformer is a tool that is often used in the electrical and electronic fields. It is an electromagnetic apparatus that adheres to the fundamentals of electromagnetism, which Michael Faraday discovered. In a recent course, we went into great length regarding the design and functioning of transformers. We shall discuss several transformer types utilized in various applications in this article. However, although having various construction techniques, all kinds of transformers adhere to the same principles. You may also make your own transformer with a small amount of work, but you should always use transformer protection procedures while doing so[1]–[3].

Types of Transformers depending on Voltage

A transformer may be built in a variety of ways. The two electrically independent coils of a transformer may nevertheless conduct electricity through electromagnetic flux even when there is no electrical connection between the two sides. On both the main and secondary sides of a transformer, there may be many coils or windings. When two coils are linked in series on several principal sides, this configuration is known as a center tapped. The secondary side likewise exhibits this center tapped state. Transformers may be built such that the voltage level on the primary side can be converted to the secondary side. The transformer may be divided into three groups based on the voltage level. Step Up, Step Down, and Transformer Isolation. The voltage level for the isolation transformer is the same on both sides.

LITERATURE REVIEW

Saniya Khan et al. in, explored that solid-state transformers (SSTs) have become a more effective substitute for traditional transformers and are thought to be the foundation of the next-generation smart grid. They go beyond the restrictions of ordinary transformers by incorporating power electronics circuitry and high-frequency operation, which allows for great controllability and permits bi-directional power flow. In-depth examination of the solid-state transformer is provided in this work, which systematically discusses its foundations, converter topologies, applications, and potential future difficulties. The study describes the setup of SST and emphasises the need for better replacement of low-frequency transformers (LFTs). It examines the genesis and development of SST while presenting the foundations of SST in each level. Also covered are the fundamental topologies, their specifications, and control schemes. Along with contemporary uses, the applications of SST to replace LFTs are examined. The potential difficulties in implementing SSTs in real-time are examined, and research possibilities are suggested.

Li et al. in, discussed that an essential foundation for determining the state of a transformer is the fundamental frequency amplitude of the transformer surface vibration signal. It is crucial to precisely and promptly forecast the fundamental frequency's amplitude. In this research, a technique is put forward to improve the artificial bee colony algorithm's prediction of the fundamental frequency amplitude of transformer vibration. At the beginning of the artificial bee colony algorithm, an opposition-based learning mechanism is implemented and the search formula for each species of bee is enhanced. By using five common test functions and the fundamental frequency amplitude prediction of transformer vibration, the performance of the suggested technique is assessed. The suggested approach outperforms the original artificial bee colony algorithm in terms of search accuracy, convergence speed, resilience, and prediction accuracy, according to experimental data[4]–[6].

Andrea in, explored that the traditional method for controlling large electrical powers and distributing and converting electrical energy is to employ magnetic transformers. They are often big and unwieldy, making one question whether they can even work with integrated circuits. Their application in integrated circuits, however, is totally widespread. Complete wireless transceivers, frequency synthesisers, power management circuits, and power amplifiers are all implemented using them. They are in fact quite helpful since they enable ac coupling via galvanic separation and also enable single-ended to differential conversion, signal combining, and power combining.

David Ernesto et al. explored that Long-distance travel is not a barrier for visitors, who are increasingly interested in new and interesting experiences. This research was done to find out why visitors from other countries choose to travel considerable distances to Penang. This study, which used cluster random sampling and was carried out around the tourist sites of Penang, attracted a total of 400 respondents. But for this study, just 370 questionnaires were employed. The 22. Version of SPSS programme was used to examine the data. According to the research, "knowledge and novelty seeking" was what pushed foreign visitors to travel considerable distances to Penang. In the meanwhile, Penang's "culture and history" were the major draw for long-distance foreign travellers. Additionally, sociodemographic, trip characteristics, and travel motivation (push factors and pull factors) showed some direct and significant connections. Overall, based on sociodemographic data, trip details, and travel purpose, this research revealed the long-haul travel drivers for foreign visitors to Penang and has aided in understanding the long-haul travel market generally for Penang and Southeast Asia. This study made recommendations for an efficient marketing and promotion plan that would focus on providing the helpful information necessary to entice visitors from abroad to go long distances.

J Chen et al. provide a thorough review of the state-of-the-art Transformer-based approaches for medical imaging after briefly introducing the fundamentals of Transformers, particularly in comparison with convolutional neural networks (CNNs), and highlighting key defining properties that characterise the Transformers. We also demonstrate recent research advancements in the areas of medical segmentation, recognition, detection, registration, reconstruction, enhancement, etc. Our review stands out in particular for its organisation based on the Transformer's key defining properties, which are primarily derived from comparing the Transformer and CNN, and its type of architecture, which describes how the Transformer and CNN are combined. These features all aid readers in understanding the justification for the reviewed approaches. Future prospects are discussed as we draw to a close [7]–[10].

Xie et al. discussed that recently computer vision has made hopeful advancements thanks to the transformers. By enhancing the original pyramid vision Transformer (PVT v1) with three new designs, a linear complexity attention layer, an overlapping patch embedding, and a convolutional feed-forward network. We propose new baselines in this study. With these changes, PVT v2 significantly improves on basic vision tasks including classification, detection, and segmentation while reducing the computational cost of PVT v1 to linearity. Particularly, PVT v2 outperforms more contemporary efforts, such the swin transformer, in terms of performance. We anticipate that our effort will help advance computer vision studies on cutting-edge transformers.

Salman Khan et al. in, discussed that the vision community is interested in researching the applicability of Transformer models to computer vision issues because of their astounding performance on natural language tasks. Transformers have many advantages over recurrent networks, such as large short-term memory, including the ability to simulate lengthy relationships between input sequence parts and permit concurrent processing of sequence. Transformers, as opposed to convolutional networks, are well suited as set-functions and only need minor inductive biases for their construction. Transformers' simple architecture also makes it possible to handle other modalities, such as photos, videos, text, and audio, using the same processing blocks, and it exhibits great scalability to extremely high capacity networks and enormous datasets. Transformer networks have made great progress on a variety of vision tasks of their capabilities. This study tries to provide a thorough review of the Transformer models

used in the field of computer vision. The key ideas underpinning the success of Transformers, including as self-attention, extensive pre-training, and bidirectional feature encoding, are introduced first. Then, we discuss numerous applications of transformers in vision, such as well-known recognition tasks, generative modelling, multi-modal tasks (such as visual-question answering, visual reasoning, and visual grounding), video processing (such as activity recognition, video forecasting), low-level vision, and three-dimensional anamorphic vision.

Muhammad Farhan et al. discussed that an essential part of the current power distribution system are power transformers. The continuous delivery of electrical energy to customers depends critically on the fault-free functioning of step-up and step-down transformers. Power distribution firms do regular maintenance on distribution transformers according to predetermined timetables to maintain such efficient functioning. The effectiveness of such maintenance relies on a thorough knowledge of the transformer and its parts as well as accurate fault prediction in those parts. To forecast transformer failures and, therefore, the general health of a transformer, it is possible to examine the state of a number of components. These consist of ferromagnetic cores, insulations, transformer oil, core insulations, and transformer windings. This study creates a novel, more straightforward fuzzy logic-based technique to forecast a transformer's health by considering the condition of a number of different components. Case studies are utilised to show the effectiveness of the created technique.

DISCUSSION

Step back Transformers are used in both the electrical and electronic fields. The main voltage level is changed to a lower voltage across the secondary output by a step-down transformer. The proportion of main to secondary windings enables this. There are more windings on the primary side of step-down transformers than the secondary side. The total primary to secondary winding ratio will always be greater than 1. Numerous applications in electronics operate on 5V, 6V, 9V, 12V, 24V, or sometimes 48V. Step Down transformers are needed to reduce the 230V AC single phase power outlet voltage to the appropriate low voltage level. The Step-Down transformer is the main need for the Power section in instruments as well as in many other electrical kinds of equipment. In the circuits for mobile phone chargers and power converters, they are also used. Step down transformers are used in electrical systems that distribute electricity over long distances and operate at very high voltages to guarantee minimum loss and economical solutions. Step down transformers are used to convert high voltage into low voltage supply lines.

The step-up transformer is the same as the step-down transformer in every way. Transform the low primary voltage to a high secondary voltage using a step-up transformer. Once again, it is accomplished through the primary to secondary winding ratio. The primary winding to secondary winding ratio for the step-up transformer is still less than 1. This indicates that the secondary winding has more turns than the main winding. Step up transformers are often used in electronics' stabilizers, inverters, and other devices that convert low power to a much greater voltage. A step-up transformer is also used in the distribution of electrical power. For applications connected to power distribution, high voltage is necessary. In the grid, a step-up transformer is used to raise the voltage level prior to distribution.

No voltage levels are converted by isolation transformers. An isolation transformer's primary voltage and secondary voltage are constant. This is due to the fact that the ratio of the main and secondary windings is always 1. This indicates that the isolation transformer's main and secondary windings have the same number of turns. The main and secondary are separated using

an isolation transformer. In addition to serving as an isolation barrier where only magnetic flux may carry electricity, the transformer, as was previously described, has no electrical connections between the primary and secondary. It is used for safety reasons and to prevent noise from transferring from the main to the secondary or the opposite.

Types of transformers depending on the core material

By channeling electromagnetic flux via a core material, the transformer transmits energy. There are variations in flux density due to various core materials. Different kinds of transformers are used in the power and electronics industries, depending on the core materials.

Transformer with iron core

Multiple soft iron plates are used as the core of an iron core transformer. The iron's superior magnetic characteristics account for the iron core transformer's very high flux linkage. The iron core transformer has a high efficiency. The soft iron core plates come in a variety of sizes and forms. On a coil forming, the main and secondary coils were coiled or wrapped. After that, soft iron core plates are used to install the coil former. A variety of core plates are offered on the market depending on the size and form of the core. A few typical forms are E, I, U, and L. The real core is made up of several thick iron plates that have been grouped together. For instance, thin plates that resemble the letter E are used to create E type cores.

Ferrite core transformer

Due of its high magnetic permeability, a ferrite core transformer employs one. In the high-frequency application, this kind of transformer delivers very low losses. In high-frequency applications like switch mode power supplies (SMPS), RF-related applications, etc. ferrite core transformers are utilized. In addition, ferrite core transformers come in a variety of sizes and forms depending on the application. In contrast to electrical applications, it is mostly employed in electronics. Toroidal Core Transformer the E core is the most popular shape for ferrite core transformers. Iron core or ferrite core are two examples of the toroid-shaped core materials used in transformers. For their excellent electrical performance, toroid's, which have a ring- or donut-shaped core material, are often employed. The ring form in very low leakage inductance and very high inductance and Q factors. In comparison to conventional transformers with the same rating, the windings are much shorter and lighter.

Air Core transformer

The core material of an air core transformer is not a real magnetic core. The air is used only in the air-core transformer's flux linkage. The main coil of an air core transformer receives alternating current, creating an electromagnetic field all around it. According to the Faraday law of induction, a secondary coil placed within a magnetic field induces a magnetic field that is then utilized to power the load. Contrary to physical core materials like iron or ferrite core, an air core transformer has a low mutual inductance. Both portable electronics and radiofrequency-related applications utilize it. Its lack of a tangible core material accounts for its very low weight. A properly tuned air core transformer is also utilized in wireless charging systems, where the charger's main windings are built within and the target device's secondary windings are located.

Transformer Sorts according to Winding Arrangement

The winding orders of the transformer may be used to categories it. Auto Winding Transformers

are one of the most well-liked varieties.

Transformer with auto-winding

The primary and secondary windings have always been fixed, but with an auto-winding transformer, they can be linked in series, and the center tapped node may be moved. The secondary voltage may be altered by changing the location of the center tap. The auto is used to alert the self or a single coil and is not the abbreviation for Automatic. This coil creates a ratio using main and secondary components. The main and secondary ratio is determined by the location of the center tap node, which changes the output voltage. The VARIAC, a device that generates variable AC from a steady AC input, is used the most often. It is also utilized in applications connected to power transmission and distribution when it is necessary to swap high voltage lines regularly.

Transformers categorized by use

Transformers come in a variety of varieties, each of which operates in a distinct field. Depending on the application, different specialized transformers are employed in the electrical and electronics industries as step-up or step-down transformers. Thus, depending on their intended use, transformers may be categorized as follows:

1. Power Domain
 - a) Power Transformer
 - b) Measurement Transformer
 - c) Distribution Transformer

2. Electronics Domain
 - a) Audio Output Transformer
 - b) Pulse Transformer

Transformers employed in the power sector

The Power domain in Electrical is concerned with the production, measurement, and distribution of power. Transformers, however, are a crucial component in a very big field to allow for safe power conversion and effective power distribution to the substation and to the end customers. Transformers used in the electricity sector may be either outdoor or indoor, however outdoor transformers are more common.

Power Transformer

The energy is transferred to the substation or the general electrical supply using bigger power transformers. Between the major distribution grid and the power generator, this transformer serves as a link. Power transformers may be further divided into three groups based on their power rating and specification: small power transformers, medium power transformers, and large power transformers. For small rated power transformers, the rating may range from 30 KVA to 500–700 KVA, or in extreme circumstances, it can be more than 7000 KVA. Large rated power transformers can take more than 100 MVA, whereas medium rated power transformers can handle up to 50–100 MVA. The building of a power transformer is also essential due to the very

high-power production. A reliable cooling system and sturdy insulating peripherals are included in the structure. The majority of power transformers are lubricated.

The power transformer's principal function is to convert low voltage, high current energy into high voltage, low current energy. To reduce the amount of electricity lost in the power distribution system, this is necessary. The phase availability is another crucial factor for the power transformer. Although modest single phase power transformers are sometimes employed, power transformers are typically three phase devices. Compared to single phase power transformers, three phase power transformers are more expensive and efficient.

Transformer Measurement

Instrument transformer is another name for measurement transformer. This is another measuring tool that is often employed in the power domain. To separate the primary power and convert the current and voltage in a lower ratio to its secondary output, a measuring transformer is used. Phase, current, and voltage of the real power line may be determined by monitoring the output.

Transmission Transformer

The last stage of the power distribution system makes advantage of this. Distribution transformers function as step-down transformers, converting high grid power to the appropriate voltage for the end user, often 110V or 230V. Additionally, it might have one phase or three stages. Depending on the conversion capacity or ratings, distribution transformers might be less in size or larger. Depending on the kind of insulation they utilize, distribution transformers may be further divided into several categories. It might be a dry variety or one that is submerged in liquid. As a core material, it is manufactured from steel plates that have been laminated and are often shaped like Cs. The location in which a distribution transformer is employed determines a particular sort of categorization for it. It is known as a pole mounted distribution transformer if the transformer is positioned on a utility pole. It may be positioned within a chamber that is buried under the earth, installed on a concrete pad (pad mounted distribution transformer), or housed inside a steel box. Distribution transformers typically have a rating of under 200 kVA.

Transformer utilized in electronics field

Different tiny micro transformers are used in electronics; they may be fitted within a small product container or put on a PCB.

Pulse Transformer

One of the most popular PCB mounted transformers that generate electrical pulses with a consistent amplitude are pulse transformers. It is used in a number of digital circuits when the demand for isolated pulse creation exists. Therefore, the primary and secondary are separated by the pulse transformers, which then send primary pulses to the secondary circuit, which is often composed of digital logic gates or drivers. A well-built pulse transformer should have minimal leakage and stray capacitance as well as good galvanic isolation.

Transformer for audio output

Another frequent transformer in the electronics industry is the audio transformer. It is specifically employed in applications involving audio where impedance matching is necessary. The amplifier circuit and loads, usually a loudspeaker, are balanced by the audio transformer. The main and secondary coils of the audio transformer may be spread out or center-tapped.

CONCLUSION

Electric transformers are non-active electrical devices that generate an electromotive force using magnetic flux. To step-up or step-down voltages between electrical systems, transformers are utilized. By adjusting voltage levels as required. Transformers help electricity systems be more reliable and efficient. They are used in several domestic and commercial settings, but possibly their most crucial function is in the long-distance distribution and control of electricity. The control and efficiency of a single-phase transformer are thus accessed via OC as well as SC testing. The parameters of the corresponding circuit are discovered. Transformers play a significant role in the transmission and distribution of power. To regulate voltage and current in the electrical system, they rely on the mutual and electromagnetic induction theories. Transformers come in a variety of varieties, each created for a particular need. Modern transformers require regular maintenance and testing, and transformer neural network models are employed in numerous applications.

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EXPLORING THE ROLE OF TRANSFORMER IN POWER SYSTEM

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ABSTRACT:

The transformer, which changes voltage levels, is the heart of the electrical system. The novel approach to load management at the consumer or distribution sides is presented in this chapter. It is suggested to use an automatic load-sharing approach to transfer the load from one consumer side transformer to another slave transformer during periods of high load or when the transformer is malfunctioning. The suggested solutions share a person's burden using a microcontroller and relays. Transformers are a significant part of the power transmission and distribution system overall. They allow the transmission of electric power at high voltages, reducing the loss due to wire heating, and they transfer electrical energy from one electrical circuit to another electrical circuit or many electrical circuits. Transformers come in a variety of varieties, each created for a particular need. Without transformers, it would be difficult to create the massive power networks that are used today.

KEYWORDS: *Low Voltage, Power Transformer, Power System, Primary Winding, Step Down, Transformer Oil.*

INTRODUCTION

Power may be transferred from one circuit to another using a power transformer without affecting the frequency. A transformer is categorised as a static device since it has no spinning or moving elements. Transformer uses an AC source to operate. Mutual induction is the underlying idea behind how transformers work. Power transformers are electrical devices used to transport electrical power without altering the frequency from one circuit to another. They function according to the electromagnetic induction theory. They are used in the electrical power transmission process between major distribution circuits and generators. In distribution networks, power transformers are used to step up or step down the voltage. These instruments are regarded as static devices since they don't have any rotating or moving components. The electrical system that powers these equipment uses alternating current (AC) [1].

A power transformer is simply a categorization of transformers with a rating over 200 MVA and a voltage range ranging from 33 kV to 400 kV. Power transformers are available on the market with voltage ratings of 400 kV, 200 kV, 110 kV, 66 kV, and 33 kV. Distribution (230 V-11kV) and instrument transformers are among the other kinds of transformers. When transmitting huge quantities of electrical power over long distances, power transformers are crucial for minimising significant energy losses caused by Joule's effect. They achieve this by turning the power into high-voltage current and then stepping it down to a safer low-voltage current. They may often be found in industrial facilities, power plants, and electric utility businesses [2].

Electromagnetic Induction

The electromagnetic induction law of Faraday is the basis for how power transformers work. All transformers, inductors, motors, generators, and solenoids operate according to this rule. According to Faraday's law, a closed-loop will create an electromotive force (emf) across it when it is placed close to a fluctuating magnetic field. An alternating or fluctuating magnetic flux envelops the coil (primary winding) when alternating current is permitted to pass through it [3]. A ferromagnetic core is necessary for the main winding's magnetic flux to successfully transfer to a secondary winding. Due to electromagnetic induction, the magnetic flux will then cause an emf in the secondary winding. The secondary winding's current will be stimulated by the produced EMF.

Staggered voltages Right or Left

The voltage per coil turn multiplied by the number of turns equals the overall voltage in a winding [4]. The induced voltage in the secondary winding may be connected to the input voltage on the primary winding since the voltage per turn of the primary and secondary windings is the same. The subscripts p and s denote the main and secondary windings, respectively, and V denotes the total voltage present in the winding. A winding has N turns. The turn's ratio (N_s/N_p) is the ratio of the secondary winding's turns to the primary winding's turns. The voltage output is lower than the input voltage (step-down transformer) if the secondary winding has fewer turns than the primary winding; on the other hand, the voltage output is higher than the input voltage (step-up transformer) if the secondary winding has more turns than the primary winding.

LITERATURE REVIEW

Liu et al. in [5], discussed that the transformer is the component of the power system that is most important. The research and development of fault diagnostic technology for Internet of Things equipment can accurately ascertain the state of equipment operation and promptly fix any hidden issues, which helps to reduce the frequency of accidents and improves people's level of life safety. Consider the Internet of Things' possible uses for detecting power transformer breakdown. Methods: A total of 30 groups of transformer failure cases were selected; 10 groups were randomly selected for network training, and the remaining samples were used for testing. The correlation function was improved in line with the characteristics of the three-ratio approach, and the mathematical model of matter-element extension for power transformer defect detection was developed. Each set of power transformers conducted continuous diagnostic testing for four months, and the data and findings from the monitoring were compiled and evaluated. The GPRS communication network completes the link between the data collecting terminal and the monitoring terminal. The instrument driver module controls a variety of sensors to complete the diagnostic of the transformer failure system, and the operating state of the apparatus is modified in line with database settings. The power transformer fault diagnosis system model created in this research can correctly identify the fault types in samples that weren't used for training and has a detection success rate of up to 95.6%. It also has a training error of less than 0.0001. It is obvious that the technological support provided by the Internet of Things is helpful for upgrading and maintaining the system for identifying power transformer failures.

Ker et al. explored that one of the key pieces of equipment in the network for power transmission and distribution is the power transformer. For a reliable supply of electricity to utilities, it is crucial to guarantee that the power transformer is operating at its peak efficiency. The

transformer insulation system, which consists of transformer insulation oil and transformer insulation paper, is one of the essential parts of a power transformer. An extensive description of the reactions that take place in the power transformer's insulation system is provided in this review. These include partial discharge, arcing, hydrolysis, pyrolysis, oxidation, and hydrolysis. In this review, the reaction mechanisms, environmental factors, and connections between these reactions are all carefully examined. In addition, this paper includes a thorough explanation of the most recent techniques for keeping track of the byproducts produced by the aforementioned processes. These techniques were created to get around the complexity and expense of traditional approaches. It also offers a fair assessment of the difficulties and opportunities for improving the power transformer monitoring system's time and cost effectiveness. It is anticipated that information confirmed in this analysis will serve as a crucial road map for future research on power transformer condition monitoring [6].

Hulaj et al. discovered that power transformer health assessment methodologies and technology have advanced significantly in recent years. The monitoring system enables constant investigation into the operational work of power transformer parameters in order to prevent failures and enhance dependability. Power transformer monitoring is nonetheless crucial for improving supply reliability for consumers and electrical power networks. As a consequence, given that monitoring involves a significant number of parameters and transformer components, a summary of the monitoring of some of the most important parameters has been taken into account in the present example. Partial discharges, oil and winding temperatures, bushing currents, tap changer, moisture analysis, and dissolved gas analysis are therefore some of the monitoring variables included in the research. The research also includes information on how these metrics performed at different points in time and under varied loading conditions. Additionally, reports of occurrences that pertain to the operational performance of the transformer and serve as a strong foundation for diagnostic and preventive actions in transformers are supplied [7].

Zhao et al. discussed that in recent years, power networks have installed an increasing amount of distributed energy resources, particularly renewable energy resources (RESs). These RESs, such as solar photovoltaic systems and wind turbines, provide operators chances to boost power system resilience, improve power quality, and contribute to the achievement of green energy objectives. But RESs can provide difficulties for the operators. As RESs operate under a wide range of situations, power systems may suffer more dynamic behaviour than conventional power systems with fewer RESs. Devices in power systems may be affected by such dynamics. Transformers need to be secured and closely watched since they are one of the most costly and important parts of power systems. This being the case, transformer monitoring and protection are important and crucial in the power system sector as well as in academic study. This study provides a thorough analysis of the current transformer monitoring and protection techniques. As historical low frequency transformers continue to play a significant role between low frequency interfaces, the study first discusses monitoring and protective measures for these transformers. The literature on the protection of solid-state transformers (SSTs), also known as transformers based on power electronics, is then researched. Following is a summary of current transformer monitoring and protection technologies [8].

Yuzhong et al. in [9], discussed that using the same frequency, the transformer may change one kind of electric energy, such as AC current and voltage, into another type of energy. Knowledge graphs (KGs) are thought of as semantic networks for power system transformers because they

can explain a variety of real-world things and ideas, as well as their interactions. The analysis and design of the power system transformer standard based on the knowledge graph are thus crucial. In order to do this, we first look at the power system transformer with one KG node and one eavesdropper E. Since the eavesdropper E may listen in on the network from the source, this might in a physical-layer security vulnerability and an event that increases the likelihood of an outage. We define the outage probability for system security by giving an analytical formulation of outage probability and analyse and design the system secure performance under the eavesdropper to address the problem. We look at the power system transformer with numerous KG nodes in more detail since it may improve the security and dependability of the system. By offering an analytical formulation of outage probability, we define the outage probability for system security and analyse and design the system's secure performance under the eavesdropper. Finally, we provide some simulations to assess how the secure transformer standard would affect the power system and to validate the validity of our analytical formulation for the power system transformer standard based on the knowledge graph [10].

Cadoux et al. discussed that power transformers may be more correctly sized by their thermal limitations than by their rated power limits, as has previously been shown in the literature. Thermal limitations, however, are often only taken into account during operations; they are not taken into account during the design stage, when the more common concept of rated power is employed. This research suggests a unique approach to consider (and profit from) thermal restrictions right at the design stage. This is made feasible by calculating the individual effects of each generator and load on the distribution transformer's temperature. The analytical formula of the hot-spot transformer temperature is linearized and rewritten to disentangle the influence of specific generators and loads. By evaluating the increase in the hosting capacity of the investigated transformer for extra generators and loads, the method's applicability is evaluated using a real-world dataset. When the transformer is scaled by generation, especially when photovoltaic (PV) generators are included, significant advantages are gained.

Borucki et al. in [11], discussed that the SPOTEL system, which is described in this article, is an innovative data gathering and transmission system created and optimised for online temperature monitoring systems in electric power transformers. The primary goal of this study is to assess a cost-effective system that is built on open-source components and a modular hardware architecture, providing the highest reliability and data safety and security criteria, and enabling it to be used in challenging industrial environments. The proposed system architecture is provided in full, including information on its hardware and software implementations. Finally, its straightforward reliability analysis and practical on-site deployment have been given. As a consequence, SPOTEL was able to demonstrate its dependability and usefulness for on-line temperature monitoring features that are often lacking in competing solutions and it is currently being used in several hundred transformers from the target population.

DISCUSSION

Power transformer use

Low voltage electrical power generation is highly economically advantageous. The sending end might theoretically receive this low voltage level electricity. When this low voltage electricity is transferred, more line current flows, which in turn increases line losses which lowers the system's ohmic or I^2R losses, reduces the cross-sectional area of the conductor, lowers the system's capital cost, and enhances voltage regulation. In order to transmit electrical power

effectively, low level power has to be increased [11]. At the sending side of the power system network, a step-up transformer carries out this function. This high voltage electricity must be stepped down to the necessary level at the receiving end with the aid of a step-down transformer since it cannot be supplied straight to the consumers. Thus, the electrical power transformer is essential for the transfer of electricity. In situations when the ratio of high voltage to low voltage is larger than 2, two winding transformers are often used. When there is a ratio of less than 2, between high voltage and low voltage, auto transformer is the most economical option.

Transformer types

Transformers may be grouped in a variety of ways based on their application, construction, function, etc. Be aware that occasionally these categories overlap; for instance, a transformer may function simultaneously as a step-up transformer and a three-phase transformer. Some of the top books on electrical engineering go into further depth on transformer operation for more information.

Step-Down and Step-Up Transformers

Step up transformers change the low voltage (LV) and high current values on the transformer's primary side into the high voltage (HV) and low current values on the transformer's secondary side. Step down transformers change the high voltage (HV) and low current value on the transformer's primary side to the low voltage (LV) and high current value on the transformer's secondary side. Due to its lower cost than single phase transformers, a three-phase transformer is often utilised in three phase power systems. However, a bank of three single phase transformers is preferred than a single three phase transformer when space is an issue since it is simpler to carry. Transformers for electrical power, transformers for distribution, and transformers for instruments. In a transmission network, power transformers are often employed to step up or down the voltage level. It works best at or close to full load and mostly at high or peak loads. For the purpose of distributing power to residential or business consumers, distribution transformers scale down the voltage. It features superb voltage control and runs 24 hours a day at 50% of full load for optimal efficiency. C.T. and P.T. instrument transformers are used to lower high voltages and current to smaller values that can be monitored by standard instruments.

Autotransformer with Two Winding Transformer

Where the ratio between the high voltage and low voltage side is larger than 2, a two winding transformer is often utilised. When the ratio between the high voltage and low voltage sides is less than 2, an autotransformer is more economical.

Transformers both inside and outside

Outdoor transformers are intended for installation outside, as their name suggests. Interior transformers, on the other hand, are intended for interior installation.

Oil cooled and dry type transformer

Transformer oil serves as the cooling medium in oil-cooled transformers. In contrast, air cooling is employed in dry type transformers. Transformer windings come in two primary varieties: core type and shell type. There are other converters in the berry style. A core type transformer includes two horizontal portions called yokes and two vertical legs or limbs. The core has a

common magnetic circuit and is rectangular in form. On both limbs, cylindrical coils (HV and LV) are positioned.

Transformer of Shell Type

Two outside limbs and a core limb make up a shell-type transformer. The middle limb is equipped with both LV and HV coils. There is a twin magnetic circuit.

Transformer of Berry Type

The core of a transformer of the Berry type resembles a wheel's spokes. This kind of transformer is housed in tightly fitting metal sheet tanks that are full with transformer oil.

Power transformer components

The main and secondary windings, as well as the core, are the fundamental components of transformers and are covered in further depth in this chapter.

Essential Elements

The core acts as both a structural support for the windings and a low-reluctance channel for the magnetic flux. Thin steel sheets are laminated and stacked to create it. A covering separates the sheets from one another. The iron or steel sheets are less than one millimetre thick, and their carbon content is kept below 0.1% to minimise hysteresis losses and eddy current losses. By incorporating silicon into the steel alloy, eddy current is further reduced. The term "limbs" refers to the vertical portions of the core in which the windings are carried, while "yokes" refers to the horizontal portions of the core that join the limbs.

Power transformer windings

A specified number of turns of copper or aluminium conductor coil make up the windings. Due to its high electrical conductivity and ductility, copper is the ideal material since it requires less winding and is simpler to wrap around the core. The main and secondary windings make up a transformer's minimum number of windings. The winding to which the input voltage is applied is known as the primary winding, and the winding to which the output voltage is supplied is known as the secondary winding. A transformer's phase's main and secondary windings may function as either the high voltage (HV) winding or the low voltage (LV) winding. The HV winding compared to the LV winding, the HV winding has more turns and is made of a thinner conductor. The LV winding has fewer turns. Given that the LV winding carries a larger current than the HV winding, it has a thicker conductor than the HV winding. The following are additional power transformer components.

Insulating Resources

The main and secondary windings, as well as each winding turn, are all isolated from the core by means of insulating materials. These components shield the transformer from harm. High dielectric strength, superior mechanical qualities, and the ability to endure high temperatures are required for transformer insulators. Although paper and pressboard may be used as insulators (i.e., dry-type transformers), their service lifetimes are limited and they need to be replaced often since these materials might deteriorate. Transformative oils are thus more prevalent than solid insulating materials. They function as a coolant for the coil and winding assembly, provide improved insulation between conducting elements, and contain fault detecting functions.

Transformer oils are hydrocarbon mineral oils made up of aromatics, paraffin, naphthenic, and olefins. To maintain the oil's insulating and dielectric qualities, contamination must be avoided.

Tap Switcher

Tap changers alter the number of turns in one winding to control the transformer's output voltage as it reacts to the fluctuating input voltage and load. The turn ratio is altered of this alteration. The output voltage rises while unloading is taking place, whereas it falls when the system is loaded. In the HV winding, tap changers are often attached to perform precise voltage adjustments and reduce core losses in the transformer. The HV winding's reduced current also reduces the chance of sparking and burning the transformer oil.

Transformer bushings

Bushings are insulated barriers that house the terminal connecting the extremities of the transformer windings to the current-carrying cable from an electrical network. Usually constructed of porcelain or epoxy resin, bushing insulation. Mounted above the main tank are the bushings.

Tank Transformer

The core, windings, and other components are housed in the transformer tank (also known as the main tank), which shields them from the outside environment. It acts as the transformer oil's storage container. It is made of aluminium or steel sheets that have been rolled.

Component of a conservator

Above the main tank and bushings is a tank called the conservator, as a reservoir for the transformer oil through a conduit, the main oil tank within the transformer receives transformer oil from the conservator the bladder of the conservator is flexible, allowing the oil to expand and shrink as needed It provides enough room for the oil to expand when the temperature is high outside. In order to counteract the pressure variations caused by the oil's expansion and contraction, the conservator is vented to the atmosphere.

Breathing Mechanism

The breather circulates air through a thin layer of silica gel within a cylindrical container to supply dry air to the conservator. The silica gel functions as an air filter to remove moisture from the conservator and the main tank and to regulate its level. A pipeline links the conservator and the breather. Moisture might cause internal defects or worsen the transformer oil's insulating capabilities. Moisture removal is required. Regardless of the insulating material used, the cooling system is an essential part of transformers. Transformer power losses take the form of heat, which raises the temperature of the core and windings. The insulating material's temperature will likewise rise. These parts could get harmed or disintegrate if heated continuously without a cooling device. Fans, radiators, and cooling tubes make up the transformers' cooling system. Natural and/or forced convection, as well as radiation, are the two main methods of heat transmission.

Detonation Vent

A metallic pipe with a diaphragm at its free end serves as the explosion vent, which is situated just above the conservator tank. During internal failures, it releases gases, transformer oil, and energy to alleviate the build-up of pressure within the transformer and stop it from exploding.

The transformer's internal pressure is dangerously increased by faults. The diaphragm will be destroyed at a relatively low pressure when such conditions arise because energy will be released into the atmosphere. The pipeline that connects the conservator and the main tank has a Buchholz relay fitted along it. By detecting the gases released, it may trigger the trip and alarm circuits to find defects in the transformer. The circuit breaker will stop the current flow to the primary winding once the trip circuit is turned on. Heat produced by faults causes the production of emitted gases.

CONCLUSION

By transforming electricity from a high voltage (transmission line) to a low voltage (consumer), transformers are essential components of the power system. By transforming enormous amounts of electrical power into high-voltage current and then stepping it down to a safer low-voltage current, transformers are crucial in minimising significant energy losses in the transmission of electrical power over long distances. Transformers play a significant role in the transmission and distribution of power. They are effective, easy to use and maintain, and allow for the transfer of electricity at high voltages, which lowers the loss brought on by wire heating. They are employed in many different places, such as power plants, substations, distribution networks, and industrial machinery.

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OPEN CIRCUIT AND SHORT CIRCUIT TEST OF TRANSFORMER

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ABSTRACT:

Transformers with high leakage rates are crucial for converting electricity. Transformers for signal and power applications in high-frequency power supply are now being developed as on-chip, silicon-integrated, and printed wiring board-integrated devices. Electric car batteries may now be charged inductively thanks to the development of high-power transformers. In comparison to ordinary transformers, these transformers may have comparatively large core loss, leakage inductances, and winding resistances. These rather high parasitic transformers can only be characterized to a limited extent using the traditional open-circuit and short-circuit test calculations. The differential (series-opposing) and cumulative (series-aiding) series-coupling tests are created and used in this study to accurately characterize the resistive and inductive parts of transformers.

KEYWORDS: Copper Loss, Load Current, Main Winding, Open Circuit, Short Circuit.

INTRODUCTION

By being aware of all the comparable circuit characteristics, it is feasible to forecast how a transformer would operate under different loads. These circuit characteristics are provided in terms of a transformer's Open Circuit (OC) and Short Circuit (SC) test data. These two evaluated tests provide the test that are utilized to establish the equivalent circuit characteristics without actually loading the transformer. These variables make it simple to predict the efficiency and control of the transformer under any power factor and load state. The Indirect Loading Method is the name given to this technique for determining a transformer's parameters. This chapter details how to conduct these tests, how to calculate the equivalent parameters from test, and if it is more important to execute the computation on the HV or LV side.

Short circuit test technique

The transformer's low-voltage (LV) side, also known as the secondary, is short-circuited, thus the test is done on the high-voltage (HV) side of the transformer. The main side is linked to a wattmeter. The main winding is coupled to an ammeter in series. Since the applied voltage and the voltmeter reading are identical, a voltmeter is not necessary. The applied voltage is now gradually raised until the ammeter registers a reading equal to the HV side's rated current. Voltmeter, Ammeter, and Wattmeter measurements are all recorded after the HV side's rated current has been reached. The major equivalent of full load current I_L is provided by the ammeter measurement. The iron losses in the transformer may be regarded as minimal in this case since the voltage supplied for full load current in the short circuit test on the transformer is

fairly low compared to the rated primary voltage of the transformer.

The image displays the connecting diagram for the transformer's open circuit test. The transformer's LV side has voltmeters, wattmeter, and ammeters connected as depicted. With the aid of an auto transformer with a variable ratio, the voltage at the specified frequency is applied to that LV side. The transformer's HV side is left exposed. The applied voltage is now gradually raised with the aid of a variance until the voltmeter registers a reading equal to the rated voltage of the LV side. We record the data from all three instruments (the Voltmeter, Ammeter, and Wattmeter) once the LV side voltage reaches the specified level. The open-circuit test's objective is to ascertain the transformer's no-load current and losses, from which its no-load characteristics are derived. The transformer's main winding is the subject of this examination. They have connections to their main winding for the wattmeter, ammeter, and voltage. Their main winding receives the nominal rated voltage from the ac source.

The transformer's secondary winding is left open, and a terminal on the voltmeter is attached to it. The secondary induced voltage is measured using this voltmeter. No-load current passes through the transformer since the secondary is open. When compared to the full rated current, the value of the no-load current is quite low. Because the secondary winding of the transformer is open, the copper loss solely affects the primary winding. The wattmeter's measurement solely accounts for core and iron losses. For all kinds of loads, the transformer's core loss is the same.

LITERATURE REVIEW

Karlo et al. [1], explored that vibrations on the tank wall, stiffeners, and cover of an experimental 5 MVA transformer model were monitored during short- and open-circuit transformer testing. In a no-load test, individual vibration measurements of a transformer tank side were made using two distinct voltage sources. For each measurement setup, the RMS values of acceleration and vibration velocity are visualised and compared using interpolation methods. At various frequencies, it is noticed that there are significant changes in the mode shapes and vibrational amplitudes. In the open-circuit test, the highest RMS values for acceleration, velocity, and displacement are 0.36 m/s², 0.31 mm/s, and 0.42 m, respectively. In a short-circuit test, the highest values are 0.74 m/s², 1.14 mm/s, and 1.8 m, respectively. The 100 Hz frequency component dominates the short-circuit test. The first several 100 Hz harmonics in the open-circuit test 100 Hz, 200 Hz, and 300 Hz, are important.

Nwankpa et al. explains how to run transformer open-circuit and short-circuit testing using MATLAB/Simulink to get similar circuit characteristics. These simulation models were created to help and improve undergraduate instruction in electric machinery [2]. Wang et al. explored that one of the most essential components in electrical networks are power transformers. The dependability of the electricity system is directly impacted by the transformers' ability to operate safely. It is crucial to detect the transformer's internal deformation as soon as feasible. Sweep frequency impedance (SFI) approach has been employed as a novel methodology to identify the transformer winding's short-circuit defect. Therefore, the SFI approach is examined in this research to identify an onsite transformer open-circuit failure. The open-circuit problem of this transformer winding is identified by carefully examining the SFI curves and SFI values at power frequency produced by the SFI test. In the meanwhile, the findings of the short-circuit impedance (SCI) and winding resistance measurements are presented in order to confirm the correctness of the diagnostic based on the SFI approach. The use of the SFI approach to identify an open circuit fault in a transformer winding not only advances the field's understanding of the technique but

also has significant practical implications for fault detection [3].

Zhang et al. in [4], discussed that AC/DC hybrid distribution networks, power electronic transformers (PETs) are crucial components. However, a PET has a greater failure probability due to the employment of several power electrical equipment. Although insulated gate bipolar transistors (IGBTs) in the cascaded H-bridge (CHB) have been the subject of most open-circuit fault investigations, a PET's short-circuit protection is still comparatively inexperienced. As a consequence, various kinds of open-circuit failures cause dead zones in the process of locating the problem. The open-circuit fault characteristics of switch elements at various points of a PET are examined in this article, and a protection circuit is created to guard against any potential overvoltage brought on by the open-circuit fault in the CHB. Additionally, approaches for locating switch element open-circuit failures are suggested. The suggested techniques might adjust to a variety of control modes, power flows, and load intensities. Simulation experiments are used to confirm the approaches' accuracy and efficacy. The foundation for fault-tolerant control and protection of PETs is provided by this study.

Martin et al. in [5], discussed that Chaotic Optimisation Approach (COA) is used to estimate the parameters of a single-phase transformer equivalent circuit. For the best possible fit between the measured and estimated transformer output characteristics, unknown transformer equivalent circuit parameters must be precisely approximated. In this research, the usage of COA is assessed on both forms of input data, in contrast to existing methods that employ various estimating methodologies and are based either on the nameplate data or the load data derived from tests. The COA-based parameter estimate is compared to several literature methodologies as well as to the conventional method based on open-circuit and short-circuit testing for two single-phase transformers that vary in terms of machine power and voltage levels.

Mohammad et al. in [6], discussed that the electromagnetic transient (EMT) modelling of industrial size (i.e., 50, 390 MVA) multilimbed transformers is done using the duality concept. The necessity for transformer internal design information, such as core diameter or material, is avoided while saturation, hysteresis, deep saturation, and remanent flux are taken into consideration. To do this, similar circuits are created using a different set of parameters that are either supplied by the manufacturer or may be found using standard methods. When compared to measurement findings, open-circuit experiments show that the models generate correct excitation currents at various saturation levels. Additionally, the models support any number of windings and enable the proper short-circuit situation. After the models have been validated, inrush current is simulated to establish the worst-case scenario given plausible remanent flux values. The are consistent with both manufacturer analytical estimates and a well-known EMT simulation model. Investigations into simulated hysteresis loops are also made.

Phung et al. in [7], investigated that there is growing concern about how harmonic pollution in the electrical system affects distribution transformer losses and temperature increase. The supply networks' harmonic current or voltage flow may be the source of the pollution. This research investigates the effects of distorted voltage excitation on oil-filled distribution transformers since the impacts of voltage harmonics have not been extensively studied. Two distribution transformers were subjected to short-circuit and open-circuit testing. The findings showed a considerable rise in temperature and losses. To calculate the power loss, an equation is devised. An equation to assess the resistance corresponding to the eddy-current loss is also derived in this work.

Goran et al. in [8], explains the power transformer's fundamental method of operation, components, and structure. The definition of equivalent circuit parameters and an explanation of how to determine them are provided. Simulink was used to create a transformer model, and the creation process is detailed. After then, tests with open and short circuits were used to imitate the constructed transformer model. Comparisons between the parameter values acquired from simulation and the real values allowed for the drawing of conclusions. The primary objective of this research is to evaluate the accuracy of the operation of the Simulink transformer model. Based on the findings, algorithms for evaluating the performance of the complete power system may be developed using the same model.

Henrique et al. discussed that it is common practise to compute the corresponding steady-state model parameters from measurements received during transformer testing. These parameters are subsequently used to load flow simulation and other modelling applications. The most frequent tests used for this are short circuit and open circuit tests, which enable calculation of series and parallel branch transformer properties. In this work, an expanded model is put out that clearly accounts for transformer connection resistance and does not use the cantilever circuit approximation that is often assumed. Utilising extra data obtained from the direct current (DC) resistance test allows for an assessment of the proposed model's input parameters. An experiment performed on a genuine distribution power transformer serves as a proof-of-concept for the suggested method, and the findings show that the proposed model and parameter calculation methodology efficiently partition total transformer resistance into winding and contact components. The numerical findings further demonstrate that contact resistance, particularly for low voltage windings, is not trivial, which further supports the utility of the proposed model in giving accurate modelling of transformer resistances.

DISCUSSION

The transformer's secondary is left open-circuited. The main is linked to a wattmeter. The main winding is coupled to an ammeter in series. Since the applied voltage and the voltmeter reading are identical, a voltmeter is not necessary. The main is receiving the rated voltage. Normal flux will be established if a normal voltage is provided. Normal iron loss will happen since iron loss depends on the supplied voltage. Therefore, at rated voltage, iron loss is at its highest. The wattmeter is used to determine this maximal iron loss. All of the input voltage is lost over the excitation branch because the transformer's series winding has a very low resistance in comparison to the excitation branch. So, the wattmeter simply records iron loss. Only the total iron losses, which include the eddy current loss and the hysteresis loss, are measured by this test. The hysteresis loss is not insignificant, even if it is smaller than the eddy current loss. Since the hysteresis loss changes linearly with supply frequency and the eddy current loss varies with the frequency squared, the two losses may be distinguished by operating the transformer from a source with a varied frequency.

Hysteresis and loss of eddy currents

The primary of the transformer only draws no-load current, which has some copper loss since the secondary of the transformer is open. Since the copper loss in the primary is inversely proportional to the square of this no-load current, it is insignificant. Since there is no secondary current, there is no copper loss in the secondary. There is no load on the secondary side of the transformer since the secondary side is left open. In this approximation, power is no longer transmitted from primary to secondary, and only very little current flows through the secondary

windings. No magnetic field is produced since no current flows through the secondary windings, and no magnetic field also implies that no current is generated on the main side. The series impedance may now be ignored since it is assumed that no current flows through it, which is essential to the approximation. The analogous circuit diagram's parallel shunt element is used to represent the core losses. These core losses from eddy currents and flux changes in direction. Eddy current losses are brought on by currents that the iron experiences of the alternating flux. The series component in the circuit diagram, as opposed to the parallel shunt component, shows the winding losses brought on by the transformers coil windings' resistance.

Test for Short Circuit

To determine the transformer's below-mentioned property, a short circuit test is conducted.

- a) It establishes that copper losses happen when the load is full. The transformer's efficiency is determined using the copper loss.
- b) The short circuit test may determine the equivalent resistance, impedance, and leakage reactance.

On the secondary or high voltage winding of the transformer, a short circuit test is conducted. The high voltage winding of the transformer is linked to measurement devices like wattmeter, voltmeters, and ammeters. With the assistance of a thick strip or ammeter that is linked to its terminal, their main winding is short-circuited. Due to the low voltage source's connection across the secondary winding, the transformer's secondary and primary windings both experience full load current flow. The ammeter linked across their secondary winding measures the whole load current. Approximately 5 to 10% of the typical rated voltage is delivered across the secondary winding by the low voltage source. The transformer's core is where the flux is installed. When compared to the average flux, the flow's size is tiny. The flux affects the transformer's iron loss. Due to the low flux value, short circuit tests don't happen as often. Only the copper loss that happened in their windings is determined by the wattmeter value. The voltage supplied to their high voltage winding is measured by the voltmeter. Because of the applied voltage, the transformer experiences a secondary current.

Test for polarity

To determine the polarity of the transformer windings, a polarity test is performed. Similar polarity refers to the endpoints of two transformers that simultaneously acquire positive or negative polarity. To connect the winding correctly, one must be aware of its polarity.

Method 1: Connection and polarity test technique

- a) The end of the main winding (let's say a1) is linked to one end of the secondary A1.
- b) Intersect the other two ends (a2 and A2) using a voltmeter.
- c) Connect the primary windings a1 and A1 to a voltage now.

The polarities of A1 and a1 are the same if the voltage measured by the voltmeter is $V1V2$, and A1 and a2 are the same if the voltage read is $V1 + V2$.

Method 2: Using DC flashing

While testing the transformer in the field, a DC flashing test is employed. A DC battery with a voltage range of 1.5 to 6V and a DC voltmeter (permanent magnet type) are required for this

procedure the circuit that needs to be built. The transformer's HV side is where the battery and switch are attached. When the switch is closed, the end of the LV winding that has the same polarity as the HV winding, which is linked to the positive terminal of the battery, becomes positive (the DC voltmeter deflects to show this). The comparable polarity end gained negative potential when the switch was opened. The "back-to-back test" or Sumpner's test is a technique for calculating the steady-state temperature increase of the transformer. In order to execute this test, two transformers with comparable ratings are connected back-to-back. Two transformers' primary are linked together in parallel, while their secondary is linked together in series but at an angle such that the voltage across the terminal is zero. Polarities of the windings must be understood in order to join them in phase opposition. So, if necessary, the polarity test may be performed. No current should flow through it even if the secondaries are short-circuited since they are wired in phase opposition; the current detected by ammeter A1 is the core loss component. Similar to when the primaries are shorted, the circuit's entire current flows. The copper loss of the transformer is represented by the current as measured by W2.

CONCLUSION

An electrical device known as a transformer is used to convert electrical energy from one electrical circuit to another, or to several circuits. It is a passive component that functions on the ideas of mutual and electromagnetic induction. Two or more magnetically connected and electrically isolated wire coils make up a transformer. The fluctuating magnetic flux in the transformer's core caused by any one of the transformer's coils causes a fluctuating electromotive force (EMF) to be exerted across any additional coils coiled around the same core. Without a metallic (conductive) connection between the two circuits, electrical energy can be transported between different coils. Transformers are used to adjust the AC voltage levels; these transformers are classified as step-up or step-down types depending on whether they raise or decrease the voltage level. Transformers are generally subjected to open circuit and short circuit tests to identify their characteristics and losses. While the short circuit test detects the copper losses of the transformer, the open-circuit test determines the no-load current and losses of the transformer. While the short-circuit test provides the equivalent resistance and reactance of the transformer, the open circuit test measures the transformer's core losses and shunt parameters.

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AN EVALUATION OF TRANSFORMER VOLTAGE REGULATION

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ABSTRACT:

A transformer's ability to maintain a consistent secondary voltage under different load situations is gauged by its voltage regulation. It is the ratio, stated as a percentage, between the transformer's full-load output voltage and its output voltage at no load. An essential factor that affects how well a transformer regulates voltage is the output voltage's quality. Through the use of open circuit and short circuit tests, the voltage regulation of a transformer is identified. The short circuit test is used to ascertain the copper losses of the transformer, whereas the open circuit test is used to ascertain the no-load current and losses of the transformer. The formula that represents the percentage change in the secondary terminal voltage of a transformer from no load to full load in relation to the no-load voltage is used to determine the voltage regulation of a transformer. The efficiency and performance of a transformer are significantly influenced by its ability to regulate voltage. For purely resistive loads, a good power transformer should have a regulation percentage of less than 3%. Poor control is actually desired in some applications, such as discharge lighting, though.

KEYWORDS: *Linear Regulator, Linear Approximation, Output Voltage, Reactive Power, Transmission Line, Voltage Regulation, Voltage Drop.*

INTRODUCTION

Voltage regulation is a measurement of the change in the magnitude of the voltage between the transmitting and receiving ends of a component, such as a gearbox or distribution line, in electrical engineering, especially power engineering. The capacity of a system to provide almost constant voltage under various load situations is known as voltage regulation. The phrase may refer to an active intervention with equipment for the explicit aim of changing voltage, or it may refer to a passive feature that causes more or less voltage drop under certain load situations. Where V_{fl} is the voltage under full load and V_{nl} is the voltage when there is no load. Since there is no voltage drop along the line, $V_{nl} = V_{fl}$, the percent voltage regulation of a perfect transmission line, which is defined as a transmission line with zero resistance and reactance, would be equal to zero. Because of this, a lower Voltage Regulation number is often advantageous and indicates that the line is getting closer to being optimum [1].

The Voltage Regulation formula may be represented as follows: "Consider power being delivered to a load such that the voltage at the load is the load's rated voltage V_{rated} , if the load then disappears, the voltage at the point of the load will rise to V_{nl} ". The impedance of the transmission line between its transmitting and receiving ends causes voltage regulation in transmission lines. Transmission lines naturally include some amount of capacitance, inductance,

and resistance that all work together to continually adjust the voltage down the line. The voltage change's magnitude and phase angle along an actual transmission line. With streamlined circuits, such as the short line approximation (least accurate), the medium line approximation (more accurate), and the long line approximation (most accurate), the effects of line impedance may be modelled.

An approximate short line impedance in this case is $Z = R + jL$.

The resistance and reactance of the transmission line are modelled as a straightforward sequence of resistors and inductors in the short line approximation, which ignores the capacitance of the transmission line. Impedance for this combination is either $R + jL$ or $R + jX$. In contrast to the medium and long lines, the short line approximation has a single line current $I = I_S = I_R$. By dividing the shunt admittance, which is typically pure capacitance, equally between the transmitting and receiving ends of the line, the medium length line approximation accounts for it. This arrangement is often referred to as a nominal π . These lumped impedance and admittance values are distributed evenly over the length of the line using the long line approximation. Due to this, the long line approximation, which yields the best level of accuracy, calls for the solution of differential equations [2].

The voltage recorded at the receiving end terminals with the receiving end open circuit is referred to as $V_{no\ load}$ in the voltage regulation formula. The transmitting and receiving end voltages are thus the same since the whole short line model is an open circuit in this scenario. Since no current flows in an open circuit, $I = 0\ A$ and $V_{line\ drop} = IZ_{line}$, the voltage drop across the line, is $0\ V$. If the transmission line had 0 impedance, the voltage at the receiving end would equal this value. The wire would not alter the voltage in any way, which is the perfect situation for power transmission. When the load is connected and current is flowing via the transmission line, the voltage across the load at the receiving end is called $V_{full\ Load}$. The voltages at the transmitting and receiving ends of the transmission line are now not equal because $V_{line\ drop} = IZ_{line}$ is not zero. By employing a combined line and load impedance, Ohm's law may be solved to get the current I :

Phase diagrams that map V_R , V_S , and the resistive and inductive components of $V_{line\ drop}$ are used to show the impacts of this modulation on voltage magnitude and phase angle. Three power factor scenarios are discussed as follows.

- (a) An inductive load on the line causes the current to lag behind the receiving end voltage;
- b) A fully real load on the line causes the current and receiving end voltage to be in phase; and
- (c) A capacitive load on the line causes the current to lead the receiving end voltage. In every situation, the reactance of the line X in a voltage drop that is 90 degrees ahead of the current and in phase with line resistance R 's voltage drop. In the short line approximation circuit, these sequential voltage dips are added to the voltage at the receiving end while tracing backward from V_R to V_S .

The graphs demonstrate how strongly voltage regulation is impacted by the current in the line's phase angle. The needed magnitude of the transmitting end voltage is fairly considerable in comparison to the receiving end due to the lagging current. However, the variation in phase angle between the transmitting and receiving ends is kept to a minimum. The transmitting end voltage may actually be less than the receiving end voltage thanks to the leading current. It

causes the voltage to counterintuitively rise down the line. The amplitude of voltage between the transmitting and receiving ends is not much impacted by the in-phase current. The majority of inductive loads served by real gearbox lines are the motors found throughout contemporary electronics and machinery. When reactive power Q is transferred in significant amounts to inductive loads, the line current lags the voltage, and voltage regulation is characterised by a reduction in voltage magnitude. Most of the time when transmitting a significant quantity of real power P to actual loads, current and voltage are in phase. Instead of a decline in magnitude, this scenario's voltage regulation is characterised by a decrease in phase angle.

Regulation of the distribution feeder

However, because of Kirchhoff's Laws, the voltage magnitude and consequently the service voltage to customers will in fact vary along the length of a conductor such as a distribution feeder (see Electric power distribution). Electric utilities aim to provide service to customers at a specific voltage level, for example, 220 V or 240 V. Actual service voltage within a tolerance range of 5% to 10% may be regarded as acceptable, depending on the legislation and local custom. Different kinds of devices are typically used to keep voltage within tolerance under changing load conditions.

Load tap changer

Load tap changer (LTC) at the transformer of the substation, which modifies the turns ratio in response to the load current and hence modifies the voltage delivered at the sending end of the feeder.

Voltage regulators

Voltage regulators, which are simply transformers with tap changers to modify the voltage along the feeder and make up for the voltage loss caused by distance.

Capacitors

Capacitors, which decrease the current flow to loads utilising reactive power and so lower the voltage drop along the feeder. The commercialization of a new generation of solid-state-based voltage control devices is just beginning. A regulation point is where the equipment strives to maintain constant voltage and is involved in distribution control. Beyond this limit, greater voltage at low load and lower voltage at high load. Customers further away see the reverse greater voltage at heavy load and lower voltage at light load.

Problems with distributed generating

Voltage control is faced with many major difficulties by distributed generation, especially photovoltaic linked at the distribution level. Standard voltage profile for a distribution feeder devoid of DG. With increasing distance from the substation, the current flowing via feeders without DG in this voltage profile. Since line voltage fluctuates predictably with distance along the feeder, conventional voltage control equipment operates upon this presumption. In particular, line impedance causes feeder voltage to fall with distance from the substation, and the rate of voltage drop reduces the farther the distance is from the substation. However, this assumption could not be true if DG is present. For instance, a long feeder with a lot of DG towards the end will have a lot of current injected in the locations where the voltage is typically the lowest. The voltage profile will rise with increasing distance from the substation if the load is sufficiently

low and current flows in the opposite direction, that is, towards the substation.

Lack of utility monitoring equipment along distribution feeders exacerbates the problems with voltage control brought on by DG at the distribution level. Utility companies find it challenging to make the required modifications to maintain voltage levels within operational limits because of the relative lack of information on distribution voltages and loads. Despite the fact that DG presents a number of substantial obstacles to distribution level voltage regulation, when used in conjunction with intelligent power electronics, DG may actually help to improve voltage regulation efforts. PV linked to the grid through inverters with volt-VAR control is one such instance. In research co-conducted by the National Renewable Energy Laboratory (NREL) and Electric Power Research Institute (EPRI), the diurnal voltage fluctuations on the feeder were dramatically decreased when volt-VAR control was implemented to a distribution feeder with 20% PV penetration.

LITERATURE REVIEW

Hui et al. [3] discussed that in low-voltage power distribution networks where photovoltaic (PV) production and electric cars (EVs) are widely used, the simultaneous charging of several big EVs may sometimes produce under-voltage problems as well as over-voltage issues due to significant PV output. Problems with over- and under-voltage make it harder to achieve voltage management. Demand response (DR) is anticipated to be successful and affordable in promoting smart grids; as a result, using FRs via DR may be beneficial for regulating distribution system voltage. In order to implement a FR-based two-stage voltage regulation approach, this work presents a hierarchical control structure comprising a community energy management system (CEMS) and several sub-CEMS. Each sub-CEMS optimises the FR schedules at the first step, also known as the day-ahead scheduling stage, in order to reduce customers' power costs and network voltage violation times.

Mohamed Seghir et al. in [4], discussed that all connected devices' dependability and reliable operation are reliant on the calibre of the network voltage. The creation of new voltage regulation systems is necessary due to the availability of unregulated energy sources, rapid changes in loads, and changes in network connections. This calls for voltage control systems that can react swiftly to unexpected voltage fluctuations. The use of semiconductor tap changers makes it feasible in substations with control transformers. Furthermore, a single system should be constructed to handle both voltage regulation and reactive power compensation. This results from the voltage and reactive power in the network node having a tight relationship. Therefore, it was suggested to build a new voltage regulation and reactive power compensation system using artificial intelligence techniques using all of the network nodes' measurement voltages. For the first 6420 periods of the mains voltage, the active and reactive powers as well as the voltage of the reference node were chosen [5].

Hasan, et al. in [6] discussed that the severity of greenhouse gases' harmful effects on the environment has recently come to the forefront of public consciousness. This has inspired people throughout the globe to use less fossil fuel to produce electricity and more renewable sources like solar and wind energy. While power generation is centralised and flows from substations to loads in a passive power system, the conventional power system was actually designed as a passive power system. In order to build an active power system where power production may take place everywhere in the power system, distributed generators, also known as decentralised renewable energy sources, were created. The traditional power system has difficulties as a result

of decentralised power production, including voltage swings, large voltage magnitudes, reverse power flow, and poor power factor. This work introduces and designs an adaptive control system that coordinates several dispersed generators for voltage management and power factor adjustment. Through a reactive power exchange between distributed generators, the control system will reduce the overall reactive power that flows in the transmission network.

Lam et al. in [7], investigated that the issue of voltage management in power distribution networks with extensive penetration of distributed energy resources, such as renewable-based production and storage-capable loads like plug-in hybrid electric cars, is addressed in this study. We model the issue as an optimisation programme, with the goal of minimising network losses while taking into account restrictions on bus voltage magnitudes, caps on active and reactive power injections, and thermal losses and limitations on transmission lines. We set up enough circumstances for the optimisation problem's convex relaxation to be solved. We demonstrate that these necessary requirements are anticipated to be met by the majority of networks using data from current networks. We also provide a successful distributed technique to address the issue. The method follows a communication topology that is represented by a graph that is identical to the graph that represents the topology of the electrical network. Through a number of case studies involving 5, 34, and 123-bus power distribution systems, we demonstrate the algorithm's functionality as well as its resilience to communication link failures.

Abdelaziz Salah et al. in [8], investigated the Tunisian electricity transmission infrastructure is expected to incorporate a 937 MW solar pool of power by the year 2023, dispersed over the whole country. The influence of high solar energy penetration on grid voltage control and dynamic performance is examined in this research. To determine if the power system is capable of integrating the needed solar electricity, load flow analysis is used. Simulations run on computers have been utilised to assess the grid upgrade. The research also relies on temporal response simulations to grid disruptions and bifurcation diagrams that use solar production as a bifurcation parameter. The power flow simulation investigations have made use of a professional PSAT simulation toolset. The biggest PV station's voltage drop and three-phase short-circuit at a conventional bus have both been taken into consideration as network-related problems.

Valentin et al. in [9], explored that in order to provide reactive power to the electrical power system (EPS) for voltage control, hydroelectric units may be operated in synchronous condenser mode. In this working mode, the hydraulic turbine uses active power, and pressurised air is pumped into the draught tube of hydroelectric plants using Francis turbines to lower the tailwater level below the runner and reduce friction losses. Due to pressure and torque variations caused by the air-water mixing during full-scale hydraulic turbine operation, a number of dynamic phenomena have been observed. These phenomena might endanger the functionality and safety of both the hydraulic machine and the EPS. In order to assess the machine behaviour's translation from the homologous reduced scale model to the full-scale prototype, the dynamic response of a Francis turbine prototype operating in synchronous condenser mode is studied in this research. Both a full-size prototype and a scaled-down replica are used to measure the torque, machine vibrations, and pressure in the draught tube cone.

Feng et al. in [10], discussed that in a distributed generating system for DC, two essential and difficult problems are power loss and voltage management. In order to accomplish trade-offs between lowering power loss and reducing voltage degradation, a multi-objective optimisation problem is constructed in this study. It has been shown that this issue can be solved convexly

under constant current and impedance loads. Without learning about the line impedance, a distributed technique based on the random coordinate descent approach is created to overcome this issue. As a result, the system's optimum operating point may be determined automatically in real-time, and the divergence from the ideal solution brought on by changes in network parameters is minimised. This method also has a low degree of complexity and requires little processing power in actual use. In order to confirm the efficiency of the suggested algorithm under the situations of line parameter fluctuation, load variation, communication line failure, and plug-play capabilities, case studies are finally put into practise.

DISCUSSION

Transformers are one example of voltage control in action. When current flows, the transformer's imperfect parts modify the voltage. The optimum model, where $V_S = V_P \cdot N_S / N_P$, provides V_{nl} at no load, or when no current passes through the secondary coils. One may refer all resistance and reactance to the secondary side by looking at the equivalent circuit and ignoring the shunt components, which is a good approximation, and plainly see that the secondary voltage at no load will in fact be provided by the perfect model. The terminal voltage across the load is lower than expected when the transformer is operating at full load due to a voltage drop through the winding resistance. According to the description given above, this is a nonzero voltage regulation that must be taken into account while using the transformer. When the source voltage and the output voltage are extremely close to one another, a low-dropout regulator (LDO regulator) may still control the output voltage.

An LDO voltage regulator has a number of advantages over other DC-to-DC voltage regulators, including the absence of switching noise (since no switching occurs), smaller device size (since neither large inductors nor transformers are required), and more straightforward design (typically only requires a reference, an amplifier, and a pass element). The drawback is that linear DC regulators must waste power and heat across the regulation device in order to control the output voltage, unlike switching regulators. A linear regulator is a kind of voltage regulator used in electronics to maintain a constant voltage. Its resistance fluctuates depending on the input voltage and the load, producing a constant voltage output. The regulating circuit constantly dissipates the difference between the input and regulated voltages as waste heat by varying its resistance, continuously modifying a voltage divider network to maintain a constant output voltage. A switching regulator, in contrast, employs an active component that oscillates (switches on and off) to maintain an output average value. Efficiency is constrained because input voltage must always be high enough to enable the active device to lose some voltage since the regulated voltage of a linear regulator must always be lower than input voltage.

Shunt regulators and series regulators are two types of linear regulators that situate the regulating device between the source and the controlled load, respectively. More complex linear regulators include distinct stages of voltage reference, error amplifier, and power pass element whereas simpler linear regulators may merely have a Zener diode and a series resistor. Single-chip regulator integrated circuits are widely used because linear voltage regulators are a frequent component of many devices. Discrete solid-state or vacuum tube component assemblies may also be used to create linear regulators. Despite their name, linear regulators are non-linear circuits since they have non-linear parts and the output voltage is ideally constant.

To provide the controlled output voltage, a voltage divider with the transistor (or another device) as one half is utilised. When the output voltage is compared to a reference voltage, a control

signal that drives the transistor's gate or base is created. The output voltage is maintained relatively constant via negative feedback and a wise choice of compensation. Because the transistor is operating like a resistor, linear regulators often lose electrical energy by turning it into heat. In reality, the current multiplied by the voltage difference between the input and output voltage in the power loss caused by heating in the transistor. A switched-mode power supply may often accomplish the same task considerably more effectively, although a linear regulator could be recommended for light loads or situations where the target output voltage is close to the source voltage. The linear regulator could use less electricity than a switcher in certain circumstances.

The input voltage must be at least a little amount greater than the intended output value for all linear regulators. The term "dropout voltage" refers to such absolute minimum. A typical regulator, like the 7805, for instance, has an output voltage of 5 V, but it can only sustain this if the input voltage is higher than roughly 7 V, beyond which point the output voltage starts to fall below the rated output. When the supply voltage is less than around 2 V above the required output voltage, as is the case with low-voltage microprocessor power supplies, so-called low dropout regulators (LDOs) must be employed. its dropout value is $7\text{ V} - 5\text{ V} = 2\text{ V}$.

No linear regulator will function (not even a Low dropout regulator) when the output regulated voltage must be greater than the available input voltage. A boost converter or a charge pump must be utilised in this circumstance. For inputs below the nominal output voltage, the majority of linear regulators will continue to give some output voltage up to the dropout voltage below the input value until the input voltage dramatically decreases. Shunt regulators and series regulators are the two most common types of linear regulators. There is often a maximum rated output current for linear regulators. This is often limited by the output transistor's capacity to transport current or by its ability to dissipate power.

Shunt controllers

The primary transistor is located in the "bottom half" of the voltage divider, and how the shunt regulator works is by providing a channel from the supply voltage to ground via a variable resistance. In general, the shunt regulator is less effective than the series regulator since the current is redirected away from the load and goes straight to ground. However, it is more straightforward, sometimes just requiring a voltage-reference diode, and it is employed in very low-powered circuits where the lost current is little enough to not cause worry. Circuits that reference voltage often have this shape. Shunt regulators typically only allow current to sink.

Series controllers

Series regulators are more popular and more effective than shunt models. The "top half" of the voltage divider, which contains the load, is where the series regulator is located. It functions by giving a conduit from the supply voltage to the load via a variable resistance, often a transistor. The power consumed by the regulating device is equal to the voltage drop in the regulating device multiplied by the output current of the power supply. Most circuits do not regulate well once the input (unregulated) voltage approaches the required output voltage; those that do are referred to as Low Dropout regulators. A series regulator can typically only source (supply) current, in contrast to shunt regulators, which can also reduce stress on the pass transistor.

Overvoltage

Overvoltage is defined as a voltage that is greater than the voltage at which a piece of equipment is intended to function most efficiently. Without a performance enhancement, it may shorten the lifespan of the equipment and increase energy consumption. Regarding overvoltage, the Wiring Regulations BS 7671 commentary states that "A 230 V rated lamp used at 240 will achieve only 55% of its rated life" (referring to incandescent lamps) and "A 230 V linear appliance used on a 240 V supply will take 4.3% more current and will consume almost 9% more energy". Different technologies may be used to prevent overvoltage, but they must be done effectively to ensure that the energy savings from using the right voltage are not cancelled out by energy lost in the device that was used to prevent overvoltage. Additionally, reliability is crucial, and electro-mechanical equipment like servo-controlled variable autotransformers may have issues while operating at maximum incoming power.

Under voltage

Under voltage defined as a voltage that is lower than the voltage at which a piece of equipment is intended to function most efficiently. Lack of consideration for voltage drop across distance to distant power users in the design of the VO may in equipment failure before its time, failure to start, increased temperature in the case of motor windings, and loss of service.

Transients

Voltage spikes that are significant, swift, and perhaps harmful are called transients. They are brought on by lightning strikes, the switching of heavy electrical loads such as motors, transformers, and electrical drives, and the switching of power production sources to balance supply and demand. Transients, which usually only last a thousandth or a millionth of a second, may harm electronic systems, deterioration of equipment parts, and shortened equipment life. Transient protection is included in several voltage optimisation devices.

Phase voltage inconsistency

Three-phase power is provided to industrial and commercial locations. Some voltage optimisation devices are able to improve balance on the building's electrical supply, reducing losses and extending the lifespan of three phase induction motors. Imbalance between the phases in issues like heating in motors and existing wiring, leading to wasteful energy consumption.

Low power

Voltage drops, known as power dips, are typically brief (around 300 MS), however they may sometimes last longer. They might damage various pieces of equipment, such as contactors and relays, which could fail and halt operations. Uninterruptible Power Supplies, the use of capacitors on low voltage DC control circuits, and the use of capacitors on the DC bus of variable speed drives are a few examples of low voltage ride through approaches. It is important to take precautions to ensure that Voltage Optimisation methods do not lower the voltage to the point where equipment becomes more susceptible to power dips.

Reactive power and the power factor

The ratio of an electrical supply's actual power to perceived power is known as the power factor. It is calculated as the site's useable power divided by the total power drawn. A power factor of 1 is preferred since the latter contains power that cannot be used. Because providers are permitted to charge for low power factors, a low power factor would essentially imply that the electricity

supplier would deliver more energy than the consumer's bill would reflect. Unusable power is referred to as reactive power. It is used to charge capacitors or create a magnetic field surrounding an inductor's field but does not do any electrical work itself. To supply enough actual power for processes to function, reactive power must be produced and supplied across a circuit. As voltage rises and equipment reactance rises, reactive power increases noticeably. Therefore, rectifying this via voltage optimisation will in a decrease in reactive power and an increase in power factor.

Electrical loads' effects

A widespread fallacy about voltage optimisation is the idea that a decrease in voltage would always lead to a rise in current and, therefore, constant power. This may be the case for certain fixed-power loads, but most sites have a variety of loads that will benefit to varying degrees from energy savings that are aggregated throughout an entire site.

Three-phase electric motors

The most prevalent kind of three-phase load is undoubtedly an induction motor, which is utilised in a range of devices such conveyor drives, pumps, air conditioners, and refrigerators in addition to their more apparent uses. It is generally known that excessive overvoltage and three phase imbalances have a de-rating impact on AC motors. Excessive overvoltage causes the iron core to become saturated, wastes energy via eddy currents, and increases hysteresis losses. Copper losses cause an increase in heat production when current consumption is high. Motor lifespan will be shortened by the increased stress of overvoltage. Because efficiency is unaffected by avoiding overvoltage's high enough to produce saturation, significant energy savings may be achieved by minimising copper and iron losses. Although this is unlikely to be a major issue, motors designed at the nominal voltage (for example, 400 V) should be able to handle typical voltage variation within the supply limits (+/-10%) without saturation. An induction motor's speed will be minimally impacted by a reduction in voltage because slip will rise, but supply frequency and the number of poles have a bigger impact on speed. Motor efficiency falls down significantly with tiny fluctuations on either side of the intended voltage and is best at a moderate load (usually 75%). Efficiency is significantly affected by larger differences.

The benefits of lowering voltage are greatest for tiny and very lightly loaded (25%) motors. When the input voltage is decreased for motors controlled by variable speed drives, the output voltage from the VSD is also decreased proportionally, which causes the motor to draw less current and ultimately use less power. However, if the motor is operating at a high load (>80%), the voltage drop will in less torque, which will cause the motor to use more current and power.

Lighting

Energy savings on lighting equipment are quite beneficial when lighting loads are active a large amount of the time. As seen in the preceding excerpts from the Electricians Guide, incandescent lighting will experience a significant reduction in power consumption, a significant reduction in light output, and an increase in lifespan when the voltage is dropped. The lighting's energy efficiency, or luminous effectiveness, will fall since the reduction in light output will be greater than the decrease in power drawn.

However, systems using resistive or reactive ballasts may also profit from higher power quality, as can other kinds of lighting. In comparison to incandescent lighting, fluorescent and discharge

lighting is more efficient. Fluorescent lighting using traditional magnetic ballasts will have a lower power need, but the lamp's lumen output will also be lower. On contemporary electronic ballasts, fluorescent bulbs will consume about the same amount of power and provide the same amount of light. More current will be needed and there will be more cable losses in order to supply the same wattage at the lower voltage. A common worry is that some lighting will not strike at lower voltages. However, lighting controllers and ballasts are responsible for high levels of harmonic distortion, which can be filtered with some types of voltage optimizers, in addition to reducing the need for lighting controllers. This shouldn't happen, however, since the goal of voltage optimisation is to get the voltage to the service level voltage at which it was intended to work most effectively, not just to decrease it as much as possible.

Power savings

Voltage Optimization's energy savings are the aggregated increase in equipment efficiency across a site of improvements in the power quality issues mentioned above. It could be a way for reducing energy use in certain situations. According to research conducted in Taiwan, for an industrial supply, voltage reduction upstream of the transformer in a 0.241% reduction in energy consumption and a 0.297% rise in energy consumption. This was based on the assumption that there would be a variety of loads, including 5% incandescent lights, 0.5% fluorescent lighting, 12.5% three-phase air conditioners, 5% motors, 22.5% small 3-phase motors, and 52.5% big 3-phase motors.

With nearly no incandescent lighting, some high-frequency fluorescent lighting (which doesn't save), some variable speed drives (which doesn't save), and improved motor efficiency (thus less waste to save), it is probable that a contemporary installation would have less opportunities. In a northern European installation, there wouldn't be as many little single-phase motors used for air conditioning. Older lighting (such as incandescent, fluorescent, or discharge lighting with inefficient ballast or control gear) might save energy but at the cost of a lower light output. Older businesses and offices may thus save more money than newer structures or industrial locations. However, installing a voltage optimizer will in substantially greater energy savings on current lighting systems (usually LED) than on older lighting systems due to their superior efficiency.

It is very doubtful if using a voltage optimizer with contemporary lighting systems would in energy savings. Modern electronic switching controllers for LED or fluorescent lighting systems are designed to operate the lights as efficiently as possible while maintaining maximum light output and lifespan. Therefore, variations in supply voltage won't have any impact on how much energy is used by these kinds of lights overall. There are, however, low-cost variations of LED and fluorescent lamp controllers that lower the voltage by dissipating energy as heat (for instance, by connecting a number of LEDs in series with a series resistance). Although these lamps are typically low power and their energy consumption would be influenced by changing the supply voltage, the light output would also be impacted.

CONCLUSION

A transformer's ability to supply a constant output voltage while operating with various load currents is known as voltage regulation. Through the use of open circuit and short circuit tests, the voltage regulation of a transformer is identified. The short circuit test is used to ascertain the copper losses of the transformer, whereas the open circuit test is used to ascertain the no-load current and losses of the transformer. The formula that represents the percentage change in the

secondary terminal voltage of a transformer from no load to full load in relation to the no-load voltage is used to determine the voltage regulation of a transformer. The efficiency and performance of a transformer are significantly influenced by its ability to regulate voltage. For only resistive loads, a decent power transformer should have a regulation percentage of less than 3%.

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INVESTIGATING THE PARALLEL OPERATION OF TRANSFORMER

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ABSTRACT:

A way of connecting two or more transformers to a common supply on the primary side and a common load on the secondary side is known as parallel operation of transformers. A single large transformer is not cost-effective for heavy loads; hence the parallel operation of transformers is a practical solution. Transformers must operate in parallel to feed a load with higher ratings to the present transformer, which is desired as load demand rises daily. The parallel operation of transformers improves the system's dependability. Transformers must all have the identical polarities, turn ratios, and internal impedances in order to operate in parallel. For every transformer linked in parallel, the ratios of the winding reactance's to the resistances should be the same. The main benefits of running transformers in parallel are to maximize electrical power system efficiency, boost dependability, and adjust the total connected load in response to dynamic load scenarios. Transformers are typically connected in parallel by having identical turn ratios, % impedances, and kVA ratings. When transformers of the same size are coupled, the parallel functioning of the transformers reduces the substation's space capacity.

KEYWORDS: *Parallel Transformer, Power System, Common Load, Magnetic Flux.*

INTRODUCTION

A transformer is a passive part that transfers electrical energy between circuits, whether they are single circuits or numerous circuits. The electromotive force (EMF) across any additional coils wrapped around the same core changes in response to changes in the current flowing through any one of the transformer's coils, which causes changes in the magnetic flux in the transformer's core. Without a metallic (conductive) link between the two circuits, electrical energy may be transported between different coils [1]. The 1831 discovery of Faraday's law of induction defines the induced voltage effect in any coil of a fluctuating magnetic flux around the coil.

Transformers are used to adjust the AC voltage levels, these transformers are classified as step-up or step-down types depending on whether they raise or decrease the voltage level. Additionally, transformers may be employed to connect the stages of signal-processing circuits and to provide galvanic isolation between circuits [2]. For the transmission, distribution, and use of alternating current electric power, transformers have been crucial ever since the first constant-potential transformer was created in 1885. Transformer designs come in a variety of shapes and sizes for use in electronic and electric power applications. Transformers come in a variety of sizes, from RF transformers with a capacity of less than one cubic centimeter to devices used to link the electrical grid that weigh hundreds of tones. When the secondary windings of two or more transformers are coupled with a common load and the primary windings of the

transformers are coupled with a common voltage source. The transformers are then said to be linked in parallel, i.e., the transformers are operating in parallel [3].

Leaching flux

According to the ideal transformer model, the main winding joins all the turns on all the other windings, including itself. In reality, some flux travels via routes that go away from the windings. This flux is known as leakage flux, and it produces leakage inductance in series with the transformer windings that are mechanically connected. With each cycle of the power supply, leakage flux causes energy to be alternately stored in and released from the magnetic fields. Although it does not immediately in a power loss, poor voltage regulation prevents the secondary voltage from being precisely proportionate to the main voltage, especially when a large load is present. Transformers are often built with very low leakage inductance.

Long magnetic pathways, air gaps, or magnetic bypass shunts may be purposefully included into a transformer's design to reduce the amount of short-circuit current it will deliver in situations when more leakage is required. Leaky transformers may be used to safely handle loads that occasionally short-circuit, such as electric arc welders, or to provide loads that display negative resistance, such as electric arcs, mercury- and sodium-vapor lamps, and neon signs. In particular, audio-frequency transformers in circuits with a DC component running in the windings employ air gaps to prevent saturation. Saturable reactors use the core's saturation as a control mechanism for alternating current. When operating transformers in parallel, understanding leakage inductance is also helpful. It can be shown that two transformers would share the load power proportionate to their individual ratings if their % impedance and related winding leakage reactance-to-resistance (X/R) ratios were equal. The impedance tolerances of industrial transformers, however, matter a lot. Additionally, various capacity transformers have varying impedances and X/R ratios.

LITERATURE REVIEW

Markus et al. explored that there are now much more active grid components for distribution grids' voltage regulation systems. Distributed generators may give a specific voltage support using reactive power control (RPC) in addition to voltage regulators such transformers with on load tap changers (OLTCs). OLTC and RPC by photovoltaic (PV) systems are two separate control entities that typically function based on regional measurements and control traits. Therefore, it is impossible to completely rule out unexpected interactions between the control units. This article examines the concurrent operation of PV systems with various RPC techniques and OLTC transformers with a voltage-based control in a distribution system setting. The emphasis is on unanticipated interactions, including a rise in PV RPC's OLTC switching activities. The uniqueness and significance of this study is to draw attention to the possibility of these unintentional interactions and to provide a preliminary technique for analysing the specific concurrent functioning of OLTC control and PV RPC. The findings demonstrate that the efficacy of parallel operation and the influence of PV RPC on the quantity of OLTC switching operations may vary significantly depending on the PV RPC strategy used [4].

Wasri Johan et al. in [5], explored that the distribution of power to customers is growing in line with the consumption or expansion of electricity users themselves, leading to issues such an overload and an imbalanced load, among others. Therefore, in order to transport power from high voltage networks to medium voltage networks so that it may be supplied to consumers, the

distribution transformer's capacity must be increased. A Mobile Substation Unit Transformer (Portable Transformer) attached in parallel to the distribution transformer is one way to enhance the necessary power. The conditions for transformer parallel operation must be met when distribution transformers are used in conjunction with portable transformers. The voltage, frequency, vector group, and phase sequence all need to be the same as the requirements.

A. Popov et al. in [6], explored that national power system (NPS), the conditions necessary for the parallel functioning of the ETS transformers, and the medium voltage (MV) transformers used in electric traction substations (ETS). The MV transformers that power the electric railway traction system (ERTS) are optimised for parallel operation, and solutions to this problem are presented. Connection to the corresponding section of the nearby ETS transformers is necessary in the event of multiple failure or load increases over the rated power delivered by an electric traction substation (ETS). If high power transformers ERTS fulfil all the requirements for parallel operation, ETS may be coupled in parallel. The consumer's access to a stable power distribution system is ensured by this method of operation. SCADA systems may be utilised for general power supply optimisation of the railway electric traction system as well as for monitoring urgent circumstances.

ZeeshanAleem et al. in [7], explored that the use of renewable energy is gaining prominence of the severe lack of conventional energy sources. There is a big market for high-voltage inverters for solar and wind power production systems. Due to its many advantages over single capacity inverters, such as the elimination of temperature management, fault tolerance, less component stress, and modularity, modular inverters are increasingly desired. This article suggests a transformer-based, parallel-configured enhanced Z-source inverter (ZSI). The paralleling of inverters in the proposed circuit's higher voltage gain and combination advantages. By using the interleaved pulse width modulation technique, it also provides reduced harmonic distortion and lower filter needs. The detailed analysis of two parallel-connected transformer-based enhanced ZSIs is followed by the application of the same idea to N parallel-connected transformer-based improved ZSIs. A hardware prototype is put into practise in the lab and put through an experimental test for high power applications.

Rajesh Kumar Arora et al. explored that one of the fundamental needs of the contemporary day is electricity. With the development of technology, there is a rising need for and use of power. The power must be produced, transmitted, and distributed with the fewest losses feasible. One of the essential parts of the power system is the transformer. It carries out the task of adjusting the alternating current's voltage levels while preferably maintaining a constant power. We require three phase transformers in our system since the electricity is produced by a three-phase generator. The construction of three phase transformers, their kinds, connections, and phasors, as well as the prerequisites for parallel transformer operation, are all covered in this article [8].

ZhiHao et al. in [9], discussed that bulk supply substations, which are composed of two transformers coupled in a main-tie-main arrangement, provide power to railway systems. These transformers may operate in three different ways: non-parallel, parallel, and single transformer mode. The ideal operating mode for the transformers necessitates a full simulation that takes into account the dynamics of the trains and their schedules since traction loads are by their very nature dynamic. The purpose of this article is to determine the transformers' ideal operating mode for various headway intervals. In order to achieve an accurate estimation of transformer losses under the three transformer operation modes and various headway intervals, the railway

traction power system of the Mass Rapid Transit 2 (MRT2) in Malaysia is modelled and simulated in ETAP-Etrax Software with the dynamic load flow analysis. The findings demonstrate that at all headway intervals, the transformer loss in the parallel mode is smaller than that in the non-parallel mode. For headway intervals of 5 min 48 s and higher, it is also discovered that the single transformer mode has the lowest transformer losses.

M. I. Kuznetsov et al. in [10], explored that there has been used to investigate the parallel functioning of three-phase power transformers with various short-circuit voltages. The bench's circuit schematic and experimentally measured vector diagrams of the transformers' primary and secondary winding currents are shown. It has been discovered that both an arithmetic difference in currents and a significant phase shift of secondary-phase voltages occur when the difference in short-circuit voltages of parallel operational transformers is more than 10%. One transformer is thus overloaded, whilst the other is underloaded. The geometric sum of the secondary winding currents in transformers has been shown to empirically determine the load current. It has been shown that one of the transformers under study operates in conversion mode, with its currents 180 degrees out of phase, which is the primary cause of the failure of the usual working conditions of parallel transformers.

DISCUSSION

At a given flux, a transformer's EMF rises with frequency. Transformers may be physically smaller by running at higher frequencies since a particular core can handle more power without becoming saturated and fewer turns are required to attain the same impedance. Core loss and the conductor skin effect, however, both become stronger with time. 400 Hz power supply are used in military and aviation systems to save core and winding weight. In contrast, certain railway electrification systems employed frequencies that were far lower than typical utility frequencies (50-60 Hz), such as 16.7 Hz and 25 Hz, for historical reasons mostly related to the limits of early electric traction motors. Compared to those needed for higher frequencies, the transformers used to step-down the high overhead line voltages were much bigger and heavier.

Reduced magnetizing current from operating a transformer at its specified voltage but at a greater frequency than anticipated. The magnetizing current will rise at a lower frequency. It may be necessary to evaluate voltages, losses, and cooling when operating a big transformer at a frequency different than its design frequency to determine whether safe operation is feasible. To prevent overvoltage at a frequency greater than the transformer's rated frequency, protection relays may be needed. Traction transformers, which are utilized for electric multiple unit and high-speed rail service running across areas with various electrical standards, serve as one example. The converter apparatus and traction transformers must be able to handle a range of input voltages and frequencies (rated up to 25 kV and as high as 50 Hz).

A physically compact transformer can manage power levels that would call for a big iron core at mains frequency. At much higher frequencies, the size of the transformer core needed lowers substantially. Switch-mode power supplies are able to create a high frequency and vary the voltage level with a small transformer thanks to the development of switching power semiconductor devices. Core materials for transformers used in higher frequency applications, such SMPS, often have substantially lower hysteresis and eddy-current losses than those used in transformers for 50/60 Hz. Iron-powder and ferrite cores serve as prime examples. These cores' decreased frequency-dependent losses often come at the price of their reduced flux density at saturation. For instance, laminated iron has a far higher flux density than the one at which ferrite

saturation occurs. Due to transient voltages with high-frequency components, such as those brought on by switching or lightning, large power transformers are susceptible to insulation breakdown.

Winding and core losses make up the majority of transformer energy losses. Transformer efficiency typically rises as transformer capacity rises. Usually, distribution transformers have an efficiency of between 98 and 99 percent. Calculating no-load loss, full-load loss, half-load loss, and so forth is often helpful since transformer losses change with load. While winding loss rises as load increases, hysteresis and eddy current losses remain constant at all load levels and predominate when there is no load. Even an idle transformer depletes the electrical supply due to the potential severity of the no-load loss. A bigger core, high-quality silicon steel for the core, or even amorphous steel, and thicker wire are needed to design energy-efficient transformers with reduced loss, which raises the initial cost. A trade-off between initial cost and operating cost is represented by the building method chosen.

Conditions for Single-Phase Transformers to Operate Parallels

1. The polarities of the parallel-connected transformers must match. Otherwise, the windings experience enormous circulating currents.
2. The transformers linked in parallel must have the same voltage ratios. Even though the primary is connected to the same voltage source, the secondary won't display the same voltage if the voltage ratios are not the same. This causes a current to flow through the secondary's, which causes currents to flow through the main side as well. The transformers consume a considerable amount of current even when there is no load.
3. Optimal Situations
4. The internal impedances of the transformers linked in parallel must be the same.
5. For each transformer linked in parallel, the ratios of the winding reactance to the resistances should be the same. The transformers share the active and reactive powers in accordance with their ratings and operate at the same power factor.

Conditions for Three-Phase Transformers to Operate Parallels

1. The main and secondary voltage ratings of the transformers that are linked in parallel must match.
2. In parallel linked transformers, the winding reactance to resistance ratios must be the same.
3. Each parallel linked transformer must have the same phase sequence.
4. All parallel-connected transformers must have the same phase shift between the main and secondary voltages.
5. The same vector group should include all of the parallel-connected transformers.

Parallel installation of several transformers with lower ratings is more cost-effective than a single transformer with a higher rating. The benefits of this are basically as follows:

To increase the effectiveness of the electrical power system

Typically, an electrical power transformer operates most efficiently at full load. Only those

transformers that will meet the overall demand by operating closer to their full load rating at that period may be turned on if many transformers are operated in parallel. To meet the whole demand when the load grows, we may swap none by one more transformer linked in parallel. This will allow us to operate the system as efficiently as possible.

To increase the availability of the electrical power system

If many transformers are operating in parallel, we may shut down any one of them for repair. Without a complete power outage, the load will be served by other parallel transformers in the system.

To increase the dependability of the power system

If a parallel transformer trip owing to a problem with another parallel transformer, the system will share the load, which may prevent a power outage if the other parallel transformers aren't overloaded.

To increase the adaptability of the electrical power system

There is always a potential that the demand for the power system may rise or fall in the future. If it is anticipated that power demand will increase in the future, it must be possible to connect transformers in the system in parallel to meet the additional demand because it is not practical from a business standpoint to install a single transformer with a higher rating simply because it would be an unnecessary financial investment. Once again, parallel-running transformers may be withdrawn from the system to balance the capital investment and its return if future demand declines.

Conditions for Transformer Parallel Operation

For good performance while running in parallel, two or more transformers must meet the requirements listed below. These are the prerequisites for transformers to operate in parallel.

1. Transformer voltage ratio is the same.
2. The same impedance percentage.
3. Similar polarity
4. The same phase order.

Same voltage ratio

There will be a variation in secondary voltages if two transformers linked in parallel with the same main supply voltage have different voltage ratios. If the secondary of these transformers is connected to the same bus, a circulating current will exist between the secondary and, therefore, the primary of each transformer. Due to the low internal impedance of the transformer, even a little voltage variation might in an excessively high circulating current and increased I²R loss.

Same percentage of impedance

Two transformers operating in parallel should share current proportionate to their respective MVA ratings. Once again, the amount of current carried by these transformers is inversely correlated with their internal impedance. This means that the impedance of transformers operating in parallel is inversely correlated with their MVA ratings. In other words, all of the transformers operating in parallel should have the same percentage impedance or impedance per

unit values.

Equal Polarity

The polarity of every transformer that operates in parallel must be the same; otherwise, a significant amount of circulating current would pass through each transformer, but no load will be supplied from them. The secondary's immediate induced emf direction determines the transformer's polarity. The transformers are said to be in opposite polarity if the instantaneous directions of the induced secondary emf in two transformers are the opposite of one another when the same input power is given to both transformers. Two transformers are said to be in the same polarity if the instantaneous directions of the induced secondary emf are the same when the same input power is given to both transformers.

Same phase sequence

For two parallel transformers, the phase sequence, or the order in which the phases achieve their maximum positive voltage, must match exactly. Each pair of phases will be short-circuited if not throughout the cycle. Although the aforementioned requirements must be strictly followed for the operation of transformers in parallel, it is practically challenging to achieve completely identical percentage impedance of two different transformers. The values of the transformers operating in parallel may not be exactly the same, but they will be as close as possible.

CONCLUSION

Transformer functioning in parallel is a crucial component of electrical power networks. Transformers must be connected in parallel to supply the required load when the load demand rises. A single large transformer is not cost-effective for heavy loads, hence parallel operation of transformers is a cheap solution. The parallel operation of transformers improves the system's dependability. The system is more adaptable and reliable because to the parallel operation of the transformers. When the transformer is under full load, it functions at about maximum efficiency. Only those transformers can be turned on if several transformers are operating in parallel to meet the complete demand. When connecting transformers of the same size in parallel, the substation's storage capacity is reduced. Due to the flexibility to shut down any system for repair without impacting the operation of other systems, the parallel connection maximizes the electrical power system availability. Transformers need to have the same polarities, turn ratios, and internal impedances in order to operate in parallel successfully. For every transformer linked in parallel, the ratios of the winding reactance to the resistances should be the same.

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HYSTERESIS AND EDDY LOSS IN TRANSFORMER

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ABSTRACT:

Transformer losses can be of two different types: hysteresis losses and eddy current losses. As current travels forward and backward, the core is magnetized and demagnetized, which results in hysteresis loss. When an alternating magnetic field is applied to a ferromagnetic material, molecular friction results in hysteresis loss. The hysteresis loss relies on the composition of the core and rises with frequency. The area of the hysteresis loop depicts the amount of energy needed to accomplish a full cycle of magnetization and demagnetization, and the area of the loop denotes the amount of energy lost during this process. The relative mobility between the core and magnetic flux is what causes eddy current loss. Current loops develop across conductor surfaces as a result of the fluctuating magnetic flux, causing eddy current loss. This chapter explores hysteresis and eddy loss in transformer.

KEYWORDS: *Current Losses, Eddy Current, Flux Density, Hysteresis Loop, Magnetic Field.*

INTRODUCTION

Rotational losses occur during the conversion of electrical power to mechanical power in all electric motors. Depending on the underlying source and mechanism, these losses are often categorised as magnetic losses, mechanical losses, copper losses, brush losses, or stray losses. Hysteresis loss and eddy current loss are two forms of magnetic losses that are included in this category.

Loss of hysteresis

As current travels forward and backward, the core is magnetised and demagnetized, which in hysteresis loss. The magnetic flux grows as the magnetising force (current) does. However, the magnetic flux decreases less gradually and at a slower pace as the magnetising force (current) is reduced. Even when the magnetising force is zero, the flux density will still be positive. Applying the magnetising force in the opposite direction will cause the flux density to approach zero. On a hysteresis curve, or loop, the connection between the magnetising force, H, and the flux density, B, is shown. The size of the hysteresis loop depicts the amount of energy needed to accomplish a full cycle of magnetization and demagnetization, and the area of the loop denotes the amount of energy lost during this process.

Factors Affecting Loss of Hysteresis

1. Because of the small hysteresis loop, the material will magnetise extremely quickly.
2. In a similar vein, a difficult time magnetising the material will in a huge hysteresis loop.

The loop height is mostly determined by the nature of the material since various materials may saturate at different values of B. The loop size and form are primarily determined by the beginning location of the specimen.

LITERATURE REVIEW

Romero Cadaval et al.[1] discussed that in order to calculate the core power loss (CPL) in magnetic components, many key approaches are employed. The Steinmetz equation serves as the foundation for one group (whose principals are the modified, generalised, and natural equations). The division of losses into hysteresis, eddy current, and excess losses is another. The final group is based on the magnetization process, whereas the third group is based on mathematical-empirical hysteresis models. To compute the CPL using these methods, a previous test or analysis is required. The cost of testing is often high, or there are too many tests required for the component design process. Due to the absence of symmetry in certain magnetic components, 2D studies are insufficient. One of the most prevalent parts found in transformers and power converters are toroidal core components. They lack symmetry in the distribution of the magnetic field, and only 3D models can adequately account for all the effects and events. To identify the primary losses in the core of magnetic components, hysteresis and eddy current losses, a thorough investigation of 3D models using finite element analysis was conducted.

Xue Feng et al. [2] discussed that investigations are conducted into the various temperature dependences of eddy current losses and hysteresis in non-oriented Si-steel laminations. According to the observed iron loss data, the hysteresis and eddy current losses both change linearly with temperature between 40 and 100 degrees Celsius, which is the usual operating temperature range for electrical machinery. Hysteresis and eddy current losses have varying rates with temperature that change with flux density and frequency. Based on this, a better iron loss model is created that can take temperature variations in hysteresis and eddy current losses into account individually. By evaluating iron losses at just two distinct temperatures, the enhanced iron loss model enables the temperature impact on the iron loss to be completely taken into account. Tests on a ring specimen and an electrical machine are used to experimentally confirm the inquiry.

A Belahcen et al. [3], explores the relationship between eddy-current losses and hysteresis in magnetic cores. The findings of a numerical model used for the investigation show that the magneto dynamic loss phenomena are clearly linked. Hysteresis and excess losses exhibit an eddy current and, thus, excitation frequency dependency due to the impact of eddy currents on the flux distribution in the lamination depth. On the other hand, hysteresis acts as a damper and is influenced by the magnetic properties of the material, which impact eddy-current and excess losses. The model's application to a spinning electrical machine has shown how important the dependency between the losses.

Najgebauer et al. in [4], discussed that the research of magnetic hysteresis' impact on macroscopic eddy current losses is presented in the publication. Typically, this loss is estimated under a number of simplifying assumptions, the most notable of which being ignoring both the material's nonlinearity and the hysteresis. For various different materials, the loss was estimated while accounting for the hysteresis phenomena to see how these simplifications affected the findings. In order to do this, a method for solving the Maxwell's equations using magnetic properties expressed as a set of observed hysteresis loops was developed. Additionally, a novel technique for converting between H and B fields utilising the observed hysteresis loops was put

forward. The calculations for three materials' eddy current losses reveal that they are less than those for linear materials estimated using the conventional method when magnetic hysteresis is taken into consideration. Depending on frequency, magnetic flux density, and electrical sheet thickness, variances may be as much as 30% for the investigated materials.

Pardo et al. explored that the performance of higher-temperature superconductor (HTS) tapes, wires, and devices may be predicted using numerical modelling of superconductors, which is generally acknowledged as a potent tool for interpreting experimental data, comprehending physical processes, and doing so. This is especially true for ac loss calculations since these materials must have a sufficiently low ac loss value in order to be appealing for commercialisation. Researchers from all around the globe have recently presented a wide range of numerical models with the aim of being able to rapidly and precisely predict ac losses in HTSs. These models are based on various approaches and implementations. The techniques for calculating ac losses in HTS tapes, wires, and devices are reviewed in this paper's overview of the literature. Technical superconductors are made of various materials and have somewhat complicated geometries (filaments that may be twisted or transposed, or layers). There are many loss contributions as a consequence. The methods for calculating these loss contributions, such as hysteresis losses, eddy-current losses, coupling losses, and losses in ferromagnetic materials, are described in this study [5].

Qiang Liu et al. in [6], discussed that six different types of rods were examined for the effective administration. The hysteresis loss, eddy current loss, coil resistance, and inductance of the rods at various frequencies and currents were simulated and calculated using finite element software. The resistance and inductance of three different types of rods' coils were tested. According to the findings, when the frequency rose, the hysteresis loss, eddy current loss, coil resistance, and coil inductance all increased while decreasing. The hysteresis loss, eddy current loss, and coil resistance of the radially slit rod were the largest, while those of the slit rods were larger than those of the sliced rods, and the coil inductance of the slit rods was less than that of the sliced rods. As the current increased, the hysteresis and eddy current losses of the rods increased, but the coil resistance and inductance remained unchanged. In general, the experimental test and the numerical calculation values of coil resistance and inductance at various frequencies and currents coincided.

PaavoRasilo et al. in [7], explored that a fresh MATLAB/Simulink implementation of an iron-loss model for laminated magnetic cores is suggested. The model is based on using a precise hysteresis model as the constitutive law and computationally addressing a one-dimensional diffusion issue for the eddy currents in the core lamination. Also taken into account is an excess loss model. The producer of the core material has only given catalogue data, which is all that is used to identify the model. The implementation is tested experimentally using a toroidal inductor supplied by a GaN FET full-bridge inverter with switching frequencies of 5-500 kHz and a deadtime of 300 ns. Analytical and finite element models are also used to evaluate the implementation. Despite the straightforward identification, a reasonable consistency between the predicted and actual iron losses is shown, with an average difference of 3.3% throughout a broad switching frequency range. In order to accurately predict the iron losses at various switching frequencies, it is shown that taking into consideration the skin effect in the laminations is important. Also highlighted are certain discrepancies between the observed and modelled findings at high switching frequency. According to the model's conclusions, laminated magnetic cores combined with power electronics circuits may be designed and analysed.

D Bhalla et al. in [8], explored that distribution transformers must be built with minimal no-load loss in mind. Inaccurate no-load loss estimates may significantly raise the cost of ownership. The utility depends on a design based on the data sheets of the core material and estimates of no-load loss given by transformer manufacturers. Finally, the test findings serve as verification. Total no-load loss is discovered using the standard open-circuit test, and these losses are not separated. The approximate contribution of hysteresis loss and eddy current loss to the overall no-load loss is equal. Additionally, and at a significant expense, the loss testing is carried out on various frequencies or temperatures once the transformer is ready. It is nearly impossible to evaluate no-load losses with harmonic content. In this study, a 315kVA distribution transformer design is created using 3-D CAD, and the finite element technique (FEM) is used to calculate the no-load losses.

Kallaste et al. in [9], explored that using a low power selective laser melting (SLM) equipment and a laser re-melting technique, samples made from FeSi4 powder were created. Magnetic measurements were used to characterise the sample material. The work demonstrated outstanding DC magnetic characteristics at low magnetization, similar to commercial and other 3D printed soft ferromagnetic materials from the literature. Through the subtraction of simulated eddy current losses and hysteresis losses calculated using the finite element method (FEM), empirical total core losses were divided into hysteresis, eddy, and excessive losses. After the annealing, it was discovered that hysteresis losses dropped from 3.65 to 0.95 W/kg. The printed bulk toroidal sample produced significant eddy currents, which were confirmed by both empirical and FEM studies. These eddy currents then increased significantly at high material saturation following annealing. Utilising a material internal structure with partitions created by printed air gaps may help to mitigate these losses. Similarly, the significantly higher core losses brought on by material oversaturation due to a lower filling factor in the samples characterised in this study may make it difficult to produce electrical machines using 3D printing that perform as well as existing 2D laminated designs.

DISCUSSION

Utilising material with a smaller hysteresis loop area helps minimise hysteresis losses. Silica steel or high-grade steel may be utilised to construct the core of a transformer since it has a very small hysteresis loop. The adoption of a particular core material that achieves zero/non-zero flux density after the current flow is stopped may help to minimise this loss. By increasing the number of laminations provided via fewer gaps between plates, these losses may be reduced. Selecting a soft-core with reduced hysteresis can reduce hysteresis loss. Silicon steel, etc., is the greatest illustration of this. The laminated core, frequency, and flux density are the key determinants of these losses. The following are some uses for hysteresis loss.

For any ferromagnetic material, the hysteresis loop offers information on coercively, retentively, susceptibility, permeability, and energy loss during the course of a single magnetization cycle. Therefore, this loop will help us choose the right material for a certain purpose. Permanent magnets, electromagnets, and the transformer core are a few instances of hysteresis loss. Hysteresis loops are important in the design of several electrical devices. These are employed in ferromagnetism.

Eddy current losses are a consequence of Faraday's law, which says that "Any change in the environment of a coil of wire will cause a voltage to be induced in the coil, regardless of how the magnetic change is produced." Consequently, a voltage, or EMF, is created in the coils when a

motor core rotates in a magnetic field. Eddy currents, which are circulating currents that are caused by this produced EMF flow. Eddy current loss is the name for the power loss brought on by these currents. Because the resistance of individual pieces is greater than the resistance of a single, solid piece, motor armature cores employ several, thin bits of iron (referred to as "laminations") rather than a single piece. Due to the smaller area per piece, the increased resistance lowers eddy currents and, therefore, eddy current losses. To stop eddy currents from "jumping" from one lamination to another, the laminations are separated from one another by a lacquer coating. Eddy current losses show in figure 1.

According to Faraday's law of induction, eddy currents, also known as Foucault's currents, are loops of electric current that are generated inside conductors by a changing magnetic field within the conductor or by the relative motion of a conductor in a magnetic field. In conductors, eddy currents move in closed loops in directions opposite to the magnetic field. A time-varying magnetic field generated by an AC electromagnet or transformer, for instance, or by the relative motion of a magnet and a nearby conductor, might induce them inside neighbouring stationary conductors. The size of the current in a particular loop is inversely proportional to the resistivity of the material and varies with the magnetic field intensity, loop area, and rate of flux change. These circular currents in a metal object resemble eddies or whirlpools in a liquid when they are graphed.

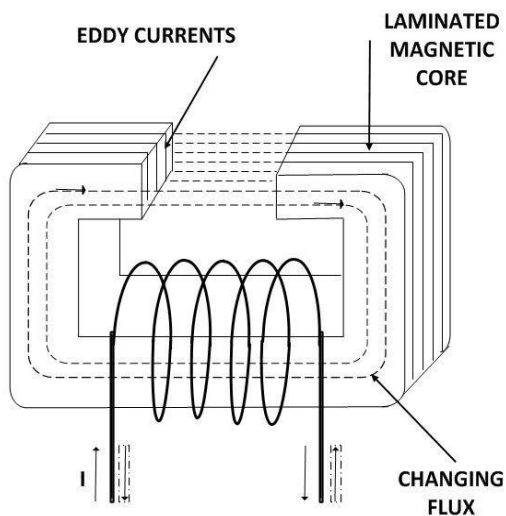


Figure 1 Eddy current losses [Circuit Globe].

Eddy currents reflect back on the source of the magnetic field because, according to Lenz's law, they produce a magnetic field that opposes the change in the magnetic field that caused them. A moving magnet, for instance, will experience a drag force that opposes its speed when it comes in contact with a nearby conductive surface because eddy currents are created in the surface by the moving magnetic field. Eddy current brakes, which are used to swiftly stop spinning power equipment when they are switched off, utilise this phenomenon. Additionally, energy is lost as heat in the conductor's substance of the current passing through its resistance. Eddy currents are a major source of energy loss in alternating current (AC) inductors, transformers, electric motors and generators, and other AC equipment; thus, reducing them requires specific design such laminated magnetic cores or ferrite cores. Eddy currents are also used to test metal components

for defects and cracks, as well as to heat items in induction heating furnaces and equipment.

DISCUSSION

In conductors with non-zero resistivity, eddy currents produce both heat and electromagnetic forces. Induction heating is a possibility with the heat. Levitation, motion creation, and powerful braking are all possible using electromagnetic forces. Eddy currents may also cause power loss in transformers and other unfavourable outcomes. In this application, they are reduced using thin plates, conductor lamination, or other conductor shape-related aspects.

The skin effect in conductors is of self-induced eddy currents. The latter may be used to evaluate materials for geometric characteristics like micro cracks without causing any damage to them. The proximity effect, which is brought on by externally driven eddy currents, has a similar effect. When the field and the object are stationary in relation to one another (as in the diagram's field centre), an object or a portion of an object experiences stable field strength and direction. In unsteady fields, currents cannot flow because of the conductor's geometry. In these circumstances, charges build up on or within the item, producing static electric potentials that block any more current. Static potentials may originally be produced by currents; however, these potentials may only exist briefly.

Resistive losses caused by eddy currents convert certain types of energy, such kinetic energy, into heat. Iron-core transformers, electric motors, and other devices that utilise varying magnetic fields are less efficient of this Joule heating. These devices reduce eddy currents by either employing thin magnetic laminations thin sheets of magnetic material or magnetic core materials with poor electrical conductivity, such as ferrites. Electrons are unable to travel in broad arcs because of the insulating space between the laminations. Similar to the Hall Effect, charges build up at the edges of the laminations, creating electric fields that prevent any more charge build up and hence suppress the eddy currents. The suppression of eddy currents increases with the decrease in the distance between adjacent laminations, or more laminations per unit area, perpendicular to the applied field.

Although there are certain useful uses, it is not necessarily a bad thing when input energy is converted to heat. Eddy current brakes, which are seen in certain railroad brakes, are one example. Eddy currents are produced in metal wheels when they are subjected to an electromagnet's magnetic field when braking. The eddy current is created by the wheels turning. Thus, according to Lenz's law, the eddy current's magnetic field will work against its intended outcome. There will be a force acting to prevent the wheel from moving at first. The impact is larger the quicker the wheels are turning, therefore as the train slows down the braking force decreases, resulting in a gentle stopping action.

The drag force produced by eddy currents is used as a brake by eddy current brakes to slow down or stop moving objects. There is no mechanical wear since there is no contact with a brake shoe or drum. Eddy current brakes may be employed in conjunction with mechanical brakes, for instance on overhead cranes, despite the fact that they are unable to provide a "holding" torque. Another use is the movement of heavy copper plates extending from the vehicle between two sets of very powerful permanent magnets on certain roller coasters. The kinetic energy of the automobile is lost due to a dragging effect caused by electrical resistance inside the plates that is comparable to friction. The same method is utilised in electromagnetic brakes on railway vehicles and in power equipment like circular saws to instantly halt the blades. In contrast to

permanent magnets, electromagnets allow the magnetic field's intensity to be modified, so altering how much of a braking effect is produced.

The generated currents show diamagnetic-like repulsion effects in a changing magnetic field. A repelling force will act on a conductive item. This has the ability to raise items against gravity, but it requires constant power input to make up for the energy lost to eddy currents. Aluminium can separation from other metals in an eddy current separator is one example of such application. Aluminium and other non-ferrous conductors are pushed away from the magnet while ferrous metals adhere to it; this may sort a waste stream into ferrous and non-ferrous scrap metal.

One may readily see a very similar effect by swiftly brushing a portable magnet, such as one made of neodymium, over a coin with a very tiny separation. Even if the coin doesn't include any magnetic components, like the US penny, one may still cause it to be pushed slightly ahead of the magnet depending on the magnet's strength, the coin's identity, and the distance between them. Another illustration involves putting a powerful magnet dramatically slowly down a copper tube. Surface eddy currents precisely cancel the internal magnetic field in a perfect conductor with negligible resistance, preventing any magnetic field from penetrating the conductor. Eddy currents produced when a magnet is placed close to a conductor continue after the magnet is stationary because no energy is wasted in resistance, and they may precisely balance the pull of gravity, enabling magnetic levitation. The Meissner effect a unique quantum mechanical phenomenon that only occurs in superconductors, causes any magnetic field lines to be ejected from the material when it becomes superconducting. The magnetic field in a superconductor is always zero. Since eddy currents are a significant source of energy loss in AC equipment like transformers, generators, and motors, the heat created by their influence is not put to any good use. It is referred to as an Eddy Current Loss. This eddy current does have certain applications, such as induction heating.

1. An iron shaft is used as the core of an induction coil in the case of induction heating. When the high-frequency current is sent through the coil, the eddy current generates a significant quantity of heat at the outermost portion of the shaft.
2. The heat decreases towards the shaft's middle. This is so that the eddy currents may travel along a low resistance route at the shaft's outside perimeter. In autos, this procedure is used to surface harden hefty shafts.
3. Electrical devices like induction-type energy metres utilise the action of eddy current to provide braking torque.
4. To provide damping torque in instruments with moving coils that use permanent magnets.

CONCLUSION

The link between the magnetic flux density and the magnetising field strength may be seen in the hysteresis loop. The loop is created by monitoring the ferromagnetic material's magnetic flux while adjusting the external magnetising field. Steinmetz developed the Steinmetz hysteresis law, a method for calculating hysteresis loss. It is discovered that the size of a magnetic material's hysteresis loop is precisely proportional to the maximum flux density to the 1.6th power. Where hysteresis coefficient is a proportionality constant. Magnetization saturation in the transformer core is the cause of hysteresis loss in transformers. When put in a high magnetic

field, such as the magnetic field produced by an AC current, magnetic materials in the core will ultimately become magnetically saturated.

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AN ANALYSIS OF INRUSH CURRENT

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ABSTRACT:

All things considered, inrush current is a transient current with a large amplitude that can happen when a transformer is turned on with no load or a light load. By extending the voltage rise time on the load capacitance and slowing the capacitors' charging, inrush current can be decreased. The frequency of inrush currents, cost, equipment power level, projected dependability, and performance all factor into the protection technique selection. The source power system experiences substantial shunt capacitance during interconnection through a subsea cable, which in a low natural or resonant frequency. The system transformer is one place where harmonic currents come from. The transformer may draw a transient inrush current with all harmonic components when it is first powered up. A sustained overvoltage may be created if one of the harmonic components of the inrush current is near to the resonant frequency of the power system, depending on the damping levels. On some recently connected offshore systems, this has lately resulted in operational issues.

KEYWORDS: *Inrush Current, Negative Temperature, Transient Current, Damping Levels, Harmonic Components.*

INTRODUCTION

A locked rotor current or input current is what an inrush current is, and it will grow as a device ages. Inrush current, to put it simply, is the huge current that occurs after turning on any electrical device and surpasses the steady-state current value. Many things contribute to its occurrence. The decoupling capacitors are charged by a significant current flow when the power is switched on. This figure gives us a good picture of the inrush stream. It displays the path taken by the current waveform when the power is switched on. The peak current value, which exceeds the steady-state current value, occurs when the power is switched on. The steady-state value stabilises, causing the current value to fall. Inrush current, which occurs before a value reaches steady-state.

Measurement of Inrush Current

This current may be readily measured by metres using an inrush button. The majority of electronic gadgets are made up of inductive or capacitive parts, which in abnormally high current when the item is turned on. Whether it be an FPGA or a drilling machine, the devices need inrush current. The right estimation or measurement of this current is necessary for the circuitry's appropriate design[1]–[3].

The power analyser offers dynamic signal range, real-time signal processing, and acquisition. This specific power analyser will be precise and prompt. Internal current measurements may be made between 15mA and 60A. Input from extra sensors is provided by the power analyser to allow for current measurements beyond the typical range. The input is paired with an external current sensing resistor to show lower current ranges. The input is paired with current probes to show higher currents. The numerical number provides a straightforward if we need the maximum current. The peak value that is shown is called IP peak. For the present range to match the anticipated current using the Range Up button, manual adjustments should be required. The auto range mode is activated by holding down the Range Down bottom. For accurate switch-on operation analysis, there is an inrush view available.

The circuit schematic for inrush current is shown below. Inrush current limiters are the circuits that are used to restrict this sort of current in order to safeguard the components and fuses. Most often, fixed resistors and thermistors with negative temperature coefficients are utilised to restrict this current. These larger-than-normal type negative temperature coefficient thermistors are created specifically for power applications. These thermistors with negative temperature coefficients initially have increased resistance to block big currents from flowing. These thermistors typically have a disc form with a radial lead on each side, and their power handling is proportionate to their size. Another way to reduce inrush current is by using fixed resistors. Fixed resistors have received criticism for being less efficient, therefore lower power circuitry prefers them. When compared to thermistors, fixed resistors have the benefit of being less expensive.

Starting current vs inrush current

The initial cycle of creating a magnetic field on iron will consist only of current transients. After the magnetic field is established, a current will run steadily until the motor achieves its maximum speed. This current is entirely resistive, and the windings' DC resistance manages it. Star-delta beginning relay utilisation may be lowered since this starting current is often greater.

Approaches to Reduce Inrush Current Surges

PTC thermistors provide dependable protection against short circuits and inrush current surges under a variety of demanding temperature and power situations. These thermistors provide precise temperature monitoring and control. Electrical currents may experience spikes in flow when power sources are switched on. The power supply components as well as other components that are receiving electrical current may be harmed by these unsuitable currents, thus precautions must be taken to safeguard the components.

LITERATURE REVIEW

Shadaei et al., explored that the transformer differential protection is known to be most seriously threatened by magnetising inrush currents. In order to prevent the differential protection from malfunctioning, it is necessary to identify the inrush current from the internal fault current. The discrimination algorithm should work well under CT saturation settings since a current transformer (CT) saturation is possible at high levels of inrush and fault current. Here, a technique for carrying out the discriminating process is devised based on the rate of phase angle change (RoCoPA). The RoCoPA of the three-phase differential currents is used in the suggested discrimination index, and the standard deviations of the RoCoPA of the three-phase differential currents are computed. The RoCoPA has the fewest fluctuations since the classification technique is based on the observation that, in fault circumstances, the signal stays essentially

sinusoidal. On the other hand, the RoCoPA exhibits noticeable changes of the inrush current's non-sinusoidal wave form.

Laaksonen et al., discussed that the black start of medium voltage distribution networks (MV-DNs) by a battery energy storage system (BESS) is addressed in this research. The BESS is made up of a restricted overcurrent-capable, two-level voltage source inverter that interfaces with MV-DN. However, MV-DN typically has a number of step-up and step-down transformers that pull sympathetic inrush current during the energising stage. Because the inverter must simultaneously manage the network voltage and its output current, performing a black start using BESS during MV-DN island operation is very challenging. In order to regulate the inrush current during an MV-DN black start, two control strategies for a BESS are presented in this work. Droop, voltage, and current loops in the stationary reference frame make up the suggested control systems. The voltage reference is created via the droop loop. For controlling output voltage, creating current references, and monitoring current, respectively, an inner current loop and an intermediate voltage are created. To reduce inrush current, new reference modifiers are included into droop and voltage loops. The suggested control systems are experimentally tested for supplying Ing MV-DN with energy in Finland using a 1 MVA BESS, and their effectiveness is evaluated in terms of the amount of inrush current and the quality of the voltage.

Grzegorz et al., explored that a high value current may sometimes flow through a superconducting transformer's windings once it is connected to the power network. The windings might lose their superconductive status if this current repeatedly exceeds the superconductor's critical value. Due to the conduction of a very high density of current, the windings' loss of superconductive condition may cause thermal disruption of their continuity. Superconducting transformers are difficult to compute using the same mathematical principles that are used to determine the inrush current of ordinary transformers. This is caused by the characteristics of the superconducting materials employed in the windings, namely by the stepped increases in resistance of the windings when they enter and leave the superconducting state. The article explains the mathematical relationships that may be used to compute how these transformers' inrush current pulse waveforms are formed. The calculations are rapid and simple since they employ common electrical circuit sizes. Calculations of the inrush current for 8.5 kVA and 13.5 kVA superconducting transformers using the formulae. Inrush current measurement data were used to confirm the findings, resulting in satisfactory compliance.

Xianggen Zhang et al. explored that when the transformer is energised, a large inrush current is produced. On the one hand, it will have a detrimental effect on the transformer's safety and may possibly make the relay protection fail. On the other hand, due of the protection constraint requirements, it may slow down protection operation speed when there is a little malfunction. Grid security will be impacted by both factors. This research offers a pre-fluxing and controlled switching technology-based inrush current reduction technique based on the inrush current's generating process. The analytical formulas of the magnetic flux at each stage of implementing the strategy are obtained by building an equivalent magnetic circuit model of the large-capacity three-phase transformer with a universal core structure, and then the parameters design method of this strategy is proposed. Through a precise simulation, the validity of the theoretical analysis of magnetic flux is confirmed. By ignoring the issue of residual flux measurement, this technique may lower the inrush current to 0.5 times the rated current or less in any circumstance where the residual flux is unknown and the effects of "core flux equalisation" are not immediately apparent. The effects of this method on the protection is finally examined in the example of the

transformer differential protection from the perspectives of theory and simulation, and it demonstrates how effectively it may enhance the performance of various safeguards[4]–[6].

Mansor et al. explored that today, maintaining a steady and effective transformer operation is essential, particularly with the integration of future contemporary and delicate electrical devices. Even yet, there is still a risk of transformer malfunction, particularly given the presence of inrush currents that resemble fault currents in the event of a fault. So, utilising a back propagation (BP) network and techniques for genetic and simulated annealing optimisation, this research provides an improved approach for inrush current detection. The suggested approach has improved solution accuracy and reduced computation complexity, and it can discover the global optimum solution while avoiding local optima. It was discovered via extensive simulations that the harmonic contents of the inrush and fault currents varied, which may be used to identify those currents using the suggested identification approach. By using 200 current samples, the suggested genetic simulated annealing-BP (GSA-BP) method increases the inrush current's detection accuracy from 80% to 97.5%. Studies that compare the GSA-BP network to the current identification techniques demonstrate that it is more accurate and efficient while still being realistic for real-world application to enhance the transformer protection system.

Zhichang Yin et al., explored that converter transformers are essential pieces of AC/DC conversion equipment and, given the current trend towards AC/DC hybrid power networks, their stability and safety are of utmost importance. There have been several major mishaps when high-impedance transformers' zero-mode inrush current, also known as ZMIC, malfunctioned the transformer's zero-sequence backup protection and even the upper-level line. Since the converter transformer is a particular kind of high-impedance transformer, the ZMIC produced during no-load operation may cause the existing zero-sequence protection to fail. However, it differs from typical high-impedance transformers in terms of its winding connection structure and no-load operating strategy. Multiple transformers may interact sympathetically with one another. Therefore, a separate analysis of the ZMIC is required. The amplitude relationship and attenuation characteristics of four bipolar converter transformer ZMIC are evident via the existing ZMIC equivalent circuit of converter transformer, which forms the basis of the subsequent protective system. Through PSCAD (Power Systems Computer-Aided Design) simulation, it is discovered that ZMIC may lead to a fault in the zero-sequence overcurrent protection. The link between the zero-mode inrush fundamental wave and harmonic amplitude is used to develop an inrush current identification technique. The usefulness of the suggested approach and its superiority compared to the present inrush current detection methods are confirmed taking into account the system resistance, closure angle, CT saturation, and fault situations.

A. YahiouMellah et al. explored that the reduction of inrush current in a three-phase transformer is the primary objective of this study. When a transformer is powered up with no load or a low load, an inrush current emerges. It may rise to very high levels and lead to electrical system malfunctions. The control technique is accomplished by respecting the phase shifting between the three phases as well as the value of the residual flux after the transformer is de-energized. In order to quantify the inrush current, a data collecting system employing a card was constructed and is provided in this work along with an experimental setup. In the experimental setting, a method to regulate the circuit breaker for energising a 2 kVA three-phase transformer without the emergence of inrush current was also investigated. The unique contribution of this study is the use of this approach in the measurements together with a careful examination of the residual

flux. The inrush current was completely eliminated by the suggested method.

AlvesGrimaldi et al. discussed that power transformer lifespan decrease and safe functioning of electrical power systems are both closely correlated with the occurrence of inrush currents in power transformers. This article processes three-phase current data and identifies the inrush current using the linear prediction approach. The linear prediction error is intended to identify the phenomena, and the linear predictors of orders 2 and 4 are applied. A database including 285 current signals was created by simulating many different amounts of inrush current in an alternative transient's programme to test the performance of the approach. The modelled electric system is based on a genuine distribution network. A noise sensitivity study is carried out after adding Gaussian noise to the signals in order to assess the method's dependability. The demonstrate the efficacy of linear prediction as a method for detecting inrush current, which worked well in conditions with SNR of 55, 60, and 65 dB.

DISCUSSION

To control these damages, often one or two strategies are used. Various factors, including power rating, frequency, the operating temperature range, and system cost requirements, determine which kind of current limiting should be utilised.

1. One is passive inrush current limitation, which employs a protective device for passive inrush current limiting.
2. Active inrush current limitation is another; it employs an active bypass circuit.

Inrush current in transformers

Transformer inrush current refers to the greatest instantaneous current taken by the transformer's primary while the secondary is open circuit. Although this current doesn't create lasting faults, it may lead to undesired switching in the transformer's circuit. When the electricity is turned on, a transformer will draw inrush current that is greater than saturation current. The inrush current has an impact on the core's magnetic property. When the transformer is turned on, a certain location on the AC wave determines its magnitude. When the AC wave passes through zero, the current drawn will be very high and will surpass the saturation current.

Inrush current in capacitors

The filtering of a power control circuit involves the employment of several capacitors. These capacitors come in a variety of varieties, including tantalum and aluminium polymer. When a circuit is connected to battery capacitors, ripple current won't have any consequences during normal operation, but at first, the connection will act like a short circuit and utilise much more inrush current than ripple current.

Inrush Current for Toroid Transformers

For certain low-frequency applications, toroidal transformers are constructed with ring-shaped cores and are around 40% lighter than E-I transformers. Due to its windings and core, toroidal technology is far more efficient than stacked core transformers. When it is not correctly controlled, toroidal transformer inrush current might sometimes in some harm. The inrush current may destroy fuses, trip circuit breakers, and potentially cause the whole transformer to fail.

How to Lower DC Motor Inrush Current

When a DC motor is turned on, the motor immediately draws its input current, and the inrush is at its highest. It's critical to keep this current under control to protect the DC motor from harm. In a DC motor, the rotor drives mechanical revolutions and the stator transforms electrical energy into mechanical energy[7]–[10].

Capacitors

When the source voltage is greater than the capacitor potential, a discharged or partly charged capacitor appears as a short circuit to the source. It will take around 5 RC time cycles to completely charge a totally drained capacitor; during this time, the instantaneous current may significantly surpass the load current. As the capacitor achieves full charge, the instantaneous current decreases to load current. The capacitor will be charged to its peak AC voltage in the event of an open circuit. AC line electricity cannot be used to charge a capacitor; it refers to the output of unidirectional alternating voltage from a rectifier. The capacitor will still seem to be a short circuit while being charged from a linear DC voltage, such as that provided by a battery; the source's internal resistance and the capacitor's ESR will be its only real limitations. The charging current in this scenario will be constant and exponentially decrease to the load current. The capacitor will be charged to the DC voltage in an open circuit. Performance of the device depends on protection against the first current inrush flow during the charging phase of the filter capacitor. The inrush current may be decreased by temporarily increasing the resistance of the power up by temporarily adding a high resistance between the input power and rectifier. This may be accomplished with the aid of an inrush current limiter, which can provide the necessary initial resistance.

A transient current that is up to 10 to 15 times the rated transformer current may flow for many cycles when a transformer is initially turned on. Toroidal transformers may have an inrush to operating current ratio of up to 60 times while using less copper and managing the same amount of power. Worst-case inrush occurs when the primary winding is connected just before the primary voltage crosses zero (which, for a pure inductance, would be the AC cycle's current maximum) and if the polarity of the voltage half-cycle coincides with the polarity of the magnetic remanence in the iron core (which was left high from a previous half cycle). The core will get saturated during such a start-up unless the windings and core are designed to typically never surpass 50% of saturation (and in an effective transformer they never do, since such a structure would be excessively heavy and inefficient).

The leftover magnetism in normal operation is about as high as the saturation magnetism at the "knee" of the hysteresis loop, which is another way to put it. However, as soon as the core reaches saturation, the inductance of the windings seems to be significantly decreased, and the current is only limited by the resistance of the primary-side windings and the impedance of the power line. Only part half-cycles experience saturation, which may in harmonic-rich waveforms that can damage other machinery. These inrush currents may linger for many seconds in big transformers with low winding resistance and high inductance until the transient dies away (decay time proportional to XL/R) and the usual AC equilibrium is achieved. Contrary to zero-voltage switching, which is preferred to reduce sharp-edged current transients with resistive loads like high-power heaters, inductive loads must be synchronously connected near a supply voltage peak in order to prevent magnetic inrush. This is true only for transformers with an air gap in the core. However, toroid transformers can only be started without an inrush-current peak if a permanentizing process is performed before to switching on.

Transformer re-energization in an inrush current of energization. Depending on when the energy is applied, the residual flux in this scenario may be zero or more. When transformer voltage is recovered after being lowered by a system disruption, a recovery inrush current flow. When numerous transformers are connected to the same line and one of them is turned on, a sympathetic inrush current flow.

Motors

When an electric motor, whether AC or DC, is initially turned on, the rotor is not moving, therefore a current equal to the stalling current will flow. As the motor gains speed and produces a back EMF to counter the supply, however, the current will start to decrease. Brushless motors fundamentally present the winding resistance, while AC induction motors operate as transformers with a shorted secondary until the rotor starts to rotate. If the mechanical stress on the motor is reduced before it gains speed, the duration of the beginning transient is reduced. In order to lower the current consumed at start up for high-power motors, the winding arrangement may be modified.

Lamps with filaments and heaters

Metals have a positive temperature coefficient of resistance, meaning that when they are cold, they have less resistance. Any electrical load, such as an electric kiln or a bank of tungsten-filament incandescent bulbs, that has a considerable portion of metallic resistive heating elements will require a large current until the metallic element achieves operational temperature. A "T" rating, for instance, indicates that a wall switch can safely handle circuits with the high inrush currents of incandescent lights. This rating is common on switches used to control incandescent lighting. The inrush may last for a few milliseconds for smaller bulbs up to several seconds for lamps of 500 watts or more, and it can be up to 14 times the steady-state current. (Non-graphitized) carbon-filament lamps, which are no longer commonly used, have a negative temperature coefficient and increase their current consumption as they warm up; they do not exhibit an "inrush" current.

To restrict the current charging input capacitors, a resistor connected in series with the line might be utilised. However, due to the resistor's voltage drop and power dissipation, this method is not particularly effective, especially in high-power devices. Inrush current limiters may help lessen inrush current. To guard against inrush current damage, switching power supplies, motor drives, and audio equipment often use negative-temperature-coefficient (NTC) thermistors. A thermally sensitive resistor known as a thermistor has a resistance that alters considerably and reliably in response to temperature variations. An NTC thermistor's resistance reduces as temperature rises.

The current starts to flow through the inrush current limiter and warms it up as it starts to self-heat. As a relatively tiny current flow charges the input capacitors, their resistance starts to decrease. The self-heated inrush current limiter provides minimal resistance in the circuit when the power supply's capacitors are fully charged and has a low voltage drop relative to the circuit's overall voltage drop. A drawback is that the NTC resistor is hot and has low resistance right away when the gadget is turned off. It can't reduce the inrush current until it cools for a longer period of time to increase resistance. The NTC thermistor has the additional drawback of not being short-circuit-proof. A "transformer switching relay" is another method for preventing the transformer inrush current. There is no need for cooling off time for this. It is short-circuit-proof and can handle half-wave voltage dips in power lines. Utilising a pre-charge circuit provides an

additional option, especially for high-voltage circuits. When the voltage on the load reaches 90% of full charge, the circuit would allow a current-limited pre-charge mode during capacitor charging and transition to an unrestricted state for regular operation.

Limiting inrush current with fixed resistors

A fixed power resistor may also be used to restrict the inrush current. The resistor is bypassed once the electrolytic capacitors at the power supply's input have been charged. Relays, triacs, and IGBTs are just a few of the many parts that may be utilised to bypass the resistance. Compared to using NTC thermistors, this approach of inrush current restriction is substantially more complicated and costly. Because of this, it is mainly used in power supplies with higher wattage designs (250W and more). The benefits include the fact that fixed resistors use substantially less power and operate independently of the surrounding temperature.

Using fixed resistors as a solution is comparable to how trailing edge phase dimming works. After the capacitors have been charged, the limiting circuit is bridged using a relay. The limiting factor itself is what distinguishes this solution. The voltage of the partially charged capacitors is compared to the instantaneous value of the AC voltage by an electronic system. A MOSFET shuts if the difference is below a certain threshold, such as 30 V. The MOSFET reopens if the differential exceeds 30 V. The max charging current is consequently limited by the MOSFET's on-resistance. For instance, if the on-resistance is 4 ohms, the maximum current is 7.5 A (30 V / 4 ohms). This ensures a soft start for all input voltages. The inrush current limiting circuit is bridged if the input capacitor is completely charged to prevent power losses. A clever and effective method of gently regulating the amount of energy permitted to charge the input capacitor is pulse charging. A tiny switched-mode power source that serves as a charging circuit is incorporated to accomplish this. The input capacitor may be charged extremely effectively and without any losses. Using this approach has the following benefits.

1. The inrush current hardly exceeds the operational current during normal operation.
2. Since there are no variables present, the peak current may be specified more precisely.
3. The design also includes a delay in the charging This implies that since nearby equipment is likewise powered on when power is begun or restored, the supply does not cause an unneeded inrush.
4. Operating current rather than peak current may be used to size fuses or circuit breakers.
5. Neither input voltage nor temperature have any effect on the inrush current restriction.

CONCLUSION

When a transformer is turned on with no load or a light load, inrush current, a transient current with a high amplitude, may happen. The highest current a circuit can draw when it is turned ON is known as inrush current. It is visible for the few input waveform cycles. The inrush current has a value that is significantly higher than the circuit's steady-state current, and this high current can harm the device or trip the circuit breaker. Transformers, industrial motors, and other devices with magnetic cores frequently exhibit inrush current. The 96 type nonlinear inductor and input hysteresis loop are used to compute the magnetising inrush current of the no-load transformer. The inrush current is described in terms of its peak, which is roughly 40% bigger than its average, or its average over a half-cycle. The frequency of inrush currents, cost, equipment

power level, projected dependability, and performance all factor into the protection technique selection. An inrush current limiter that is frequently employed is the NTC thermistor. By extending the voltage rise time on the load capacitance and slowing the capacitors' charging, inrush current can be decreased.

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CONSTRUCTION OF TRANSFORMER CORE AND WINDING

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ABSTRACT:

The magnetic flux, capability to handle voltage and current, and general efficiency of the transformer all depend on how well the transformer's core and winding are built. A transformer's core is where electricity passes through a primary winding to produce a magnetic flux. The secondary winding picks up the voltage when the magnetic field passes across it. According to the number of turns in each winding, the power is increased or decreased. In order to accommodate larger currents, the low-voltage winding has fewer turns of thicker, insulated wire surrounding the core. But unlike the high-voltage winding, the insulation on this winding does not have to sustain the same extreme strain. Many turns of relatively thin, insulated wire are coiled around the core to create the high-voltage winding. Because it is intended to accommodate lesser currents, this winding is narrower than the low-voltage winding. The increased voltage that is placed across this winding must not damage the insulation on it.

KEYWORDS: Cross Section, Eddy Current, Magnetic Flux, Transformer Core, Voltage.

INTRODUCTION

The "transformer core" a more generally used term for the magnetic circuit that forms part of a transformer's construction is intended to provide a channel for the magnetic field to circulate around. The voltage induction between the two input and output windings requires this magnetic route. However, since the primary and secondary windings are so far apart from one another, this style of transformer design, in which the two windings are coiled on different limbs, is not particularly effective [1]. Low magnetic coupling between the two windings and significant magnetic flux leakage from the transformer itself are the effects of this. But in addition to this "O" shape structure, there are many "transformer construction" kinds and designs that may be employed to get around these shortcomings and create a smaller, more compact transformer.

By putting the two windings into close proximity to one another and enhancing the magnetic coupling, it is possible to increase the efficiency of a straightforward transformer design. The magnetic coupling between the two windings may be improved by enlarging and concentrating the magnetic circuit surrounding the coils, but doing so also in an increase in the magnetic losses of the transformer core. The core is designed to avoid flowing electric currents within the iron core itself in addition to providing a low resistance route for the magnetic field. Eddy currents, which circulate and produce energy losses and core heating, reduce the transformer's effectiveness. The iron circuit, which is continually exposed to the alternating magnetic fields created by the external sinusoidal supply voltage, is the principal cause of these losses. Voltages produced in the iron circuit are what cause these losses. Making the transformer core out of thin steel laminations is one technique to cut down on these undesired power losses[2].

The centre iron core of the majority of transformer designs is formed of a highly permeable material, often from thin silicon steel laminations. These thin laminations are put together in an assembly to provide the necessary magnetic route with the least amount of magnetic loss. Because the steel sheet itself has a high resistivity, any eddy current loss may be minimised by using thin laminations. These steel transformer laminations range in thickness from 0.25 mm to 0.5 mm, and because steel is a conductor, they are separated from one another electrically by a very thin layer of insulating varnish or by the application of an oxide layer to the surface.

LITERATURE REVIEW

Pavel Yu Grachevet al. [3], explored both small and large-scale wind turbine generators with high-efficiency winding architecture are discussed. For all kinds of stand-alone systems, electromechanical converters built on these small winding generators have great potential. This article studies a squirrel-cage induction generator with a novel stator. Reduced cross sections are seen at connecting points between rectangular slots and winding turn overhangs in stator winding architecture. It is anticipated that many electric motor and generator types may benefit from this small structure. The authors provide a novel design methodology for induction generators for wind turbines that takes into account the construction characteristics of compact windings. It describes the idiosyncrasies of calculating resistance and end-winding leakage, and estimates the impact of compact winding on generator size and efficiency. The design of a generator should take the electromagnetic field research findings from this page into account. Calculations have shown that the planned induction generator's size was lowered and its efficiency increased. Power electronic components may be mounted on the stator core within the machine enclosure thanks to the generator's reduced end-windings. The essay provides recommendations for future study, focusing on the advancement of induction generator design technology.

Kaikka et al.[4], discussed that due to its straightforward design, magnet-free rotor, and inexpensive price, line-start synchronous reluctance machines (LSSRMs) have attracted increased attention. It necessitates precise assessment of these machines' electromagnetic properties utilising intricate and time-consuming finite element analyses (FEAs) in order to enhance control performance, design optimisation, and fault diagnosis analysis. In this study, winding function analysis and conformal mapping were used in place of FEA to compute the inductances and electromagnetic torque of the LSSRM. The hybrid technique, which has no restrictions on the saliencies and topologies of the rotors, may be used to forecast motor behaviour while accounting for all spatial harmonics of the air-gap permeance. Additionally taken into account were the effects of stator slots, rotor bars, and core saturation. In terms of accuracy and computing time, the findings from simulations were contrasted with those from FEA.

Wenjie Chenget al. [5], explored the slot less stator core is often used in ultrahigh-speed axial-flux permanent magnet (AFPM) motors to reduce cogging torque. However, the stator winding design and the permanent magnet (PM) topology structure continue to be the two causes of the torque ripple. The paper provides an analytical solution to the electromagnetic torque in order to ascertain the impact of the two aforementioned elements on the torque ripple of an ultrahigh-speed AFPM motor. A novel topological structure of PM is also created in order to improve the spatial utilisation ratio of PM and to produce a sinusoidal back electromotive force. Results indicate that when $N-q$ (number of coil-pairs per phase) is equal to 6, the ratio of net torque to total torque may reach 99.2%, and the back EMF of the proposed rotor is 7.69% higher

than that of the previous rotor. Data from experiments and the 3-D finite element technique (FEM) are used to validate the analytical model.

Novotnyet al. [6], discussed that transformers used in high-power, high-frequency DC/DC converters are designed with certain factors in mind. The choice of the core material, minimising copper losses caused by proximity and skin effects, and achieving regulated leakage inductances are the main areas of concern. The coreless properties of several high-frequency materials are described, and it is shown how different conventional winding configurations affect copper losses and the leakage field. The employment of coaxial winding methods, which are often employed in high-frequency transformers, is then looked at as a potential means of limiting the leakage flux within the interwinding space, preventing it from entering the core, reducing core losses, and avoiding localised heating. Reduced forces within the transformer, fewer copper losses, and sturdy construction are other advantages of this method. Two experimental single-phase 50 kW, 50 kHz units' performances are presented. Coaxially wound transformers are also given in a three-phase variant.

Adam Lindblomet al. [7], explored that coaxial transmission lines may be used to construct high-voltage transformers. The coaxial screen serves as the main winding and the inner conductor serves as the secondary winding of the transformer described in this article. An advantage of transmission line transformers is that the insulation issue is resolved and the construction can be kept simple. Despite the transformer using an air core, the coupling between the primary and secondary coils is high. Another benefit of the air core is its ability to store a lot of magnetic energy. This transformer is perfect for quickly charging high-voltage capacitors due to its strong coupling factor and substantial energy storage capacity. Alternating Archimedean spirals are the transformer's winding type. Here, using a finite-element solver, we offer a magnetic field analysis of the transformer's main, secondary, and mutual inductance. We contrast the estimated and observed magnetic flux densities. If the architecture has an equal number of spiral layers for each pair of windings, the step-up winding ratio of the transformer only slightly affects the coupling factor. However, if the step-up transformer construction has an odd number of spiral layers, the finite-element solver predicts a decrease in coupling factor. The transformer's copper conductors resemble isotropic copper pipes.

Javier Martinezet al.[8], explored that due to the importance of induction machines (IMs) in many industrial processes, condition-based maintenance (CBM) systems should be used to identify problems with them early on and prevent expensive production line disruptions. The creation of rapid models that can faithfully imitate the machine under malfunctioning situations is essential for the development of CBM systems for IMs. Due to the intricate relationships between spatial and temporal harmonics, IM models in particular must be able to replicate the distinctive harmonics that the IM defects imprint in the spatial waves of the air gap magnetomotive force (MMF). The eccentricity of the rotor core is a typical kind of problem that causes an imbalanced magnetic pull and may cause harmful rotor-stator friction. Although models created using the finite element method (FEM) can achieve the necessary accuracy, their use in online CBM systems is constrained by their high computational costs.

Arumugam et al.[9], discussed that when using sweep frequency response analysis (SFRA) measurements, it is highly desirable to maximise the capability of detecting even the smallest movement in the winding-core arrangement of a power transformer. The detection sensitivity that may be attained is largely influenced by the terminal connection used and system function

taken into account. Since they are conducted using a low-voltage, off-line method, SFRA tests are capable of testing any potential system configuration and terminal connection. Despite everything, when interpreting the measured SFRA data meaningfully, an expert opinion is unavoidable. More skill is particularly needed when determining the minor winding deviations, which typically show up in the mid-frequency range.

Tootoonchian et al. [10], explored that many linear actuators are controlled in closed loop by linear position sensors. Since 2-DOF linear planar motors are becoming more widely used in industry, the demand for 2-DOF sensors is also anticipated to rise. Because using a 2-DOF sensor rather than two separate sensors reduces control system complexity, reduces volume and mass, and improves position determination accuracy. Therefore, a novel design for a 2-DOF linear resolver is presented in this article. The stator and the mover have orthogonal slots in the proposed design. There are two parallel excitation/signal windings in the mover's and stator's slots. High-frequency voltages are utilised to feed the excitation windings, and the signal windings' induced amplitude modulated voltages are used to determine the mover's location in the plane. Time-stepping finite element analysis is also used to explore the effects of the ferromagnetic cores' finite size, winding design, and winding pole number.

DISCUSSION

Core Transformer Construction

In general, how the primary and secondary windings are twisted around the central laminated steel core determines the name given to the transformer structure. The Closed-core Transformer and the Shell-core Transformer are the two most popular and fundamental designs for building transformers. The magnetic flux between the main and secondary windings flows wholly inside the core in both kinds of transformer core designs, with no loss of magnetic flux via air. One half of the winding is wrapped around each leg (or limb) of the transformer's magnetic circuit when it is built using a core type transformer, as seen above.

In order to increase magnetic coupling and allow virtually all magnetic lines of force to pass through both the primary and secondary windings at the same time, the coils are not set up with the primary winding on one leg and the secondary winding on the other. Instead, half of the primary winding and half of the secondary winding are stacked concentrically on each leg. The term "leakage flux" refers to the tiny number of magnetic lines of force that flow beyond the core of this kind of transformer. The primary and secondary windings of shell type transformer cores are wrapped on the same central leg, which has double the cross-sectional area of the two outer limbs, therefore preventing leakage flux. The magnetic flux has two closed magnetic routes outside the coils on the left and right before returning to the core coils, which is advantageous in this situation.

Transformer Winding Configurations

Transformer windings, which are the primary current-carrying conductors coiled around the laminated portions of the core, are another crucial component of a transformer's design. Two windings would be included in a single-phase, two-winding transformer, as depicted. The main winding is the one that is linked to the voltage source, generates the magnetic flux, and induces a voltage by mutual induction in the secondary winding. A transformer is referred to as a "Step-down Transformer" if the secondary output voltage is lower than the main input voltage. A

"Step-up Transformer" is referred to as such if the secondary output voltage is higher than the main input voltage.

Core-type Building

Either copper or aluminium wire is utilised as the primary current-carrying conductor in a transformer winding. Although aluminium wire is lighter and often less costly than copper wire, it is primarily employed in bigger power transformer applications since a higher cross-sectional area of conductor is required to convey the same amount of current as with copper. Copper conductors are often utilised in low voltage electrical and electronic circuits because they have a better mechanical strength and a smaller conductor size than corresponding aluminium kinds. This is especially true for tiny kVA power and voltage transformers. The drawback is that these transformers may be rather heavy when they are fully assembled with their cores. Concentric coils and sandwiched coils are two major categories for transformer windings and coils. The windings are often placed concentrically around the core limb in core-type transformer construction, as illustrated above, with the higher voltage primary winding being coiled above the lower voltage secondary winding. Sandwiched or "pancake" coils are made out of flat conductors twisted in a spiral shape; the term comes from the way the conductors are arranged into discs. Individual coils are piled together and kept apart by insulating materials like paper or plastic sheet, and alternate discs are designed to spiral from the outside towards the core in an interleaved manner. With a core architecture of the shell type, sandwich coils and windings are more prevalent.

Transformer Dot Positioning

A laminated core cannot simply have one of the coil configurations wrapped around it. The secondary voltage and current may not be in phase with the main voltage and current, but that is a possibility. The orientation of each of the two coil windings in relation to the other is unique. To maintain track of their respective orientations and since each coil might be coiled around the core in either a clockwise or an anticlockwise direction, dots are employed to designate a specific end of each winding. The dot convention is the name given to this technique for determining a transformer's orientation or winding direction. The transformer's polarity is then defined as the relative polarity of the secondary voltage with regard to the primary voltage, after which the windings of a transformer are wound such that the right phase relations exist between the winding voltages.

Core Losses in Transformer Construction

The capacity to enable magnetic flux to flow is known as permeability, and it is significantly larger in steel or iron than it is in air. The majority of transformer cores are made of low carbon steel, which has a permeability of up to 1500 as opposed to merely 1.0 for air. This indicates that a steel laminated core is capable of carrying a magnetic flux 1500 times better than air. However, two different forms of losses in the steel happen when a magnetic flux runs in the steel core of a transformer. One was known as "eddy current losses" and the other as "hysteresis losses."

Losses from Hysteresis

The friction of the molecules with the magnetic lines of force needed to magnetise the core, which are constantly changing in value and direction first in one direction and then the other under the influence of the sinusoidal supply voltage, in transformer hysteresis losses. Heat is

produced of this molecular friction, which costs the transformer energy. The lifespan of the insulating materials used in the construction of the windings and structures might be shortened over time by excessive heat loss. A transformer's cooling is crucial. Transformers are also built to function at a certain supply frequency. Lowering the supply frequency will enhance hysteresis and raise the iron core's temperature. Therefore, dropping the supply frequency from 60 Hertz to 50 Hertz will increase the amount of hysteresis present and lower the transformer's VA capacity.

Losses from Eddy Current

On the other hand, circulating currents that are induced into steel of the passage of the magnetic flux around the core are what lead to transformer eddy current losses. These circulating currents are produced of the core behaving like a single wire loop in the magnetic flux. The eddy currents produced by a solid iron core will be substantial since iron is an excellent conductor. Eddy currents don't help the transformer be more helpful; instead, they operate as a negative force that causes the core to heat up and lose power as they fight the flow of induced current.

Losses of copper

However, the transformer is also responsible for a different kind of energy loss known as "copper losses". The electrical resistance of the primary and secondary windings is the principal cause of transformer copper losses. The majority of transformer coils are wrapped using copper wire, which has a resistive value in Ohms. According to Ohms Law, any magnetising currents passing through copper wire will be resisted by the copper wire's resistance. Large electrical currents begin to flow in both the main and secondary windings of a transformer when an electrical load is attached to the secondary winding, and electrical energy and power losses (the $I^2 R$) happen as heat. Copper losses often change with the load current, ranging from practically nil at no load to a maximum at full load when current flow is at its greatest.

To decrease these core and copper losses, a transformer's volt-amperes (VA) rating may be raised by improved design and construction. Conductors having a wide cross-section are needed for a transformer with high voltage and current ratings in order to reduce copper losses. By enhancing its insulation to tolerate greater temperatures or by boosting the rate of heat dissipation (better cooling) using forced air or oil, the transformer's VA rating may be raised.

Building a transformer core

The term "limbs" refers to the vertical portion of a core where the windings are installed, while the term "yoke" refers to the horizontal portion that joins the limbs. Transformers are divided into two groups based on the configuration of the main and secondary windings:

1. Transformers of the core type
2. Transformers of the shell type

Transformers of core type

The main and secondary winding are wrapped around the transformer limbs in core type design. The high voltage windings surround the low voltage windings, which are positioned further from the core.

Transformers with a single-phase core

The rectangular core of this kind of transformer has two limbs and two yokes. Each limb is wrapped with a portion of the main and secondary windings. It is maintained that the limb and yoke cross sections are identical. Because the windings in these types of cores are dispersed, the leakage flow is larger.

Construction of single-phase core type transformers

Three limbs and two yokes make up the core of this sort of transformer. They are often used for small and medium power rating three phase transformers. Each phase is looped around the transformer's legs individually. The magnetic fluxes that the phases cause have an algebraic sum that is always zero.

Construction of a transformer with a three-phase core.

To provide a better flow of magnetic flux, the windings of shell transformers surround the outer limb and the middle limbs.

Transformers of the shell type for one phase

The middle limb of the core is wrapped with windings in single-phase shell-type transformers. The auxiliary limbs are traversed by the magnetic flux. The cross-section of the auxiliary limbs and yoke must equal half that of the central limb. Given that it is more affordable than the core type, this style of building is favoured.

Shell type transformers for three phases

Five limbs make up the core of a three-phase shell type transformer. Three inner limbs are wrapped in primary and secondary windings, one set of primary and secondary windings for each phase. The height of the core may be lowered with the aid of this design. There are several possible arrangements for the limb and yoke diameters.

1. All yokes' cross sections may equal 50% of the cross section of the limbs.
2. The cross section of the inner yokes is 58% of inner limbs, and the cross section of the outer yokes is 45% of inner limbs.
3. Yokes and the outer limbs have cross sections that are 40% smaller than the limbs' cross sections.

Construction using a wound core and layered cores

A transformer core is created by joining thin steel sheets, or laminations, as was previously explained. These laminations may either be piled or wrapped around the coil. The CRGOS sheets are cut into the shape of the full wound core or a hollow rectangle to create wound cores. Then, a core is created by stacking these laminations together. After that, the core is sliced to allow for insertion via the coils. The cut-core is then put back together to create a step-style joint. Compared to stacked core structures, wound cores contain fewer joints. They may almost continuously pass the flux through them.

Constructed using stacked cores

The laminations for each of the yokes and limbs are cut independently in stacked core assembly before being merged to create the core. The corners of the stacked cores, where the yoke and the limbs intersect, contain gaps. When compared to wrapped core construction, these gaps provide

inferior magnetic properties. Both a circular and a rectangular core are possible. The cross-section of the core may be either rectangular or circular for single-phase transformers rated below 5MVA and three-phase transformers rated below 10MVA. Circular cross-sections are recommended to maximise the flux carrying area for all other transformers rated higher.

Core material for transformers

The choice of core material is influenced by the following factors:

1. The greatest magnetic induction.
2. Low no-load loss with little specific core-loss.
3. Low magnetic flux resistance.
4. A low apparent input of power.
5. Minimal noise due to low magneto striation.
6. Strong mechanical holding power for the windings.

Thin laminations of cold-rolled grain-oriented silicon steel (CRGOS), sometimes referred to as core steel, make up the transformer core. By alloying silicon with steel that has a low carbon concentration, the core steel is created. The permeability of CRGOS transformer cores is quite high. High permeability consequently lowers core losses and magnetising currents. In addition, silicon steel ages differently from non-silicon steel. In addition to the aforementioned, the CRGOS cores are made using a process called cold rolling, which modifies the grain's orientation in the direction of rolling. Reduced flux losses in the core will lower iron losses when magnetic flux is flowing in the direction of grain orientation. The issue with cold rolling is that higher core losses occur when the flux flow is opposite from the direction in which the grain is oriented. Additionally, core losses are impacted by mechanical loads, limb joints, and bolt holes.

The thickness of the cold-rolled, grain-oriented steel used for the transformer core lamination ranges from 0.18 mm to 0.35 mm. The lamination is divided into normal grain-oriented and HI-B steels based on the orientation of the grain. In addition, HI-B steel has lower watts/kg than CGO steel. Thinner sheets are usually preferred for core construction since eddy currents heavily rely on the thickness of the sheets and the frequency of the alternating current. Conversely, decreasing the thickness of the sheets causes the stacking factor to decrease. In a natural gas environment, debarring the sheets and annealing them at 800-900 degrees Celsius increases the stacking factor and reduces eddy current losses. Typically, heated steel slabs are used to crush the laminations into thin sheets. Additionally, the sheets have a Carlit coating on both sides to insulate them from the sheets next to them.

Leaching flux

According to the ideal transformer model, the main winding joins all the turns on all the other windings, including itself. In reality, some flux travels via routes that go away from the windings. This flux is known as leakage flux, and it produces leakage inductance in series with the transformer windings that are mechanically connected. With each cycle of the power supply, leakage flux causes energy to be alternately stored in and released from the magnetic fields. Although it does not immediately in a power loss, poor voltage regulation prevents the secondary voltage from being precisely proportionate to the main voltage, especially when a large load is present. Transformers are often built with very low leakage inductance.

Long magnetic pathways, air gaps, or magnetic bypass shunts may be purposefully included into a transformer's design to reduce the amount of short-circuit current it will deliver in situations when more leakage is required. Leaky transformers may be used to safely handle loads that occasionally short-circuit, such as electric arc welders, or to provide loads that display negative resistance, such as electric arcs, mercury- and sodium-vapour lamps, and neon signs. In particular, audio-frequency transformers in circuits with a DC component running in the windings employ air gaps to prevent saturation. Satiabale reactors use the core's saturation as a control mechanism for alternating current.

When operating transformers in parallel, understanding leakage inductance is also helpful. It can be shown that two transformers would share the load power proportionate to their individual ratings if their % impedance and related winding leakage reactance-to-resistance (X/R) ratios were equal. The impedance tolerances of industrial transformers, however, matter a lot. Additionally, various capacity transformers have varying impedances and X/R ratios.

Polarity

In transformer circuit nameplates, or terminal marks, a dot convention is often used to indicate the relative polarity of the transformer windings. Positive polarity voltage induces itself at the 'dot' end of the secondary winding when instantaneous current entering the main winding is positively rising. The phase relationships between the terminals of three-phase transformers used in electric power systems are shown on the nameplate. The kind of internal connection (wye or delta) for each winding may be indicated using an alpha-numeric code or a phase graphic.

Impact of repetition

At a given flux, a transformer's EMF rises with frequency. Transformers may be physically smaller by running at higher frequencies since a particular core can handle more power without becoming saturated and fewer turns are required to attain the same impedance. Core loss and the conductor skin effect, however, both become stronger with time. 400 Hz power supply are used in military and aviation systems to save core and winding weight. In contrast, certain railway electrification systems employed frequencies that were far lower than typical utility frequencies (50-60 Hz), such as 16.7 Hz and 25 Hz, for historical reasons mostly related to the limits of early electric traction motors. Compared to those needed for higher frequencies, the transformers used to step-down the high overhead line voltages were much bigger and heavier. Reduced magnetising current from operating a transformer at its specified voltage but at a greater frequency than anticipated. The magnetising current will rise at a lower frequency. It may be necessary to evaluate voltages, losses, and cooling when operating a big transformer at a frequency different than its design frequency to determine whether safe operation is feasible. To prevent overvoltage at a frequency greater than the transformer's rated frequency, protection relays may be needed.

Traction transformers, which are utilised for electric multiple unit and high-speed rail service running across areas with various electrical standards, serve as one example. The converter apparatus and traction transformers must be able to handle a range of input voltages and frequencies (rated up to 25 kV and as high as 50 Hz). A physically compact transformer can manage power levels that would call for a big iron core at mains frequency. At much higher frequencies, the size of the transformer core needed lowers substantially. Switch-mode power

supplies are able to create a high frequency and vary the voltage level with a small transformer thanks to the development of switching power semiconductor devices.

Core materials for transformers used in higher frequency applications, such SMPS, often have substantially lower hysteresis and eddy-current losses than those used in transformers for 50/60 Hz. Iron-powder and ferrite cores serve as prime examples. These cores' decreased frequency-dependent losses often come at the price of their reduced flux density at saturation. For instance, laminated iron has a much lower flux density at which ferrite saturation occurs.

Energy is lost

Winding and core losses make up the majority of transformer energy losses. Transformer efficiency typically rises as transformer capacity rises. Usually, distribution transformers have an efficiency of between 98 and 99 percent. Calculating no-load loss, full-load loss, half-load loss, and so forth is often helpful since transformer losses change with load. While winding loss rises as load increases, hysteresis and eddy current losses remain constant at all load levels and predominate when there is no load. Even an idle transformer depletes the electrical supply due to the potential severity of the no-load loss. A bigger core, high-quality silicon steel for the core, or even amorphous steel, and thicker wire are needed to design energy-efficient transformers with reduced loss, which raises the initial cost. The building method chosen indicates a trade-off between upfront expense and ongoing costs.

CONCLUSION

Increasing the coupling between the two windings and putting them into close proximity to one another can increase the efficiency of a simple transformer construction. The primary and secondary winding are wrapped around the transformer limbs in core type design. Closer to the core are the low voltage windings. Accuracy of current transformers with through-going primary cable is influenced by the choice of the core shape and winding configuration. The less energy that is wasted as heat as a result of circulation (eddy) currents in the core, the higher the resistance. To lower the transformer core's magnetic reluctance, ferromagnetic cores are frequently employed.

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MEASURES OF STRAY LOSS CONTROL IN TRANSFORMER

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ABSTRACT:

The typical induction machines (IM) model serves as the foundation for common vector controllers for induction machines. As a result, they are ignorant of the presence of iron losses and stray losses. In vector controllers, these losses might cause a significant disparity between the reference and real flow vectors. The operational flow and load have a significant impact on this imbalance. Two distinct strategies are discussed in this study for compensating for this mismatch. The first includes investing in IMs with low stray load and iron losses, while the second entails creating a control algorithm that accounts for both of these losses. Three small IMs with various efficiency classes and different rotor cage materials (copper vs aluminium) are used to assess the performance of the designed vector controller in comparison to the conventional controller. This chapter explores the measures of stray loss control in transformer.

KEYWORDS: *Leakage Flux, Transformer, Metal Structure, Power Transformer, Structural Components.*

INTRODUCTION

One of the most important and costly pieces of the power system equipment is the power transformer. The ratings of power transformers have significantly grown in recent decades due to the rise in electrical power consumption. Stray loss situation has emerged as a noteworthy aspect with such high evaluations. Losses in stray loads are caused by the flux coming from the current-carrying windings. The magnitude and intensity of the leakage flux, the permeability and resistivity of the metal structures, as well as the separation between the metal structures and the leakage flux source, all affect the losses. A severe local overheating might result from such significant stray losses in the metal structures[1].

Stray losses may account for a significant portion (20–25%) of the overall load loss if they are not effectively assessed and managed. Despite the fact that the transformer is the energy-efficient piece of equipment, reducing stray losses would increase thermal efficiency even further. The transformer benefits from optimal performance, low cost, improved loss capitalization, and longer life as a consequence. Eddy losses and circulating current losses in the transformer's windings are two examples of stray losses, as are losses in the structural components of the transformer, such as the flitch plates, end frames, and tank walls. The goal of this work is to decrease stray losses in structural components. The radial component of flux is considered to be a significant element in reducing stray losses. When stray flux leaves the winding in a radial direction, it causes eddy current losses in the transformer tank and strikes the flitch plates located on the core. Only the flux penetrating properly to the surface of structural components causes stray loss and additional temperature increase[2].

There are two main ways to reduce stray loss: electromagnetic shielding (using magnetic shunts) and eddy current shielding (using copper or aluminium shields). A bundle of core lamination known as a magnetic shunt draws flux and directs it through the core of a transformer, keeping it away from solid metallic components. Currents are generated on shield surfaces during eddy current shielding, which repels the incoming field and lowers losses in metallic components. There has been a lot of study recently on reducing stray loss in power transformers that use just one of the aforementioned shields. Innovative shield configurations are employed in a transformer in this work's cutting-edge design to significantly reduce loss. For stray loss reduction, power transformers often utilise either Cu sheets or wall shunts. However, using shunts and Cu screens in tandem with strategically positioned them reduces total stray loss by up to 60%.

In order to increase the thermal performance of the transformer and achieve better loss reduction, this study discusses combinations of stray loss mitigation methods (such as shunts and eddy current shields). Analysis is also done on the impact of various metallic construction materials on hot spot temperatures. In this research, the behaviour and properties of structural components are examined using Dirichlet boundary conditions. The stray loss and hotspot temperatures are examined in this paper using a three-dimensional (3D) finite element technique (FEM).

Mateo et al. in [3], explored the typical IM model serves as the foundation for common vector controllers for induction machines. As a result, they are ignorant of the presence of iron losses and stray load. In vector controllers, these losses might cause a significant disparity between the reference and real flow vectors. The operational flow and load have a significant impact on this imbalance[4]. In this study, two distinct strategies are taken into account to correct for this mismatch: the first entails investing in IMs with low stray load and iron losses, while the second involves creating a control algorithm that accounts for both of these losses[5]. Three small IMs with various efficiency classes and different rotor cage materials (copper vs aluminium) are used to assess the performance of the designed vector controller in comparison to the conventional controller. Various loads, speeds, and magnetization levels are tested experimentally and in simulation. The controller detuning is measured using the predicted rotor speed. Here, a typical estimator is changed for the first time to take into account stray load and iron losses inside the model reference adaptive system. The last issues are those with numerical integration, sample frequency, and temperature-induced changes in IM parameters.

Leonardo [6] and Strac, et al. [7] elucidated that transformers are made up of two windings, a primary and secondary winding, and an alternating magnetic field in their most basic configuration. High permeability iron core is where the majority of the magnetic field is located. Every transformer, however, also has a stray magnetic field component that does not coupling the main and secondary windings. Stray losses are the losses in a transformer's metal component caused by the stray component of the magnetic field. The stray magnetic field in a power transformer helps to reduce the short-circuit current in the grid even if it causes losses. Power transformer manufacturers created a variety of mitigation strategies to deal with the drawbacks of the stray field. The article offers suggestions for reducing stray losses outside of the winding, including raising magnetic resistance and using both active and passive magnetic shields. A case study for three-phase shunts used on a 245 kV, 500 MVA transformer is also included.

There is a very significant risk of electrical shock from arc welding processes. The issue has

received attention recently in Canada due to a spate of deadly welding accidents and catastrophic injuries. Technology like the VRD is widely accessible on new arc welding equipment or may be incorporated as an after-market item to prevent secondary voltage dangers[8]. The chance of receiving an electric shock from these dangers may be significantly decreased or completely avoided with training and enforcement for strict adherence to best practises for PPE and equipment maintenance. It is also possible to think about changing a higher-risk procedure, like SMAW, for a lower-risk one, like FCAW. The stringent universal adherence to approved practises is now the sole preventive strategy available for dangers caused by stray welding current. Welder electrocutions have been linked to damage caused by stray welding current, which may cause large financial losses. A stray-current interrupter device, a new technological advancement, claims to provide an engineering solution to this issue.

DISCUSSION

The single-phase generator power transformer under inquiry has ratings of 315 MVA, 420/27 kV. Models were created for the transformer's half. Given that the findings in this paper are for the half-transformer model, the overall losses in the transformer will be two times higher (taking z-plane symmetry into account)[9]. For the tank walls, flitch plates, and end frames, non-linear conducting mild steel was utilised. For certain structural elements, a "surface impedance boundary condition" is included since mild steel is a ferromagnetic material. The transformer model's number of turns and strand area are used to simulate coil windings. A flitch plate with three openings that is 20 mm deep has been created. Modelled end frames have a hollow-box design. We failed to consider the effects of leads, bushings, and tapings in our study. Also ignored are the losses in the previous core stack. For accurate finite-element analysis, appropriate meshing values are provided.

This study's analysis was resolved using the electromagnetic FEM software MAGNET. Eddy current-related issues may be analysed in three dimensions using this programme, which also provides loss distribution for all conducting components. To determine temperature increase in all those conducting components, these losses may be read in THERMNET (FEM) programme. Conduction, convection, and radiation-related thermal issues may be resolved via THERMNET. The conducting portions must receive an "environmental boundary condition" for temperature analysis, together with the heat transfer coefficient between the surface and environment. The figure of 70 is believed to represent the rate of heat transfer from metal to oil. To estimate stray losses and hotspot temperatures, a 3D time-harmonic coupled study of the transformer model is carried out.

A continuity tester should be used frequently to check that there are no shorts between any of the parallel strands of the winding since any shorts will cause circulating current to flow and, as a consequence, will produce stray losses. Continuous transposed cable/conductor is a cable that is made with a greater number of strands depending on the current and size before each strand is individually insulated with super enamel varnish and lastly covered with paper in accordance with the design specifications. Even with a soft plastic mallet, stress and placement of turns and conductor during winding may sometimes harm the enamel varnish, resulting in inter strand shorts and ultimately increasing stray losses.

Stray Losses Associated with Magnetic Flux Linkage

The magnetic conductive materials, such as the body of the MS tank, the frame part, and the core

lamination, have the highest magnetic flux linkage. The stray losses in the transformer are a result of leakage flux, which is one of the lines of flux that cannot return to its principle or originating field owing to a lengthy trip. Leakage flux is produced when the frequency changes and begins to connect with magnetic material. Figure 1 reducing stray losses in transformer.



Figure 1 Reducing stray losses in transformer [ElectricalIndia].

The benefits of the above two shields are numerous They lower the transformer's stray losses by 40–45%. They prevent the core and coil from overheating, which lowers the winding and oil's overall temperature rise by 7–10%. They provide a stable common base for the three phases of winding, which prevents the forces' effects from becoming unbalanced during short circuit short applications. According to Lenz's Law, when all of the primary's magnetic field is intercepted by the secondary winding, an induced E.M.F known as back E.M.F and current known as eddy current result. This eddy current causes losses in the transformer winding, and the losses caused by eddy current in the transformer winding are known as stray losses. Due to the presence of skin effects in this situation, these losses depend on the frequency of alternating supply. These losses, which are inversely correlated with frequency during inrush current (harmonics), rise as frequency rises. A part of the leakage flux might cause an eddy current to generate in surrounding conductive items like the support for the transformer or the MS structure, and this current could then be heated. Magnetic shielding of the tank from the HV side for the best transformer design under investigation in order to choose the version that would protect the wall the best while minimising losses. Where hotspots were anticipated, the horizontal shunts were added and the vertical shunts were shortened.

CONCLUSION

This book chapter explores about the measures of stray loss control in transformer. It is vital to protect the plate in flitch plates to effectively decrease hot areas and stray losses. This may be done by putting shunts, or what we referred to as limb shunts, next to the flitch plate on the core limb. Iron losses are another name for stray losses. Eddy currents are caused by the leakage field that is present in the transformer and they cause stray losses in conductors, tanks, channels, and bolts. Induction machine loss from causes other than main or secondary copper loss, no load core loss, friction and wind age loss is referred to as stray load loss. In general, magnetic shunts, FRSL testing, and coupled electromagnetic-thermal field analysis are methods of stray loss control in transformers. These actions can increase the transformer's effectiveness and lower overall losses. Some methods for reducing stray losses in transformers include mounting magnetic shunts,

wisely choosing magnetic shunts, horizontal magnetic wall shunts, and improved width wise electromagnetic shunts.

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ANALYSIS OF SHORT CIRCUIT CURRENT IN POWER SYSTEM

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ABSTRACT:

The current that passes through a short circuit and can harm electrical systems and equipment is known as short circuit current. The system voltage and the system impedance are two crucial factors that affect the short circuit current's size. The system's short circuit current capacity is determined using a short circuit current analysis, which compares the magnitude of the short circuit current to the interrupting rating of the overcurrent protection devices (OCPD). The available fault current or short circuit current at each location in the system is determined using a short circuit analysis. The relative phases of the currents and voltages at various points of the system during short circuits are frequently required for relay problems, in addition to the knowledge of the magnitude of short-circuit currents. This chapter explores the short circuit current analysis.

KEYWORDS: *Circuit Current, Electrical Systems, Power System, Short Circuit.*

INTRODUCTION

In a power line, power transformer, or any other power element, when two or more conductors of various phases come into contact with one another, a portion of the impedance is shunted out of the circuit, causing a significant current to flow in the phases that are not defective. This current is known as the short circuit current. While the circuit's current increases, short circuit current lessens the impact of impedance. A short circuit is a link that shouldn't exist between two electrical circuit nodes that are supposed to be at different voltages. As a consequence, an electric current that may destroy circuits, produce overheating, fire, or explosions is only constrained by the remaining network's Thevenin equivalent resistance. Although short circuits are often the consequence of a defect, they may sometimes be created on purpose, such as when using voltage-sensing crowbar circuit protectors.

A short circuit is described as a link between two nodes that requires them to have the same voltage in circuit analysis. This indicates that there is no resistance and, hence, no voltage drop across the connection in an "ideal" short circuit. The outcome is a link with nearly low resistance in actual circuits. The sole factor limiting the current in such a situation is the remaining circuit's resistance. When a battery's positive and negative terminals are linked via a low-resistance conductor, such as a wire, a short circuit of this kind often happens. Low resistance in the connection will allow for a high current to flow, which will supply a lot of energy quickly [1]–[3].

An explosive explosion with the emission of hydrogen gas and electrolyte (an acid or a base), which may burn flesh in blindness or even death, can happen when a battery has a high current

running through it. Wires that are overloaded can also overheat, which might lead to a fire or damage to the insulation. Unintentional short circuits in electrical equipment often occur when a wire's insulation fails or when another conducting material is added, enabling charge to flow in a direction other than that intended.

Short circuits may happen between two phases, between a phase and neutral, or between a phase and earth (ground) in mains circuits. Such short circuits are probably going to produce a lot of current, which will immediately activate an overcurrent protection mechanism. Short circuits may, however, develop between conductors of the same phase as well as between the neutral and earth wires. Such short circuits may not instantly in a big current, making them less likely to be noticed and potentially harmful. Unexpected energization of a circuit that was thought to be isolated is one of the potential outcomes. Power distribution transformers are purposefully designed to have a particular degree of leakage reactance to assist lessen the damaging effects of short circuits. Both the amplitude and the rate of increase of the fault current are limited by the leakage reactance, which is typically between 5 and 10% of the full load impedance.

An electric arc might emerge of a short circuit. The arc, a stream of hot, ionised plasma, is very conductive and may continue to exist long after the conductors' initial material has evaporated to a large extent. A common indication of electric arc damage is surface erosion. Significant quantities of material may be removed from the electrodes by even brief arcs. Due to the electrical arc's very high temperature (tens of thousands of degrees), the metal on the contact surfaces melts, pools, and migrates with the current, releasing tiny particulate debris into the atmosphere.

Within milliseconds, a short circuit fault current might be millions of times bigger than the system's typical operating current. Fuse, circuit breaker, or other overload protection devices, which cut off the power in response to high current, may decrease or prevent damage from short circuits. The current rating of the circuit must be taken into consideration while selecting overload protection. When compared to lighting circuits, big household appliance circuits need protection devices that are configured or rated for larger currents. Wire gauges are selected in accordance with construction and electrical requirements to provide safe operation when combined with overload protection. The greatest potential short-circuit current must be securely interrupted by an overcurrent protection mechanism.

The overcurrent from a short circuit may heat circuit components with low conductivity (such as bad wire joints, faulty power socket contacts, or even the short circuit site itself) in an incorrect installation. Fires often start because of this warming. If it develops during a short circuit, an electric arc generates a lot of heat and has the potential to ignite flammable materials. High short-circuits currents produce dynamic forces that spread conductors apart in utility and industrial distribution systems. The forces produced by a short circuit may damage bus bars, wires, and equipment.

Because there is always zero potential difference between an operational amplifier's input terminals, regardless of the output voltage, the ideal model (infinite gain) is said to create a virtual short circuit between them. The second input terminal is said to as providing a virtual ground if one of the input terminals is linked to the ground since its potential is (ideally) the same as the grounds. Because a perfect operational amplifier also has infinite input impedance, unlike a genuine short circuit, the virtual short does not have current flowing between its terminals.

LITERATURE REVIEW

Zhang et al. explored that induction motors in the distribution network will contribute to the short-circuit current when a short-circuit failure in the power grid occurs. For the motors short-circuit current calculations to be accurate, a thorough distribution network model is needed. Large-scale electricity grids are not a good fit for this technology. This study proposes an analogous modelling approach for the short-circuit current contribution from induction motors that is suited for large-scale grid calculations without altering the fundamental short-circuit current algorithm or the fundamental electromechanical transient data format. The Central China Power Grid is used as an example, and real fault inversion is used to confirm the correctness of the suggested approach.

Pan et al., discussed that the current national standard mandates that the induction motor load's contribution to short circuit current be taken into account, but China lacks an induction motor modelling technique suitable for power grid simulation calculations, which has an impact on the adoption and use of the national standard algorithm. The equivalent method of 110 kV/220 kV bus conversion coefficient of motor contribution short-circuit current in distribution network is proposed. It is based on the simulation and calculation of Central China Power Grid and takes into account the distribution characteristics of medium and low voltage motors on the short-circuit current of high voltage bus.

Liu et al., explored that due to its many benefits, the modular multilevel converter (MMC) has been extensively used in high voltage direct current (HVDC) transmission systems. In order to increase dependability, MMC-HVDC is moving towards a multi-terminal direct current (MTDC) power system. However, the low impedances of DC lines and MMCs cause a large amplitude and a sharp rise in fault current, endangering the security and dependability of the DC power grids. To maintain the secure and reliable functioning of DC power grids, the DC short circuit current must be constrained. In terms of MMC modelling, short circuit calculation, and suppression method, this study provides a thorough examination and evaluation of the suggested DC short-circuit current analysis and suppression strategies employed in MTDC power grids. Future developments in short circuit current protection in MTDC power grids based on MMC are also highlighted.

Wira et al., discussed that Maximum Power Point Tracking (MPPT) system must have an output that is close to 100% if photovoltaic (PV) systems are to be significantly more efficient. MPPT techniques, including the fractional open-circuit voltage (FOCV), perturb and observe (P&O), fractional short-circuit current (FSCC), incremental conductance (INC), fuzzy logic controller (FLC), and neural network (NN) controllers, are used to manage this process. One current sensor is all that is required to implement the FSCC algorithm. The unique presence of the linear approximation between the Maximum Power Point (MPP) current and the short-circuit current under normal circumstances is the foundation of this technique. This MPPT optimisation technique is quick, however in order to get the short circuit current, each time it is used, the PV panel must be shorted. Energy is lost throughout this process, and oscillations are quite high. We suggest an approach based on the straightforward reading of the PV panel's output current in order to directly identify the short-circuit current in order to enhance the FSCC algorithm. By increasing or decreasing the sun irradiation, this parameter enables the short circuit current to be calculated immediately. In comparison to the traditional FSCC approach, experimental findings reveal that the upgraded algorithm exhibits temporal response attenuation, few oscillations,

power loss reduction, and greater MPPT accuracy[4]–[6].

Niancheng Zhou et al., explored that with a large penetration of VSC-based renewable energy, the power grid's short-circuit current level will rise, and the fault characteristics will alter due to a strong interaction between the transient fault process and control approach. According to the transient properties of short-circuit current, the total current expression of VSC-based renewable energy was achieved. Additionally, equivalent circuits of VSC-based renewable energy for fault transient state and steady state were proposed by examining the closed-loop transfer function model of the controller and current source characteristics presented in steady state during a fault. The theory's accuracy was subsequently confirmed by experiments. Additionally, the superposition theorem was used to determine the AC component and DC component of the short-circuit current for the power grid using renewable energy based on VSC, and the peak value of the short-circuit current was successfully evaluated. The computed findings might be used to relay protection alterations, short-circuit current control, and grid planning and design. The efficiency of the suggested technique was confirmed by comparing the calculation and simulation results of the 6-node 500 kV Huainan power grid with the 35-node 220 kV Huaisu power grid.

Sher et al., explored that the recommended study offers a novel approach for calculating the photovoltaic (PV) system's short-circuit current (ISC) and open-circuit voltage (VoC). Additionally, a modified relation of reverse saturation current (I_s) is employed to avoid misestimating the values of I_{sc} and V_{oc} at any P-V curve location. The cost of the suggested approach is further decreased by using a novel current-sensor less method of PV current estimate. Testing on three distinct PV panels, including the Yingli 245C-30b, Sharp NT-180U1, and Risen SYP-110S, is done to determine the correctness of the suggested approach. Additionally, the proposed and conventional analytical methods are used to implement the fractional short circuit current (FSSC) and fractional open-circuit voltage (FOCV) algorithms, and the results are contrasted. The Matlab/Simulink and hardware testing used to verify the suggested technique. The results of the proposed method show the following benefits: 1) precise prediction of the I_{sc} and V_{oc} values at any point of the P-V curve, 2) uninterrupted output power during the I_{sc} and V_{oc} measurement, 3) accurate sensorless estimation of PV current, 4) no overshoot and undershoot in the tracked power of PV module, and 5) significantly improved tracking efficiency by 38.33% for the FSSC algorithm and 28.2% for the FOCV algorithm compared to the previous method.

V. María Barragán et al., explored that non-isothermal electrochemical devices used to produce electricity from thermal energy. Along with the ion flux, heat is also transferred in a thermocell, which can lessen the temperature gradient and, in turn, the amount of delivered current. This issue might be mitigated by using a charged membrane as a separating barrier in the electrolyte liquid. As a result of their high Seebeck coefficient, ion-exchange membranes have been recommended as a thermoelectricity alternative. When a temperature gradient is applied, ion transfer happens not only at the liquid solution but also at the solid membrane. As a result, the thermocell's ability to provide an electric current will also be greatly influenced by the characteristics of the membrane system. This paper investigates the performance of a polymeric membrane-based thermocell with 1:1 alkali chloride electrolytes and reversible Ag|AgCl electrodes at various temperatures. The experimental relationship between the short-circuit current density and the temperature differential is the main emphasis of this study. The greatest electric current that a thermocell can provide is known as the short-circuit current, and it is

inversely proportional to the maximum electrical output power. As a result, it may provide insightful data on the effectiveness of the thermocell. From an experimental standpoint, the influence of the membrane, electrolyte type, and hydrodynamic circumstances is investigated.

Han et al., explored that bus and line separation techniques are optimised using genetic programming (GP) in order to lower the short-circuit current. The grid impedance decreased as a result of increased electric power efficiency and transmission lines. Because of this, short-circuit currents are generated more often during failure, making it hard to keep creating higher-capacity breakers to handle them. Therefore, busbar separation and line separation are necessary for the systematic management of short-circuit currents. For power systems, there are innumerable different bus and line separation strategies. In addition, no lines or transformers should be overloaded once such controls are implemented in order to adhere to criteria for power-system dependability. In order to find a solution, this study suggests using GP to optimise the bus and line separation procedures. The convergence probability and optimisation time are decreased since the solutions are restricted to techniques that may be used in actual power systems. The suggested method is helpful for building power systems that take the short-circuit current into account.

Hussain Al Mahdiet al., explored that the deterioration of the ethylene-vinyl acetate (EVA) encapsulant caused by extended UV exposure and other environmental stress factors, such as temperature and humidity, is one of the often occurring failures in solar modules. Experimental investigations have shown that a large loss in optical transmission caused by EVA deterioration results in a loss of more than 50% of the available power. The early deterioration of the EVA encapsulant is predicted using a unique method in this paper that links short-circuit current (ISC) with EVA degradation. The short-circuit current acquired under varied optical transmission brought on by EVA discolouration is evaluated using an electrical circuit simulator called Simulation Programme with Integrated Circuit Emphasis (SPICE). The simulation is performed in three steps to produce the short-circuit current (ISC), maximum power output (Pmax), open-circuit voltage (VOC), and fill factor: simulation of the transmitted solar spectrum, simulation of the spectral short-circuit current density, and simulation of the current-voltage (I-V) curve. Results indicate that the decrease in short-circuit current caused by EVA deterioration is different from the decreases anticipated as a result of a spectrally uniform decrease in solar irradiation.

Jan Herterichet al., conducted a research that employing phenethylammonium iodide (PEAI) as n-side passivation in p-i-n perovskite solar cells results in a significant short-circuit current density (JSC) loss. Different theories for the cause of the JSC loss are presented and assessed by contrasting experiments with drift-diffusion simulations. The examined cell stack's optical characteristics stay the same, but the internal quantum efficiency of the PEA-based devices substantially declines. The causes of the charge extraction restriction are ruled out, including strong bulk doping and interface traps. The inhomogeneity of the PEA-based quasi-2D perovskite wide-bandgap interlayer, which is discovered to be critical for the observed JSC loss, is directly imaged by high-spatial resolution photoluminescence (PL) spectroscopy. The observed behaviour is faithfully reproduced by a 2D drift-diffusion model with mobile ions and an inhomogeneous electron transport layer. The effective charge-carrier diffusion length is shortened by the ionic space charge distribution under short circuit, which prevents charge from moving towards the domains in the perovskite-electron transport layer interface where electrons may be extracted effectively. The JSC loss is decreased by a longer charge-carrier lifetime,

emphasising the significance of suppressed non-radiative bulk recombination for both reaching high open-circuit voltages and effective charge extraction[7]–[9].

DISCUSSION

The short-circuit current is often determined in power transmission systems and industrial power systems using the nameplate impedances of connected equipment and the impedance of interconnecting wire. Hand computation is viable for small radial distribution systems with few parts, but software is often employed for more complicated systems. The time-varying impact of spinning machines' contribution to a short circuit may be assessed when they are present in the system (such as generators and motors). The interrupting rating chosen for circuit breakers and fuses is impacted by the fact that stored energy in a generator may contribute much more current to a short circuit in the first few cycles than afterwards. To guarantee that it can generate enough current on a short circuit to let subordinate overcurrent protection devices to function effectively, an isolated generator may be specifically built.

The short circuit level at the point of connection, when an industrial system is supplied by an electrical utility, may be stated, often with minimum and maximum values or values to be anticipated following system expansion. This enables an industrial client to calculate the internal fault levels in its facility. The assumption of an "infinite bus" with zero effective internal impedance in a prospective short-circuit current that is only constrained by the impedances after the defined "infinite bus" if the prospective short-circuit current from the utility source is very large compared to the customer's system size.

Phase-to-phase, phase-to-ground (earth), and phase-to-neutral faults in polyphase electrical systems are often investigated, together with a scenario in which all three phases are shorted out. The potential short-circuits current changes based on the kind of fault because cables' or devices' impedances vary across phases. The system's protection mechanisms must react to each of the three scenarios. Analysis of unsymmetrical faults in three-phase systems is made easier by using the approach of symmetrical components. The maximum electric current that might be present in a certain electrical system under short-circuit circumstances is called the prospective short-circuit current (PSCC), also known as the available fault current or short-circuit making current. It is governed by the supply system's voltage and impedance. For a typical household mains electrical installation, it is on the order of a few thousand amps, but it may be as low as a few mill amperes in a segregated extra-low voltage (SELV) system or as high as tens of thousands of amps in massive industrial power systems.

To securely safeguard the circuit from a fault, protective devices like circuit breakers and fuses must be chosen with an interrupting rating that exceeds the potential short-circuit current. When a significant electric current is interrupted, an arc occurs, and if a fuse or circuit breaker's breaking capacity is exceeded, it won't be able to put out the arc. The current will not stop, causing equipment damage, a fire, or an explosion. A switch protected by a suitable short circuit protective device (SCPD) in series but lacking integral short-circuit protection can withstand a conditional short-circuit current of a certain value for the duration of the current's operation under certain test conditions. It may be interpreted as the RMS value of the maximum allowable current for the operating circumstances and the time period (t_0 , t_1).

A transient defect is one that disappears if power is briefly cut off and then turned back on, or an insulation fault that momentarily degrades a device's dielectric qualities before returning to

normal. Overhead electricity lines often experience transitory problems. Equipment for power system protection kicks into action to isolate the problem location when it happens. The transient fault will then go away, allowing the power line to be used again. Examples of transitory faults include the following:

1. Brief interaction with trees; Brief contact with birds or other animals
2. Lightning bolt
3. Conductor squabbles

In the case of a transient failure, transmission and distribution systems utilise an automated re-close feature, which is often used on overhead wires to try to restore power. On subterranean systems, this feature is less frequent because the defects there are more often of a permanent type. As fault current is created, transient faults may still in damage, either at the initial fault location or elsewhere in the network.

Perpetual error

Regardless of the amount of power being supplied, a permanent malfunction exists. The majority of faults in subterranean electrical lines are chronic because of mechanical damage to the wire, however lightning may sometimes cause temporary faults.

Fault categories

Not all phases are impacted equally by an asymmetric or unbalanced fault. Common asymmetric fault types and their causes are as follows:

1. Line-to-line fault: a physical contact between lines, such as from a busted insulator, or an air ionization-induced short circuit between lines. Asymmetric line-to-line problems make up around 5% to 10% of transmission line defects.
2. A line-to-ground fault is a short circuit between a line and the ground that is often brought on by physical contact, such as that brought on by lightning or other storm-related damage. Asymmetric line-to-ground problems make for around 65% to 70% of transmission line defects.
3. Double line-to-ground faults, which often from storm damage and include two lines coming into touch with the ground (and one another). 15% to 20% of all transmission line failures are asymmetric double line-to-ground faults.

Symmetrical error

A balanced or symmetric defect has an equal impact on all phases. About 5% of failures in transmission lines are symmetric. When compared to asymmetric defects, these faults are uncommon. Line to line to line (L-L-L) and line to line to line to ground (L-L-L-G) are the two types of symmetric faults. Approximately 2 to 5% of all system problems are symmetrical. However, even if the system is still in balance, they may seriously harm equipment.

The largest possible short-circuit current is possible when the defect has zero impedance, which is one extreme. A "bolted fault" occurs when all conductors are ostensibly linked to ground as if via a metallic conductor. A metallic short circuit to earth would be uncommon in a well-designed power system, although such defects might happen accidentally. To hasten the action of

protective devices, a "bolted fault" is purposefully inserted in one form of gearbox line protection.

Earth fault or ground fault

Any malfunction that enables an unauthorised connection of power circuit conductors with the earth is referred to as a ground fault (or earth fault). Such defects may in undesirable circulating currents or may energise the device housings at a hazardous voltage. A single ground fault may be tolerated by certain particular power distribution systems, allowing them to continue operating. In this situation, an insulation monitoring device may be required by wiring regulations to sound an alert so that the source of the ground fault may be found and fixed. In such a system, the development of a second ground fault may lead to component failure or overcurrent. Some applications need the use of a Ground Fault Interrupter or similar device to detect faults to ground, even in systems that are typically linked to ground to prevent overvoltage[10].

Authentic flaws

The resistance in a defect may, in reality, range from being almost negligible to being rather significant in comparison to the load resistance. In contrast to the zero-impedance situation, when the power is zero, a significant amount of power may be consumed in the failure. A simple resistance is a bad model since arcs are also quite non-linear. A thorough study must take into account every scenario that might occur.

An electric arc may emerge between the conductors of the power system and ground if the system voltage is high enough. Such an arc may have a significantly high impedance (in comparison to the system's typical operating levels) and be difficult to locate using straightforward overcurrent prevention. For instance, a few hundred-amp arc on a 1,000-amp circuit may not trigger overcurrent circuit breakers, but it might severely damage bus bars or cables before it causes a full short circuit. Additional safety measures are in place for utility, industrial, and commercial power systems to catch tiny yet unwanted currents that are leaking to ground. Arc-fault circuit interrupters may now be required by electrical codes for home wiring in order to detect tiny arcs before they in damage or a fire. These precautions are implemented, for instance, in areas with flowing water.

Finding and identifying problems

It is possible to locate problems in a cable system with the circuit de-energized or, in certain circumstances, with the circuit powered. The two main types of fault-finding methods are tracer methods and terminal methods, which both involve examination throughout the length of the cable. Terminal methods employ voltages and currents monitored at the ends of the wire. To speed up tracing on a lengthy or buried cable, terminal approaches might be utilised to pinpoint the overall location of the issue.

Inspection of the wires may often identify the problem site in extremely basic wiring systems. A Time-domain reflect meter is used to find wiring defects in complicated wiring systems, such as the wiring in aeroplanes, where the wires may be concealed. To find flaws in the electrical wire, the time domain reflect meter sends a pulse down the wire and then examines the pulse that is reflected back. Sensitive galvanometers were employed in historical undersea telegraph cables to detect fault currents. By testing a cable at both ends, the defect site could be located to within a

few miles, enabling the line to be raised and repaired. For finding cable defects, there were two different kinds of connections: the Murray loop and the Valery loop.

At lower voltages, an insulation defect in a power wire may sometimes go undetected. The cable is pulsed with a high-energy, high-voltage pulse using a "thumper" test equipment. By keeping an ear out for the sound of the discharge at the fault, a defect may be located. Although this test causes damage to the cable site, it is necessary since, in any event, the faulty point would need to be re-insulated. A feeder may develop a defect to ground in a grounded distribution system with high resistance, yet the system keeps running. With all of the phase wires of the circuit collected in a ring-type current transformer, the defective yet energised feeder may be identified; only the circuit with a fault to ground will display a net imbalanced current. The system's grounding resistor may be altered between two values to create pulses in the fault current, which will make it simpler to identify the ground fault current.

Limiting reactor for current

Current limiting reactors in electrical engineering may lower short-circuit currents, which are caused by plant expansions and new power sources, to levels that can be handled effectively by existing distribution equipment. They may serve a similar function in high voltage electric power transmission systems as well. Current limiting reactors may be used to limit the beginning current of electric motors or as a component of a speed control system.

Operation

When it is determined that the potential short-circuit current in a distribution or transmission system would exceed the interrupting rating of the related switchgear, a current limiting reactor is utilised. The inductive reactance is set to be strong enough to prevent a short circuit and low enough to allow for an acceptable voltage drop during normal operation. The percentage increase in system impedance that a current-limiting reactor gives determines the level of protection it provides.

Limiting reactor for current

Reducing short-circuit currents allows circuit breakers with lower short circuit breaking capacities to be employed, which is the major goal of utilising current limiting reactors. They may also be used to restrict the inrush current while starting a big motor and to safeguard other system parts against excessive current levels.

Reactor in line

An inductor connected in a line between a power source and a load is called a reactor. In addition to its role in current limitation, the device also filters out current spikes and may lessen harmonic current injection into the power supply. The kind that is used most often is made for three-phase electric power, in which three isolated inductors are each coupled in series with one of the three-line phases. Line reactors may be used to safeguard motors and variable-frequency drives as well as to restrict beginning current in equipment that is motor-driven.

Ratio of short circuits

An electromechanical generator's stability is gauged by the short circuit ratio (SCR). It is the difference between the field current needed to generate the rated armature voltage at an open circuit and the field current needed to generate the rated armature current at a short circuit. On a

grid, the SCR may be computed for each point. A grid has strong grid strength when the SCR is over one. It will be less impacted by frequency changes and may produce more short circuit current.

Concerns regarding the stability of the system are often raised when integrating renewable energy sources. The strength of a power system, which evaluates how sensitive its variables are to disturbances, determines the effectiveness of its various components. The short circuit ratio (SCR), which measures system strength, is a measure of a network bus's strength relative to a device's rated power. A stronger system will have a lower effect of disturbances on voltage and other variables, which is shown by a greater SCR rating. SCR is defined as the ratio of the device's MW rating to the short circuit capacity at the bus where it is installed. An SCR of three or above is considered to be a strong system, whereas SCRs of three to two or below are considered weak and extremely weak systems, respectively.

SCR-related problems are often encountered in power electronic applications, especially in renewable energy systems that employ power converters to link to power grids. There are certain technologies that must be used in order to overcome SCR of less than three when connecting HVDC/FACTS devices based on current source converters to weak AC systems. In applications with SCR close to one, voltage-source-based converters or capacitor-commutated converters are used for HVDC. As low levels of SCR may in issues such excessive overvoltage, low-frequency resonances, and control system instability, failing to apply these technologies would need additional studies to ascertain the impact and take action to mitigate or minimise the negative impacts.

Away from the primary regions of electricity demand, wind farms are often connected to less stable network segments. It is vital to pay attention to difficulties with voltage stability that from integrating large-scale wind power into weak systems. There are certain minimum system strength requirements for some wind turbines. GE claims that systems with a Short Circuit Ratio (SCR) of five or higher may use the wind turbine model's standard characteristics. To ensure that the model parameters are properly updated, more study is required if linking to weaker systems. To guarantee optimum performance, special wind turbine control techniques or dynamic reactive compensating tools like STATCOM are needed.

Generator SCR

Alternator reactance (X_d) and inductance L_d decrease with SCR size. Larger air gaps in generator designs (such as hydro generators or salient pole machines) are the cause of this. As a consequence, the Machine is only weakly linked to the grid, which slows down its reaction time. The machines are more stable when using the grid, but at the same time, they may produce more short circuit current (a greater short circuit current), which in bigger machines and higher costs. SCR for hydro alternators is typically in the range of 1 to 1.5.

On the other hand, the bigger the alternator's reactance (X_d), the lower the SCR, and the larger the L_d . It happens as a consequence of tiny air gaps in the design of the equipment (as in turbo generators or cylindrical rotor machines). Machines will respond quickly since they are closely tied to the grid, the machine will be less stable while using the grid, have a reduced capacity to produce short circuit current (lower short circuit current), be smaller, and cost less money. SCR ratings for turbo alternators may often fall between 0.45 and 0.9.

Effect on the grid

For any location on an electrical grid, the SCR may be determined. Voltage instability is less likely to occur at a grid node that includes a significant number of machines with SCRs greater than or equal to a figure between 1 and 1.5. Thus, a powerful grid or power system is what is known as such a grid. Lower SCR power systems (grids) are more susceptible to grid voltage volatility. A weak grid or weak power system is what such a grid or system is known as.

Breaker circuit

A circuit breaker is a kind of electrical safety device used to guard against overcurrent damage to electrical circuits. Its primary purpose is to stop the flow of electricity in order to safeguard machinery and lower the likelihood of a fire. To restart normal functioning, a circuit breaker may be reset (manually or automatically), unlike a fuse, which can only be used once before needing to be replaced. There are many different sizes of circuit breakers, from tiny devices that protect low-current circuits or specific home appliances to massive switchgear built to safeguard high voltage circuits supplying a whole city. The acronym OCPD (Over Current Protection Device) is often used to refer to the general purpose of a circuit breaker or fuse, which is to automatically cut power to a malfunctioning system.

Origins

Despite using fuses for his commercial power distribution system, Thomas Edison detailed an early kind of circuit breaker in a patent application from 1879. Its goal was to safeguard the wiring in lighting circuits against unintentional short circuits and overloads. In 1924, Brown, Boveri & Cie received a patent for a contemporary micro circuit breaker that is comparable to those in use today. Engineer Hugo Stotz, who had sold his business to BBC, was given credit for creating DRP. Stotz's innovation served as a precursor to the current thermal-magnetic breakers still in use today in home load centres.

It was necessary to build circuit breakers with growing voltage ratings and enhanced capability to properly stop the increasing short-circuit currents generated by networks in order to link various generating sources into an electrical grid. Simple air-break manual switches that interrupted high voltages caused dangerous arcs; they were replaced by contacts that were encased in oil and other devices that used a directed flow of pressurised oil or air to cool and stop the arc. By 1935, the specifically designed circuit breakers employed at the Boulder Dam project were able to stop faults up to 2,500 MVA in three cycles of the AC power frequency using eight series breaks and pressurised oil flow. Operation While the functioning of all circuit breaker systems has certain commonalities, the specifics vary greatly depending on the voltage class, current rating, and circuit breaker type.

A fault state must first be found by the circuit breaker. Small mains and low voltage circuit breakers often carry out this function internally. Typically, electric current is used for its heating or magnetic properties. In order to detect a fault situation and activate the opening mechanism, protective relay pilot devices are often mounted on circuit breakers for big currents or high voltages. Although some high-voltage circuit breakers are self-contained with current transformers, protective relays, and an internal control power supply, they normally need a separate power source, such as a battery.

The contacts on a circuit breaker must separate whenever a fault is detected in order to interrupt the circuit; this is often accomplished by employing physically stored energy already within the breaker, such as a spring or compressed air to separate the contacts. Circuit breakers may

alternatively utilise a magnetic field or thermal expansion to separate the contacts using the greater current generated by the fault. Larger devices employ solenoids to trip the mechanism and electric motors to recharge the springs, while small circuit breakers often feature a manual control lever to turn off the load or reset a tripped breaker.

The contacts of the circuit breaker must be able to carry the load current without overheating, as well as endure the heat generated by the arc created when the circuit is interrupted (opened). Copper or copper alloys, silver alloys, and other highly conductive materials are used to make contacts. The corrosion of contact material caused by arcing when stopping the current limits, the service life of the contacts. Power circuit breakers and high-voltage circuit breakers have replacement contacts, however miniature and moulded-case circuit breakers are often destroyed after the contacts have deteriorated.

An arc is produced when a high current or voltage is interrupted. While the intensity (or heat) of the arc is often related to the current, the length of the arc is typically proportional to the voltage. So that the space between the contacts can once again sustain the voltage in the circuit, this arc has to be confined, cooled, and put out in a controlled manner. The medium in which the arc originates might be vacuum, air, insulating gas or oil depending on the kind of circuit breaker. The arc is put out through a variety of methods, including.

Interrupting an arc

Air alone is used by low-voltage micro circuit breakers (MCB) to put out the arc. Arc chutes, a stack of parallel, mutually insulated metal plates in these circuit breakers that split and cool the arc, are what they are named. The arc is cooled down as the arc voltage is raised and acts as an extra resistance, limiting the current via the circuit breaker, by breaking the arc into smaller arcs. Although magnetic blowout coils or permanent magnets might also deflect the arc into the arc chute (used on circuit breakers for higher ratings), the current-carrying elements close to the contacts make it simple for the arc to be deflected into the arc chutes by a magnetic force of a current route. The short-circuit rating and nominal voltage of the circuit breaker determine how many plates are in the arc chute.

Oil circuit breakers use the vaporisation of part of the oil in bigger ratings to shoot a jet of oil into the arc. Gas circuit breakers, which often include sulphur hexafluoride, may occasionally prolong the arc using a magnetic field before quenching it with sulphur hexafluoride (SF₆) due to its high dielectric strength. Vacuum circuit breakers have very little arcing (because there is just the contact material to ionise). When the arc is expanded only little (less than 2-3 mm (0.08-0.1 in)), it quenches. In contemporary medium-voltage switch gear up to 38,000 volts, vacuum circuit breakers are often employed.

Circuit Brief

Both the maximum short-circuits current that they can safely interrupt and the typical current that they are intended to carry are used to grade circuit breakers. The breaker's ampere interrupting capacity (AIC) is represented by the latter number. The anticipated or observed maximum projected short-circuit current under short-circuit circumstances may be several times the circuit's regular, rated current. Electrical contacts have a propensity to produce an arc between themselves when they open to stop a big current, which would let the current to continue. The arc may continue or lead to new short circuits under these conditions, which might cause the circuit breaker and the equipment it is mounted in to explode. These conditions can also produce

conductive ionised gases and molten or vaporised metal. Circuit breakers must thus have a variety of functions to split and put out the arc.

Testing is used to establish the maximum short-circuit current that a breaker can stop. A breaker may fail to safely interrupt a fault if it is applied to a circuit with a potential short-circuit current greater than the breaker's interrupting capacity rating. In the worst situation, the breaker could be able to stop the fault, only to blow up when reset.

Conventional current ratings

Circuit breakers are produced in conventional sizes and cover a variety of ratings using a system of preferred numbers. Since the trip setting on miniature circuit breakers is fixed, altering the working current value necessitates replacing the whole circuit breaker. Larger circuit breakers may feature customizable trip settings that enable the application of standardised components with a setting intended to increase protection. For instance, the over current detection on a circuit breaker with a 400 ampere "frame size" may be adjusted to only work at 300 amperes to safeguard a feeder wire.

CONCLUSION

Simple electrical theorems and formulas can be used to do short circuit current analysis. Methods that interpret the system at steady state are related to quasi-steady-state short circuit current evaluation. Voltages are presented using phasorvectors. For the purpose of developing and safeguarding power systems, it is crucial to comprehend the mathematics involved in computing short-circuit currents. In order to establish the necessary, short-circuit ratings for power distribution system components including bus transfer switches, variable speed drives, switchboards, load centres, and panel boards, fault current calculations are also needed. In general, short circuit current analysis is crucial for developing and safeguarding power systems. Basic electrical theorems and formulas can be used to do short circuit current analysis, and knowing the mathematics involved in computing short-circuit currents is crucial for designing and safeguarding power systems. To determine the available fault current or short circuit current at each point in the system, short circuit studies are used.

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EXPLORING TRANSMISSION LINES OVERHEAD LIGHT

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ABSTRACT:

One of the biggest dangers to the functioning of high voltage overhead transmission lines is lightning. Various lightning protection methods are used to enhance the lightning performance of overhead transmission cables. The main difficulty in selecting lightning protection measures is that it is challenging to quantify how these measures alter the lightning performance of the transmission lines. Insulator is shielded from an arc created by a lightning discharge using a parallel gap. This article examined the connection between the installation of insulators in parallel gaps and the lightning performance of transmission lines using data from a significant insulator parallel gap installation project. In this study, a technique for assessing the lightning performance of existing overhead transmission lines was first devised, and the approach was then applied to groups of transmission lines built with insulator parallel gaps. A comparison and analysis of the transmission lines' lightning performance before and after the installation of insulator parallel gaps is conducted.

KEYWORD: *Lightning Strikes, Lightning Density, Lightning Protection, Overhead Transmission.*

INTRODUCTION

If the consumer's power supply is to remain stable, power cables must be upgraded to be more resistant to the effects of lightning over voltage. Several environmental elements, most notably the intensity of the lightning, must be taken into account while determining the sizes of electrical cables. The "Electrical Installation Regulations" regulation sets down the current lightning effect limitations for power lines in Russia. It shows lightning density maps that were created more than 30 years ago using observations of genuine lightning and thunder. Accurate maps of lightning density and thunderstorm days have also been developed using the instrumental approach and have been used for a very long period in international practise. In addition to ground-based lightning detection devices CIGRE-500 and CGR3, the authors of make use of lightning data collected by NASA satellite-based equipment OTD and LIS. For the investigations, a network of direction finder-based lightning location and protection sensors was employed, which was under the management of. It was suggested, for instance, to measure the number of discharges each day in cells of 20 km, which approximately corresponds to the area of a typical rain and the field of view for hearing and seeing lightning and thunder in a person. Nevertheless, Russian academics are investigating lightning activity using contemporary methods. The Vaisala LS8000 network, located in the North Caucasus, keeps an eye on thunderstorms.

It is sometimes possible to predict how lightning may affect OHTLs by using a buffer zone or a corridor. The corridor normally has a width of a few hundred to a few thousand metres. For demonstration purposes, a map plot was created with a 9 km-long corridor on each side of the line. It implies that OHTL is no longer affected by lightning discharges beyond this range. The corridor width, which seems to be too wide for the lightning detecting system (LDS), is also shown to correspond with the LDS's data's margin of error. Additionally, it seems that the square cells that the built-in corridor uses are larger than 20 km by 20 km. During long-term lightning registration, a method for building an overhead line route lightning density map is presented. The accumulation of the necessary number of discharges (100-150) in the cell during a five-year observation period determines the size of the 5 km 5 km cells in the study zone. The lightning density in the OHTL zone is calculated using grid cells that cross the overhead line route and are located near to it at a distance of less than 1/5 of the grid cell side.

The flash incidence of specific power line sections and towers is not discussed in depth; instead, the projected impact on the power line is estimated based on the density of the strokes. For instance, despite the fact that the high voltage class overhead wires' transmission towers are typically just a few hundred metres apart, varied cell sizes ranging from 5 km to more than 20 km are used. Uncoordinated distances may also be used to compute the buffer distance. In order to identify areas that need particular management, electrical linemen employed by energy and utility companies need information on lightning strikes throughout the whole length of power lines. Because of this, it is currently difficult to gauge how much lightning affected OHTLs throughout their whole length.

Despite the importance of lightning density maps for estimating lightning incidence to power lines generally, we aim to develop a measure of the average annual lightning impact intensity along the entire length of the overhead line, taking into account the lightning discharges that actually occurred over a long period of time. To do this, the study combined the raw LDS data with the transmission tower coordinates. This study uses the Murmansk region of the Russian Federation as an example to show how easy it is to calculate the impact of lightning on overhead electricity wires over their whole length. Using this method, you can see how important the buffer zone is for estimating how much lightning will hit a power line throughout its whole length. The recommended method has been tested on 200 OHTLs on the Kola Peninsula in the Arctic Zone of the Russian Federation. In areas that are often damaged, the majority of overhead wires are located.

The phases listed below might be used to assess the lightning performance of an overhead wire. Using an incidence model to predict where the return stroke will occur, computing the overvoltage caused by each stroke depending on where it would occur, and calculating the flashover rate. Generating random numbers to produce the overhead line and lightning stroke characteristics at random. Utilising the approach requires taking into account its drawbacks and uncertainties; for instance, our knowledge of the lightning parameters is sometimes incomplete. These limitations might be somewhat alleviated by doing a parametric investigation that may highlight the characteristics for which accurate information is required. The objective of this paper is to investigate the shortcomings of the overhead transmission line model utilised in lightning simulations. This study offers a sensitivity analysis that looks for any possible effects on the flashover rate of the model and parameters used to simulate the key gearbox line components. The impacts of the tower, footing impedance, and insulator string models are examined. The document has the following structure.

Details about energy lines

The electric power companies in the Murmansk area spoke about the transmission lines. The data collection consists of 200 complete transmission lines with varied voltage classes. Some of these data will be provided in this research anonymously and without the required dereferencing since they include service information. We will be able to demonstrate how to determine the lightning intensity on electrical cables over their whole length even without this information. The method and of this study's processing setup were used to transmit real-time data on flash incidence to power lines above the ground and to replicate the conditions of the Kola power system.

The Process for Real Power Lines

In particular for power suppliers, it is critical to see the process on real overhead wires. Additionally, it's crucial to swiftly locate the electrical line segments that have been struck by lightning. Depending on the lightning density (least amount of lightning strikes), the approach may sometimes be beneficial for people picking the optimal route for electrical transmission lines. Before attempting to apply the approach to real nearby overhead wires, you must first assemble the basic data. Overhead line tower positions, lightning strike proximity, and the size of the power line buffer are a few examples. It is important to determine the buffer size if the coordinates are simple enough. For this investigation, the OHTLs buffer is chosen such that it is inside the LDN error limit. This inaccuracy may be estimated using the maximum deviation span (MDS) statistic for each flash.

Transmission cables are protected against lightning strikes by ground wires. There is a very high risk that the insulation will fail after a back flashover (BF) in places with strong ground resistance. Additionally, there is a potential that the shielding might fail and cause a flashover (SF). the lightning flashover rate (LFOR) of a transmission line (SFFOR) is identical to both the back flashover rate (BFR) and the flashover rate brought on by shielding failure. An incidence model is required to get both quantities in order to separate strokes to shield wires from those to phase conductors and those to ground. The following stages might be included in a Monte Carlo technique to evaluate lightning stress. Determining the site of impact of each lightning strike using an incidence model, figuring out the overvoltage that each hit produces based on the point of impact, and figuring out the flashover rate. Creating settings for the overhead line and randomly occurring lightning strikes using random numbers. This research estimates flashover rates for vertical and non-vertical strokes, and it evaluates lightning performance. The ground-breaking method was created in MATLAB and coupled with an EMTP/ATP sketch tool to enable immediate network simulations. Because accurate component modelling enables the collection of statistical data from networks, an insulator string is represented by a leader progression model, and a transmission tower by a multi-storey model.

Stroke parameter characteristics and statistical distribution. The methods for calculating lightning's impact, including both vertical and non-vertical strokes, are compiled in this page. The Monte Carlo method's essential components are described. There is a list of modelling requirements. To show the relationship between the flashover rate and different gearbox line characteristics and return stroke current components, we present and examine the simulation. This undertaking is over.

Reduce the earthling resistance of the tower to avoid back-flashovers. Poor soil and challenging terrain make it impossible to erect towers in certain areas. Another strategy for reducing back-

flashover is to use asymmetrical or superior line insulation. Nevertheless, this choice is uneconomical since it would need replacing the tower and new insulator discs. The most feasible and economical way to stop back-flashovers is to install Transmission Line Arresters (TLA) at certain tower locations. But in order to install TLAs, special cross arm arrangements or special conductor installation methods are also required. The main objective of this research is to investigate the feasibility of replacing conventional Insulator Strings with MCIA Strings.

The MCIA's basic design is known as the Multi Chamber System (MCS). Several electrodes are joined together over a length of silicon rubber to form the gadget. The holes that have been bored into the electrodes along their length produce tiny gas discharge chambers. When applied to the arrester, a lightning overvoltage impulse destroys the spaces between the electrodes. Electrode discharges are able to occur in very small chambers. The resulting extreme pressure pushes the electrode channels along the routes of spark discharge, raising their combined resistance, which lessens the lightning overvoltage impulsive current.

LITERATURE REVIEW

Yaqin Zhou et al.[1], explored that power facilities' safety depend on the identification of overhead transmission line corridors. An effective and autonomous UAV inspection system is needed due to the frequent and unpredictable changes in the transmission line corridor environment, as opposed to the current UAV-based inspection systems, which have certain issues with control model and ground clearance measurement. For starters, the manual control mechanism now in use runs the danger of colliding with power lines since it is difficult for manipulators to precisely gauge the distance between the UAV fuselage and power lines. Another issue is that it might be challenging to strike a balance between efficiency and accuracy when using ground clearing technologies based on UAV that often rely on LiDAR (Light Detection and Ranging) or single-view visual repeat scanning. In order to overcome the problematic challenges mentioned above, a unique UAV inspection system has been created. This system works in conjunction with a dual-view stereovision module and a powerful embedded NVIDIA platform to detect 3D information of transmission line corridors. A number of sophisticated algorithms are also included into the system to enable ground clearance measurement and autonomous UAV operation.

Choi et al.[2], discussed that with the development of autonomous or smart cars, the Internet of cars (IoV) is drawing the attention of several academics. Roadside vehicles are becoming into intelligent machines with a variety of sensors, as well as strong computer and networking capabilities. In the IoV setting, cost-effective traffic signal management may assist to increase the effectiveness of road transportation. The length of the vehicle line, or the number of cars waiting for the green light, is used by traffic signal controllers to manage traffic lights. The use of video cameras or sensors as an intelligent method of estimating the duration of the vehicle wait has been thoroughly investigated up to this point. However, it has drawbacks like high installation and maintenance costs, high susceptibility to the environment, and high computing overhead. We suggest in this work an economical, low-computing-overhead method for intelligent traffic signal management that is also highly resistant to environmental challenges. Using the IoV's built-in vehicular communication capabilities, traffic signals are effectively controlled in the vehicular communication-based approach without incurring any additional costs.

Bahtiar et al.[3], discussed that Corona effect is caused by the use of too high voltage in

electrical power transmission systems. Visible light radiation, hissing noise, ozone generation, and power losses are signs of a visual corona phenomena. The environment around the overhead line transmission and power losses in the line are both impacted by corona. This study uses a mathematical approach to examine the power and energy losses caused by corona. Relative air density values, disruptive critical voltages, power losses, and corona energy were calculated. The study item was transported from TanjungJati B Power Plant to Ungaran Substation via a 500kV extra high voltage overhead line transmission. According to the corona power losses are 0.25 to 0.27 kw/km (0.25 to 0.44 kW/mil) each phase, for a total of 0.78 to 0.81 k/w/km (0.25 to 1.30 kW/mil). Corona power losses on the line range from 107.57 to 112.08 kW. Corona energy losses on average were 2642.67 kWh. Corona power losses as a proportion of electrical power provided range from 0.005% to 0.011%.

Abdulrahman et al.[4], explored that technological and financial advantages over HVAC methods for long distance transmission, HVDC systems are becoming more and more important in the transfer of energy. For overhead point-to-point transmission projects and for the cable-based interconnection or grid integration of far-off offshore wind farms beyond 50–100 km, HVDC is preferred beyond 300-800 KM. There are a number of HVDC review articles in the literature, however they often concentrate on certain regions or system parts. In contrast, this study provides a thorough, current analysis and evaluation of HVDC transmission networks on a worldwide level, addressing both a specialist and lay readership.

Shadaram et al.[5], investigates a fibre optic-based fault detection sensor for radial and network overhead transmission power line systems. Power system faults are found and measured using the Bragg wavelength shift. Magnetostrictive materials experience strain of the magnetic fields produced by overhead transmission line currents, which is then detected using Fibre Bragg Grating (FBG). The signals are processed once the Bragg wavelength shift is determined and the Fibre Bragg interrogator detects the reflected FBG signals. In the control room, a broadband light source scans the change in the reflected signal. Any increase in the magnetic field causes a localised increase in fault current. Additionally, an artificial neural network (ANN) algorithm can precisely define the location of the fault. Combining this algorithm with other security measures is simple. It is shown that problems in overhead power lines in a measurable wavelength shift on the reflected signal of FBG, which may be utilised to identify and categorise various fault types. The suggested technique has undergone thorough simulation testing, and the findings show that it is capable of spotting various failure types in both radial and network systems.

Masato Yoshida et al.[6], explored that first on-line 256 QAM digital coherent optical transmission system using an FPGA-based transceiver, an ECLD light source, and DFB LD-based injection-locking. In this system, an optical injection-locking circuit and a phase-locked loop circuit at the receiver were used to precisely regulate the optical phase, which helped to simplify the digital signal processing in the FPGA-based receiver. Using a training symbol in the FPGA, a 256 QAM signal's accurate polarization-demultiplexing was accomplished. We successfully showed the on-line detection of a QAM signal with a multiplicity of up to 256 using these approaches. Then, using an FPGA-based transmission system, we present a high capacity next-generation mobile fronthaul consisting of a 10 channel WDM 80 Gbit/s/ch, 256 QAM bi-directional coherent transmission. With a 14% overhead FEC for 10 km down-link (on-line) and

up-link (off-line) transmissions for all channels, we were able to operate error-free.

Yang et al., explored that real-time rendering requires the depiction of translucent materials, which is a crucial component. The accuracy of the transmission thickness computation is essential for transmission rendering, which is often constrained by the complexity of scene models and lighting. The approach for calculating the transmission thickness in depicting transparent materials was suggested in this research and is based on virtual light. The scene was enhanced with a virtual light, and the depth information of the scene was sorted at the virtual light. It was suggested that samples be taken along a straight-line segment of the world space that connected the two points in order to estimate the transmission thickness from the actual light source to the shading point. The proportion of sampled points inside the object to the total number was then calculated, which was multiplied by the length of the straight-line segment to arrive at the estimation. Additionally, the sampling-based approach could reuse the scene depth data saved in the virtual light in the scenario of multiple real light sources in the scene. The suggested technique might significantly improve the computation of transmission thickness accuracy while lowering memory overhead brought on by an increase in the number of light sources. The suggested technique can successfully balance efficiency, efficacy, and memory overhead, according to experiments.

Ioannidis et al.[7], assessing the lightning performance of overhead transmission lines, a stochastic lightning attachment model is presented. The suggested model takes into consideration the branching and tortuous behaviour of the lightning discharge to take into account the stochastic character of lightning attachment. By using the Petrov and Waters model, it incorporates physical requirements for leader inception as well as leader discharge development, taking into account the conflicting interactions of many ascending leaders. To estimate the back flashover and shielding failure flashover rates of HVDC overhead lines, a generalised methodology combining stochastic modelling of lightning incidence with an electromagnetic transients (EMT) simulation model is proposed; an application to a monopolar -400 kV line sheds light on the fundamental factors that influence the lightning performance of HVDC lines. As opposed to what the deterministic lightning attachment models predicted, the chance of shielding failure is greater. For the design and assessment of the lightning performance of the future HVDC systems, it is important to take into account the stochastic character of lightning attachment and the impact of lightning peak current distribution.

Sadoff et al.[8], authors of this review paper outline opportunities and priority areas for electric utilities in developing and emerging economies to use Earth observation (EO) data in planning for rural electrification, evaluating renewable energy sources, deploying distributed generation, ensuring the reliability of the grid, and reducing disaster risk. The authors performed a thorough evaluation of primary and grey literature using a systematic approach. The numerous uses for EO data are reviewed in this paper, including the use of nighttime light imagery for estimates of rural electrification, NDVI products derived from EO for vegetation monitoring for overhead transmission line management, solar radiance data for planning renewable energy projects, and nowcasting for monitoring extreme weather events and other disasters. Through better management of renewable energy sources, disaster risk assessment in developing countries, and improved access to modern, dependable electricity, these and other applications can increase energy security and pave the way for more sustainable social and economic development. The usage of EO data by utilities in developing and emerging countries, as well as challenges and potential for the transmission of EO technology, are given as examples from the real world.

There are also suggestions for involving stakeholders, future EO training possibilities, and developing human capability.

DISCUSSION

To analyse lightning strikes on transmission lines, you may use Times New Roman or Times Roman fonts. Please use that font in place of Times if your word processor does not have it. Furthermore, it is suggested to use open type fonts. Please be careful to include math and other symbol fonts code. The notion of the whole wave process is used to quickly examine the lightning stroke process. In the meanwhile, attention is given to the real wave process of the transmission and transformation system, grounding device, and subsurface grounding system. The effectiveness of the line back strike is lit when striking the tower's peak directly. The eigenvalue and characteristic vector theories of matrices are applied. The wave process on multiple conductor lines with mutual electromagnetic contact is compressed into n mutually independent moduli, which are comparable to the wave process on a single conductor, using the matrix similarity transformation. For the tower, the simulation uses a multi-wave impedance model. A primary support and auxiliary supports are on each side of the tower. It is assumed that the distribution of each component is uniform. They calculate the wave impedance using their own geometry and dimension functions. Both the current source model and the bi-exponent pulse are applied to the lightning current model. The impedance size is 300.

Short Lines

Power lines that are less than 50 miles (80 km) long are referred to as short power lines. Homes and other low-demand power networks are often supplied with energy using these lines, which have a voltage flow of 11 to 33 Kv.

Medium Lines

Medium power lines are defined as those between 50 and 100 miles (80 and 160 km) in length and typically transmit between 66 and 132 Kv over their cables. Pi-Models and T-Models are two further categories that fall under this umbrella. A Pi-Model line has equal concentrations of capacitance (the capacity to hold electrical charge) at either end, but a T-Model line has more capacitance concentrated in the middle.

Long line

A long power line has a voltage capacity of 132 Kv or more and may go more than 100 miles (160 km). Only in these lines are the four performance-related variables (resistance, inductance, capacitance, and leakage conductance) distributed uniformly over the full length of the power line.

Transmission line shielding studies on failure

The leader progression model's fundamental tenet is that when light progresses downward, the field intensity of the ground and ground objects continuously increases. When the ascending and descending leads come into touch with the breakdown scenario, which happens when the field strength is enhanced to a certain degree on the ground objects, lightning strikes happen during relative development. The four model components head-on leader beginning criteria, upward leader model, and ultimate breakdown criterion have the largest impact on the calculation when a lightning leader model is employed to analyse the characteristics of line shielding failure. Since

the lightning channel is lowering, the direction in which it is expanding is somewhat unexpected. However, statistical principles demonstrate that a lightning channel always develops in the direction with the highest electric field. In lightning fractal modelling, the electric field is considered as the primary parameter for determining the growth direction of lightning. The lightning leader is thought to always grow in the direction of the transmission line's highest electric field breakdown, according to the article Lightning Strikes.

This Method of Tripping Out of Lightning Strikes' Calculation

Elements including line back-striking trip-out rate, shielding failure trip-out rate, line lightning stroke trip-out rate, line tower types, dielectric strength, ground resistance, as well as terrain and lightning activity along the line, have an influence on the performance of line lightning protection. The tower type, size, dielectric strength, topography, and grounding conditions are unique to each base tower. Each base tower has a different amount of lightning protection. In contrast, each base tower must do a time-consuming trip out rate evaluation on its own since there are so many towers in the real queue. Therefore, it is required to evaluate the overall effectiveness of the lightning protection for the lines using the helpful approach described below: The lines are split into a number of groups according to statistical criteria for all factors effecting the efficiency of line lightning protection. Based on the estimated line lightning stroke trip-out rate in the reach category, the weighted total methodology is utilised to determine the line's overall lightning protection effectiveness.

Reliable Power Grids

Power grid dependability is defined as a power system's capacity to reliably fulfil short-term system operation restrictions and measurements of power user load requirements while operating in real-time and in an outside environment. An objective reliability index is used to assess the dependability of the power generation and transmission systems. The indexes generally include PLC (Probability of Load Curtailments), EFLC (Expected Frequency of Load Curtailments), EDLC (Expected Duration of Load Curtailments), ADLC (Average Duration of Load Curtailments), ELC (Expected Load Curtailments), EENS (Expected Energy Not Supplied), BPII (Bulk Power Interruption Index), BPECI (Bulk Power Energy Curtailment Index) and SI (Severity Index), etc.

A common transmission line basic parameters for common line evaluation is given herein. In order to investigate and evaluate the lightning protection performance of the three typical lines, one 500 kV, one 220 kV, and one 110 kV line in Jinmen with more lightning strike trip out incidents per line are each chosen. The standard DL/T 620-1997, "Overvoltage protection and insulation coordination of AC electrical equipment," which specifies a typical value, should be followed when choosing the sag. Table I presents three examples of ground wire and phase conductor line specifications. The usual value of the line is used to determine the insulator parameters, and U50% is translated in accordance with standard DL/T 620-1997. Which tower models in each line either most precisely represent tower attributes or have the greatest percentage are determined. For 500 kV lines, single-circuit construction is used, and angled and straight-line cup types of towers are the most common. The study makes use of two standard tower constructions with the following measurements. For the construction of 110 kV lines, there are three alternative configurations: double-circuit, three-circuit, and four-circuit. There have been four-circuit straight line towers, three-circuit straight line towers with one base, and two-circuit angled towers among the ones used.

The Lightning Crest Current Distribution Impact Equation accounts for both the dispersion of the lightning crest current and the lightning attachment model to determine the projected SFR for an overhead electrical line. The literature reports on the statistical properties of various lightning crest current distributions. The distributions were derived from measurements made in the field in Austria and Japan, respectively. Since the two are seen as being comparable, adopting the recommends using distribution for SFR estimates. The effect of lightning peak current distributions on the SFR of conventional transmission lines was shown using an equation. The statistical model, the general Rizk model, and the Eriksson model are examples of electro geometric models. Both the overhead transmission line design and the lightning attachment model show that the SFR is much higher for lightning crest current distributions that are both low and big. This is more obvious for relatively low-height lines, and for higher lines, according to Eriksson's and general models as well as statistical and electro geometric models.

Poles

Power is moved across shorter distances using. They typically handle low-high voltage levels and are often used for distribution lines. Steel, concrete, and wood are the most often used materials for poles.

Wooden poles

Wooden poles are a cost-effective choice for carrying low-medium power levels and are often utilised to cover shorter distance spans. However, compared to their counterparts constructed of artificial materials, timber poles have a shorter lifespan and are far more susceptible to environmental factors.

RCC Concrete Poles:

Concrete poles are a great option for supporting buildings that need an additional boost of strength or resilience, such as those located in places with harsh climatic conditions, since they are low maintenance and have a greater loading capacity. Unfortunately, they are more costly and difficult to transport because to their heavier structure.

Steel Poles

Steel poles are often used in metropolitan areas because they are strong and provide a great degree of manufacturing flexibility, making them a desirable alternative suitable for a variety of different uses. Galvanised poles have a long lifespan, although they may still corrode and are expensive.

Steel towers

Steel towers are the preferred line supports for the transmission of greater power levels across wider stretches of land. Their construction gives strong resistance to the weather and a better quality of gearbox since they are massive steel structures with a high degree of mechanical strength.

Electrical conductors

For the purpose of facilitating the transfer of energy from one area to another, conductors are parts connected to power lines. They also contribute to increasing the electrical network's safety. AACs (all aluminium conductors), AAACs (all aluminium alloy conductors), ACARs (alloy reinforced aluminium conductors), and ACSRs (steel reinforced aluminium conductors)

are the four primary conductor types used in overhead lines. The most common conductors on current power lines are ACSR conductors and, to a lesser extent, AAACs. Since ACSRs and AACs are inexpensive and lightweight conductors with high capacitance, they are perfect for use in high voltage lines that need bundled or numerous conductors.

Insulators for power lines

Insulators limit the flow of electricity at certain locations within an electrical network. By strengthening the line and maintaining the conductors' separation, they are utilised on power lines to help ensure the safety and stability of the structure. Depending on how they are put, power line insulators may be divided roughly into two groups: pin insulators (installed above the line) and suspension insulators (installed to hang below the line). Modular (many units) suspension insulators are often used for higher-voltage lines to manage the greater amount of resistance needed. They can readily raise or lowered depending on the situation since they are made of a series of movable insulator discs [9], [10]

Earth Anchors for Power Lines

Heavy-duty engineering tools called earth anchors, commonly referred to as ground anchors, are used to strengthen and stabilise the poles or towers put in place to hold electrical lines. Earth anchors assist to safeguard the structural integrity of the lines against unfavourable or harsh weather conditions, as well as any ensuing natural or artificial changes to the local terrain. They are driven or corkscrewed into the nearby foundations.

CONCLUSION

According to the study's findings, overhead high-voltage alternating current (HVAC) transmission lines provide a good compromise from a financial and technical standpoint. Most likely, this technology will continue to be the primary method of electricity transmission. A power or national grid is formed by overhead power wires, which are used to carry and distribute electrical power across large distances. Electricity-carrying conductors are suspended from steel tower structures, pylons, or timber poles throughout a variety of operating voltages. Transmission line protection really serves the function of identifying flaws or unusual operating situations and launching repair action. Protective relays need to be able to assess a wide range of factors in order to choose the best course of remedial action undoubtedly, a relay cannot stop the issue.

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ANALYSIS OF RADIAL FORCES IMPACT ON TRANSFORMER

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ABSTRACT:

One of the main mechanical failure mechanisms in big power transformers is the axial instability of the winding conductor. It is brought on by electromagnetic forces that are produced by the electromagnetic interaction of the radial leakage flux and the short-circuit current. Under compression, there is a mechanical instability known as buckling. This work identifies and examines two potential mechanisms of failure in the layer type coil wrapped with the continuously transposed cable. The critical design loads that may cause instability in both the cable as a whole and in each of its individual strands are independently determined. The smaller of the two critical loads would be the coil's real instability threshold. This threshold must be higher than the highest compressive force on the cable under the worst-case short-circuit current for the through-fault integrity of the transformer design. This chapter provides analysis of radial forces impact on transformer.

KEYWORDS: *Distribution Transformer, Distribution System, Epoxy Bonded, Free Buckling, Hv Winding, Lv Winding.*

INTRODUCTION

Transformer is a static machine that is made with a sturdy design and extremely high efficiency. In India, distribution transformer failure rates are greater (12–17%) than in wealthy nations (2–3%). All of the country's distribution companies (Discoms) are worried about this high failure rate. The Discoms spend close to 200 crore Indian Rupees (INR) annually on distribution transformer maintenance and replacement. If the income lost due to supply disruption is also taken into account, the loss caused by the transformer failure becomes significant. The growing failure rate each year has made it a severe issue.

As electricity is produced at a maximum voltage of 11 KV at producing stations in India, distant from the load centers, the transformer's job starts at the generating station. The transmission losses of this electricity must be reduced by stepping it up to very high voltages. In order to provide users of various categories, such as home, commercial, etc. it is then stepped down to 66/11KV at substations for the main distribution network and further stepped down to 11KV/400V using distribution transformers for the secondary distribution system. Low tension (LT) three phase, four wire systems, distribution transformers, and 11KV feeders make up the distribution system. Therefore, the distribution transformer is a crucial part of the distribution system that must be extremely dependable and effective in order to give customers with an uninterrupted supply of electricity[1]–[3].

Failures of transformers cause loss not only in terms of the cost to repair or replace the failed

transformer, but also in terms of lost income for the utility as a consequence of customers not receiving electricity. The system's decreased dependability of the power supply's frequent failures is another significant drawback. The risk of failure is calculated as the sum of the consequences and the chance of failure. It's crucial to lower the failure rates in order to increase system dependability and lower the danger of failure. This calls for a thorough analysis of distribution transformer failures, which also necessitates the collecting of real-time field data on distribution transformer failure. Several international standards have been developed to take into account the aforementioned transformer failure risk.

In order to prevent future transformer failures in the distribution system and the significant financial losses they cause the Discoms, as well as to enhance the quality and dependability of the distribution system, this study examines the causes of transformer failure in the distribution system. The study is organized into six major sections: introduction, fundamental parts of a transformer prone to failure, causes of transformer failures, investigations into transformer failures, corrective actions, and conclusion.

Tensile tension is present on conductors in the outer winding that are being pulled outward. When below the withstand strength, this tensile stress does not alter the geometry of the winding; rather, the design parameters for short-circuit withstand strength relate exclusively to the mechanical characteristics of the conductor, such as its proof stress at 0.2% offset. The conductors stretch when the tensile stress exceeds the material proof stress, which may cause the insulation of damaged conductors to fail and the axial stability of the winding to collapse owing to a local bulge beyond the spacer contour.

DISCUSSION

Compressive stress is present on conductors in inner windings that are sensitive to inward pressures. When this stress surpasses acceptable levels, the conductors buckle or the geometry of the winding is altered, there are two different kinds of buckling: forced buckling and free buckling. If the compressive stress is greater than the conductor material's proof stress, forced buckling will occur, causing the conductors to bend inward between sticks. The same way a conductor between radial spacers bends axially, so does the collapse process. A significant factor is the quantity of sticks positioned around the inner perimeter of the winding.

Free buckling happens more often than forced buckling because it does so with significantly less radial force. The number of sticks positioned around a winding's inner diameter has no bearing on free buckling. Free buckling critical stress is mostly determined by tightness, starting eccentricity, and winding diameter, and conductor shape. The conductor's size, proof stress, and the bonding power of CTC or multi-wire conductors all have a significant role in the conductor's ability to withstand free buckling deformation. The windings must be totally self-supporting according to the design idea for the free buckling. Sometimes, in order to achieve self-support, it is necessary to lower the current density in the winding conductors more copper is required.

Spiraling

The "spiraling" failure mode, which is another form of failure mode brought on by radial (as well as axial) compressive pressures. It is a pattern of distortion that often occurs in helical windings. The possibility of spiraling is considerable when helical winding has a high pitch, such as when an electrical turn is made up of multiple cables stacked axially. The winding next to the major leakage flux channel, which has larger radial stresses than the inner winding, is where spiraling

is restricted when an LV winding has two physical helical windings, such as an LV winding of a big GSU. The stress limit to prevent spiraling in an epoxy-bonded CTC winding may be more important than the critical stress for buckling.

Tilting

Under strong axial stresses, the conductors lost their axial stability and began to tilt. In general, a winding is more likely to tilt if it has a thin conductor, a large diameter, and few strands arranged radially. Additionally, the radial spacer's coverage is important since a larger area offers a higher level of tilt resistance. In comparison to a conductor with a short corner radius, one with a big corner radius tilt more readily. Critical tilt strength is enhanced by a high conductor hardness degree, a notion that will be covered in more detail in the next section. The discussion up to this point has only been applicable to strand conductors like single, twin, or triple wires and CTC that is not epoxy-bonded. There are no tilt design restrictions for windings built of epoxy-bonded CTC since all strands are bound together to form a solid bar. In spite of the conductor hardness level, epoxy-bonded CTC exhibit extraordinarily high tilt resistance. Check the pressure being provided to the epoxy CTC winding in the oven. If the pressure is too great, the strands can tilt before the epoxy hardened, irreversibly deforming the cable.

An axial bend

Conductors are bent between spacers when subjected to strong axial stresses. In the part that follows, the bending stress will be covered.

Telescoping

An axial collapse of winding called telescoping. Because of the radial looseness brought on by stretched conductors, telescoping causes certain turns to be driven axially beyond neighboring turns.

Winding End Supports Collapse

If the end thrust stress exceeds the material's strength or the stability of the end insulation structure is poor, the end insulation structures between the yoke and the winding may be damaged. If the clamping pressure on the winding set is insufficient to maintain the conductors stable or if the end insulation structure is weak, axial forces may cause winding conductors to shift (vibrate). To stop this kind of vibration, it's crucial to have a strong clamping structure and a mechanically sturdy end insulating support system. The sturdy clamping structure has the capacity to both deflect axial forces and sustain constant pressure on the winding set for an extended period of time. As winding insulations, such as conductor paper and spacers, age and become brittle with the passage of time, less initial pressure is provided to the winding set, which causes the windings to become loose[4]–[6].

In such circumstances, the paper may be readily torn off by vibrations brought on by short-circuit pressures, resulting in electrical breakdown after a short-circuit incident and final failure. One alternative is to provide a strong initial clamping pressure in order to maintain the winding set under a certain pressure even after many years of use. Although the clamping pressure is believed to diminish with time, it is still believed to be sufficient to hold the windings tightly. High clamping pressure also raises the winding's inherent mechanical resonance frequencies. We won't go into great detail about other forms of winding lead, crossover, and transposition problems here.

The following factors may be taken into account for fundamental resilient design. Reduce short-circuit forces by changing the conductor's current density and winding heights and diameters. According to the preceding explanation, the forces are smaller the higher the winding. Other elements, such as impedance and unit shipment height, have an impact on the winding height. The short-circuit pressures may be decreased by reducing the current density, but the cost is increased due to the need for more material, larger overall sizes, and more labor.

Increase the conductor's proof stress. A conductor is more rigid against deformation during short-circuit occurrences when the proof stress is higher. Remember that a stiffer conductor will be harder to wind, thereby sacrificing the winding quality. CTC that is epoxy-bonded. With an equal cross-sectional area, a huge bar would have about the same stiffness as CTC thanks to epoxy. Epoxy-bonded CTC is advised and often used in big units because it enhances radial and axial strengths. The bonding power of the epoxy is essential to this enhancement. It has been discovered through experiments that there is no significant decay in the bonding strength from 100°C to 120°C provided that the epoxy curing process has been carried out properly 50% bonding strength at 120°C is typically accepted in the industry. Test from some manufacturers show that the bonding strength at 125°C is approximately 50% of the strength at 25°C. the tertiary winding-related increase in impedances. The tertiary winding may sometimes be the weak link in a big device, particularly an autotransformer, for both single-phase fault and three-phase fault. Impedances between HV and tertiary are increasing. Short-circuit currents and the associated stresses in all windings may be decreased by LV to tertiary. The impedances may be raised in two different ways. The first is to enlarge the whole core and coil assembly by extending the distances between the tertiary winding and other windings. The alternative approach is to raise the impedance by connecting the current limit reactor to the tertiary winding. It is worthwhile to evaluate the two ways for each particular design and choose the one that works best. The current limit reactor may sometimes be less costly than the first method.

Forces of Short-Circuit in Special Transformers

The neutral of an autotransformer is often well grounded, which allows for single phase-to-ground faults. Autotransformers often have lower impedances than two-winding devices. Greater short-circuit pressures in the autotransformer windings are a consequence of these two variables. It is important to do a detailed analysis of short-circuit forces during the design phase. In large GSU (generator step up) transformers, shipping height is frequently the determining factor for the height of the core and coil assembly. Although the core height can be decreased by using a five-leg core, it occasionally still falls short of the height requirement, so increasing winding height is not an option in this situation to reduce short-circuit forces. Additionally, raising the winding height is ineffective when relatively modest impedances are needed for big units for the same reason as before. To address this problem, the HV winding is divided into two pieces and positioned on each side of the LV winding (HLH). In actuality, this configuration greatly reduces impedance value. Radial split is another name for this configuration of winds.

The transformers used for auxiliary power supply in power plants can feature two sets of secondary winding with one main winding. On each side of the HV winding (LHL), there are two LV windings. It is possible to divide either an HV winding or an LV winding into two equal sections or into unequal halves with 30% and 70% as the extremes. The innermost and outermost windings are susceptible to compressive and tension forces, respectively, but the center winding is subject to far fewer radial forces. It is important to analyses the tension stress when the

outermost winding, such as a tap winding, has a thin radial build from having few turns. To avoid the winding burst, preventative measures like keyed-in sticks surrounding the windings outside surface should be adopted. A larger axial force is applied to the central winding due to increased radial flux components at its ends.

Another configuration with two LV and one HV winding has the HV winding divided into two halves and linked in parallel. In this configuration, the LV windings are stacked axially one on top of the other. It is known as an axial split. Short-circuit performance for axial split winding arrangements requires special attention. Because the impedances of HV2-LV1 or HV1-LV2 are not infinite despite being very high, there is still some current flowing through the HV winding portion facing the opened LV winding when one of the LV windings is short-circuited while the other LV is open. In this situation, the ampere-turn is not completely balanced, which might in more short-circuit pressures than typical. When both HV halves are linked, the same issue in additional eddy current loss on metallic components or circulating current.

Components of Transformers and Failure

The primary components of the distribution transformer are the magnetic circuit (Core, Yoke, and Clamp Structures), the electrical circuit (Windings and Insulation), the terminals, the bushings, the tank, the oil, the radiator, the conservator, and the breather. Any of the components listed below that are failure-prone may cause the transformer to malfunction.

Core

The transformer's core both conducts magnetic flux and gives it mechanical strength. DC magnetization or displacement of the core steel during the transformer's construction are the two main causes of core failure.

Winding

The transformer's windings' primary purpose is to convey current, and they are placed around the core limb as cylindrical shells, with each strand being covered in paper insulation. The windings must be able to endure mechanical forces that can induce winding displacement in addition to dielectric stress and temperature requirements. Such energies may manifest during lightning and short circuits. Most winding failures are caused by transient overvoltage or short circuit. The formation of a hot spot, the production of copper sludge, a low oil level in the transformer, or a mechanical flaw in the transformer's windings during construction are a few examples of causes for winding short circuits. Transient overvoltage in the LT system may be caused by lightning, improper transformer connections, or short circuits.

Tank

The tank physically protects the transformer core and windings and also acts as a receptacle for the cooling oil. It must be able to tolerate environmental pressures including solar rays, corrosive air, and high humidity. Oil leaks, severe corrosion, dents, and other indications of hard treatment are checked for in the tank. An oil-filled transformer's internal arcing may rapidly vaporize the surrounding oil, creating a high gas pressure within the transformer that can cause the tank to break.

Firm Insulation

For electrical isolation, press board and paper formed of cellulose are employed as solid

insulation between the windings. Long chains of glucose rings make up the structure of cellulose, which breaks down over time to form shorter chains. The average amount of these rings in the chain, or degree of polymerization (DP), serves as a proxy for the condition of the paper. DP 200 indicates that the paper has weak mechanical strength and may no longer survive short circuits and other mechanical stresses. New paper has DP between 1200-1400. The transformer insulation system's most vulnerable point is this sturdy insulation. Forces produced during short circuits or by the movement of the transformer may mechanically damage solid insulation. CuSO₄ production, hot spots produced by insufficient oil, or overloading of the transformer may all cause faults in insulating materials.

Transformer oil

Insulation between the windings and the appropriate cooling of the transformer are both provided by the transformer oil. Transformer oil is made of hydrocarbons including paraffin, naphthalene, and aromatic oils and is a highly refined product from mineral crude oil. There are two causes of cooling oil failure: either improper oil circulation or inadequate heat transfer to the secondary cooling circuit. The oil in the transformer becomes more viscous and the temperature in the second cooling circuit becomes too high. The main factor for oil contamination and the production of conducting particles is moisture and oxygen combined with heat. As a consequence, the temperature within the transformer will increase, and a short circuit will ensue from the oil insulation failing.

Bushings

To connect the transformer with the power system, bushings are used to remove the winding terminals from the tanks outside and cover them with electrical insulation. Sliding bushings and capacitance graded bushings are the two main kinds of bushings employed. A center conductor and insulation made of porcelain or epoxy surround the solid bushing. Short circuit is the primary bushing failure mode. It can be damage or insulating material flaws. Sabotage, shipment, or flying bits from other malfunctioning equipment may all cause harm. Damages, porcelain cracks, and faulty gaskets allow water to enter the bushing's insulation, which causes the bushing to fail.

Modes of Transformer Failure

It is usually difficult to identify a specific mode of failure for a transformer since it may fail due to a mix of electrical, mechanical, or thermal reasons. The majority of transformer failures are caused by insulation breakdown. Therefore, the transformer may experience electrical failure as a consequence of insulation failure brought on by mechanical, electrical, or thermal stress.

Electrical aspects

The following three categories may be used to classify the numerous electrical causes of transformer failures: Overvoltage or transient circumstances; surges from lightning and switches; partial discharge [7]–[10].

Mechanical elements

Damage to the transformer windings is caused by mechanical forces, which rupture the solid insulation. Acute damage may in an electrical failure of the transformer. Due to electromechanical forces or damage sustained during shipment, a transformer's winding may burst. The following list includes another potential cause of failure. Electromagnetic forces,

transformer shipping, buckling of the innermost winding, conductor tilting, conductor telescoping, spiral tightening, end ring crushing, malfunction of the coil clamping mechanism, and displacement of the transformer leads are all potential causes of failure.

Thermal Aspects

Due to heat production during typical transformer loads, the cellulose insulation of the transformer deteriorates with time. It causes the insulation's dielectric strength to diminish, weakening it to the point that it might burst under normal voltage levels. Other potential causes of failure are listed below. Long-term overloading of the transformer; use of nonlinear loads; failure of the cooling system; blockage of the oil ducts; operation of the transformer in an overexcited state; operation of the transformer in an environment with a high ambient temperature.

Report On Transformer Failure

Documentation, and analysis for power transformer and shunt reactors is used to do failure analysis on distribution transformers. It offers a method for doing failure analysis on transformers to determine the most likely reason for a transformer failure. No supply complaints from the affected region where the distribution transformer failed are often the starting point of a failure inquiry. When failure is proven, onsite investigation and testing are carried out to gather crucial site data. It is necessary to compile all previously recorded information about the transformer before beginning the failure inquiry. The failing transformer is examined from the outside and the inside, and then it is torn apart so that an investigation may be done to determine the reason for the failure of the transformer.

It is required to conduct a brief on-site assessment of a failing transformer to get the crucial information that could be lost during supply restoration. An on-site assessment includes a detailed evaluation of the transformer as well as a look at the surroundings of the failed transformer. External circumstances prior to beginning the visual examination of the surrounding circumstances around the transformer, arrive at the location and conduct an interview with any nearby residents about any anomalies they saw either during normal operation or at the time of a failure. Any strange noises, smells, debris ejected from the transformer or its accessories, foreign items in the region, any signs of vandalism, a load on the transformer, system issues, or any dead animals nearby must all be investigated.

Transformer circumstances

The following obvious abnormalities should be looked for by the investigator: bulging, cracks, leaks, signs of overheating, oil spills, or fire; oil levels in the main tank and conservator; damage to the radiators and conservator; damage to the bushings for leaks; broken porcelain; holes in the caps; and tracking. Conducting a diagnostic test on the transformer is the next step if no externally obvious damage is discovered.

Diagnostic Examination

When the transformer's outside inspection reveals no obvious damage. Then, diagnostic tests are performed to identify the problem and provide a repair recommendation. It is important to properly document test, and it is possible to identify a condition by combining the of many examinations. Before opening the transformer for examination, insulating oil samples must be collected for testing. The transformer may be put through the following testing.

Insulation Resistance

Dielectric absorption (Polarisation Index), core to ground, winding to winding, and winding to winding. Excitation (low voltage), Transformer Turn Ratio, Winding DC Resistance, Oil Dielectric Breakdown, and other tests. Safety measures should be taken to make sure the transformer has been properly earthed and unplugged from all power and auxiliary sources before conducting field testing. An interior examination is carried out on the spot to identify the location of the problem and the amount of the damage when the diagnostic test show that the transformer has failed. When removing transformer oil for inspection, the exposure period must be as short as possible to prevent moisture from entering the tank. Internal anomalies might consist of.

Error Analysis

Before drawing any conclusions about the causes of mechanical damage and electrical failure in service distribution transformers, the data from on-site and off-site collection must be carefully examined. Both events may be triggered by the energy from the power system. Therefore, while reporting cause and effect, caution must be given.

An analysis of winding mechanical failure

Understanding the axial and radial forces producing mechanical deformation to the winding is necessary to fully analyse distribution transformer failure. In contrast to shell type transformers, core type transformers have a distinct failure mechanism and force direction. Different further winding types have varying degrees of conductor moment resistance. The winding's reaction to electromagnetic forces is affected by the stiffness of the insulation system, the rigidity of the winding clamping system, the durability of the conductors, and the elasticity of the coil.

CONCLUSION

In this study, transformer failure modes are examined, and a PSPCL subdivision's distribution transformer failure is analysed. According to this examination, line surges and insulation failure are the main causes of transformers fail. Some other factors contributing to the failure of a large number of transformers include manufacturing flaws, overloading, poor maintenance, dampness, and oil contamination. There are certain transformers whose true cause of failure is unclear, but they are assumed to have failed due to problems with the quality of the power.

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INVESTIGATING THE SHORT CIRCUIT TEST TRANSFORMER

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ABSTRACT:

The short circuit testing transformer is the primary element of an On-line Short circuit facility. Such transformers are not regularly produced by any companies. Such transformers must be designed while taking into consideration a variety of parameters. It is crucial for the manufacturer to play a part in having the transformer created for a certain application. Before beginning production, it is crucial to carefully validate the design calculations for a variety of characteristics, including sufficient design margins for strong electromagnetic forces during short circuit. Such transformers are typically low impedance transformers, and short circuit testing them to confirm their design presents a number of challenges since a full-scale short circuit test involves unusually strong electromagnetic forces and might shorten the test transformer's lifespan.

KEYWORDS: *Applied Voltage, Circuit Test, Electric Motor, Induction Motor, Magnetic Field.*

INTRODUCTION

The transformer's low-voltage (LV) side, also known as the secondary, is short-circuited, thus the test is done on the high-voltage (HV) side of the transformer. The main side is linked to a wattmeter. The main winding is coupled to an ammeter in series. Since the applied voltage and the voltmeter reading are identical, a voltmeter is not necessary. The applied voltage is now gradually raised with the aid of a variance until the ammeter registers a reading equal to the rated current of the HV side. Voltmeter, Ammeter, and Wattmeter measurements are all recorded after the HV side's rated current has been reached. The major equivalent of full load current I_L is provided by the ammeter measurement. The iron losses in the transformer may be regarded as minimal in this case since the voltage supplied for full load current in the short circuit test on the transformer is fairly low compared to the rated primary voltage of the transformer[1]–[3].

The DC motors

Following Sturgeon's work, American inventors Thomas Davenport and Emily Davenport constructed a commentator-type direct-current electric motor, which he patented in 1837. The first commentator DC electric motor that could turn machinery was created by British scientist William Sturgeon in 1832. The motors were commercially unsuccessful and led to Davenport's bankruptcy because main battery power was so expensive. The motors could turn at speeds of up to 600 revolutions per minute and drove machine tools and a printing press. Innovators who came after Sturgeon in the development of DC motors had the same problems with battery expense. At the time, there was no commercial market for these motors since there was no electrical distribution system.

Moritz von Jacobi, a Prussian/Russian, built the first actual rotating electric motor in May 1834 after making several prior, more or less successful experiments with feeble rotating and reciprocating machinery. It produced mechanical output power that was astounding. In September 1838, Jacobi improved upon his first engine, which had established a new world record, and was now strong enough to move a boat carrying 14 passengers across a broad river. Other inventors were able to create motors with comparable and later superior performance in 1839/40 as well.

In 1855, Jedlik created a working device employing concepts related to those in his electromagnetic self-rotors. He also created a model electric car that year. Antonio Pacinotti's 1864 description of the ring armature originally intended for a DC generator, or dynamo marked a significant turning point. This included symmetrically-grouped coils closed upon themselves and connected to the bars of a commutator, whose brushes provided practically non-fluctuating current. The first commercially successful DC motors came after developments.

AC motor

By manually turning switches on and off, Walter Baily demonstrated the existence of rotating magnetic fields, or Arago's rotations, in 1879, effectively creating the first primitive induction motor. In the 1880s, many inventors tried to create functional AC motors because AC's advantages in long-distance high-voltage gearbox were outweighed by the inability to run motors on AC. Galileo Ferraris created the first alternating-current commutatorless induction motor in 1885. The Royal Academy of Science of Turin published Ferraris's research describing the fundamentals of motor operation in 1888, but came to the conclusion at the time that "the apparatus based on that principle could not be of any commercial importance as motor. Ferraris was able to improve his first design by creating more sophisticated setups in 1886.

Nikola Tesla, who independently created his induction motor in 1887 and received a patent in May 1888, foresaw potential industrial progress. Tesla presented his paper A New System of Alternate Current Motors and Transformers to the AIEE that same year. It described three patented two-phase four-stator-pole motor types: one with a four-pole rotor forming a non-self-starting reluctance motor, another with a wound rotor forming a self-starting induction motor, and the third with a true synchronous motor and separately excited DC supply to rotor winding. However, an induction motor with a shorted-winding-rotor was also mentioned in one of Tesla's 1887 patent applications. George Westinghouse, who had previously purchased Ferraris' rights for US\$1,000, quickly purchased Tesla's patents for US\$60,000 plus US\$2.50 for each sold horsepower, paid until 1897, hired Tesla to create his motors, and delegated C.F. Scott to assist Tesla, but in 1889 Tesla departed for other endeavours. The constant speed AC induction motor was discovered to be unsuitable for street cars, but Westinghouse engineers successfully modified it to power a mining operation in Telluride, Colorado in 1891. Westinghouse developed a line of polyphase 60 hertz induction motors in 1893, but these early Westinghouse motors were two-phase motors with wound rotors. In 1892, the company achieved its first practical induction motor.

Powerful tests

With very little power given to the transformer and winding currents of the same size as during operation, a short-circuit test is performed to determine the transformer impedance and losses. To evaluate the mechanical strength of the transformer windings and their capacity to resist the

strong forces created if an energised transformer encounters a short-circuit defect, a new kind of short-circuit testing is carried out. The rated current during such situations may be many times higher. The stresses may cause internal connection breaks or winding distortion. High-power test labs have the equipment to apply the very high-power levels typical of a failure on an interconnected grid system for big utility-scale power transformers.

Test for Open Circuits on a Transformer

The image displays the connecting diagram for the transformer's open circuit test. The transformer's LV side has voltmeters, wattmeter, and ammeters connected as depicted. With the aid of an auto transformer with a variable ratio, the voltage at the specified frequency is applied to that LV side. The transformer's HV side is left exposed. The applied voltage is now gradually raised with the aid of a VARIAC until the voltmeter registers a reading equal to the rated voltage of the LV side. We record the data from all three instruments (the Voltmeter, Ammeter, and Wattmeter) once the LV side voltage reaches the specified level.

The no load current I_e is determined from the ammeter value. The voltage dips caused by this current might be considered insignificant since the no load current I_e is fairly little in comparison to the transformer's rated current. Wattmeter reading V_1 reflects the input power used during the test, and V_1 may be equated to the secondary induced voltage of the transformer. The input power in this case is made up of core losses in the transformer and copper losses in the transformer when there is no load since the transformer is open circuited and has no output. However, as was previously stated, the transformer's no-load current is quite low compared to its full load current, so we may disregard the copper loss caused by the no-load current. We may thus assume that the wattmeter value is equivalent to the transformer core losses.

Test for short circuits on a transformer

The image below displays the connecting diagram for the transformer's short circuit test. The HV side of the transformer has voltmeters, wattmeter, and ammeters connected as illustrated. A varies, or variable ratio auto transformer, is used to provide a low voltage of around 5–10% to that HV side. The transformer's LV side has shorted out. Now, applied voltage is gradually raised with the aid of a varies unit until the wattmeter and an ammeter provide readings equal to the rated current of the HV side. We record the readings from the three instruments (the voltage, amperage, and watt metres) after the HV sides rated current has been reached. The major equivalent of full load current I_L is provided by the ammeter measurement. The transformer's core losses may be assumed to be insignificant in this case since the voltage supplied for full load current during a short circuit test on the transformer is fairly low compared to the main voltage for the transformer.

Say the voltmeter shows a reading of V_{sc} . The input power used for the test is shown by the watt-meter value. Since there is no output since we short-circuited the transformer, the input power here is made up of copper losses in the transformer. We may disregard the core loss because of the modest applied voltage as the applied voltage V_{sc} is short circuit voltage in the transformer and is thus relatively low compared to the rated voltage. We may thus assume that the wattmeter value is equivalent to the copper losses in the transformer [4]–[6].

LITERATURE REVIEW

GönülSakallet al. in, explored that due to their benefits over other motor types, asynchronous motors are often favoured in industrial applications. Transformers are another frequently used category for adjusting the voltage that will be provided to an electrical system. When it comes to the unavoidable use of this equipment, the fault diagnostics are often satisfied by comprehensive analyses of stator current signals, magnetic flux patterns, etc., which call for standard electrical measurements. Here, thermal image analyses become a convenient method for determining electrical equipment situations where no direct intervention with the structure is required. In this article, we deal with the use of thermal image-based studies to differentiate between asynchronous motor and transformer scenarios. Effective deep learning architectures without a pre-processing phase are needed for this.

ShaoyuXieet al. in, describes a method based on genetic algorithms for parameter estimation of the MIT-proposed top oil temperature nonlinear model in power transformers used in on-line diagnosis and monitoring systems. The method has been installed since 2003 in a 100 MVA 230/115/24 kV OA/FA/FOA power transformer at the Substation Barquisimeto ENELBAR in Venezuela. The parameter estimate using evolutionary algorithms, parameter estimation using least-squares, and top oil temperature measurements are contrasted. These findings are explored, and the authors suggested this model as a useful tool for power transformer diagnostics.

Faizet al. in, explored that the transformer neural network (TNN) is used in this study to present a new deep learning (DL) based inter-turn short circuit fault (ISCF) severity detection technique. The outputs are the number of shorted turns and short circuit (SC) current amplitude, while the input characteristics are the currents in alpha-beta reference frame. The fault severity may be fully assessed using this approach, which solely monitors the stator currents. The multi-head attention (MHA) mechanism is used by the proposed TNN to generate various representations of the input. This enables the network to concentrate on certain input signal components and provide an accurate approximation. A motor with re-wound windings was used to imitate the stator ISCF and was used to gather the data. It was run under nine different load and speed settings as well as three different numbers of shorted turns. On the test dataset, the shorted turns and SC current amplitude estimations both have accuracy levels higher. On the basis of several criteria, a comparison of numerous approaches is offered. The suggested technique has excellent potential in terms of comprehensiveness, accuracy, practicability, and cost based on comparison and taking the acquired accuracy into consideration.

Shafik et al. in, explored that for safety-critical applications that need extensive fault tolerance capabilities and improved system dependability, multiphase machines have evolved into difficult options. However, the power converters that have been used become more complex. Electric motor power is often provided via a three-phase low voltage variable frequency drive system (VFD), followed by a step-up transformer and a medium voltage long feeder, in applications like electrical submersible pump (ESP) systems. Recent research suggests that using multiphase machines in these situations may be advantageous, but doing so requires both a multiphase transformer and a more sophisticated multiphase power converter. As an alternative, stepping up the three-phase output of a typical off-the-shelf three-phase inverter and converting it into n-phase secondary voltages is a workable and more cost-effective approach.

Amin Saadatet al. in , explored that disturbances in power quality may harm the users of the electrical network. power quality is increasingly seen as a crucial problem in distribution

networks. Voltage sag is one of the most important power quality issues in this respect. Finding the source of the disturbance is the first step in minimising the harm caused by voltage sag. Furthermore, the inefficiency of the earlier voltage sag source location (VSSL) approaches was brought about by recent attention to distributed generation (DG), particularly in distribution networks. In this paper, a novel approach based on voltage and current measurement data is put forward, in which a voltage sag cause is identified using cosine similarity (CS). In the suggested technique, the relative position of the voltage sag source is determined by comparing the CS sign between two data sets. The IEEE 33 bus test network presents the simulation for several situations. This allows for the simulation study of a number of concerns, such as VSSL, voltage sag original type (symmetric/asymmetric short-circuits or motor starting), fault resistance, grid line x/r ratio, DG size, DG position, measurements error, and current transformer saturation. The performance of the suggested strategy for finding the cause of voltage sag is supported by the simulation. Furthermore, a comparison with some earlier approaches reveals that the suggested approach provides a better response in locating the voltage sags.

Wang et al. in, describes a method based on genetic algorithms for parameter estimation of the MIT-proposed top oil temperature nonlinear model in power transformers used in on-line diagnosis and monitoring systems. The method has been installed since 2003 in a 100 MVA 230/115/24 kV OA/FA/FOA power transformer at the Substation Barquisimeto ENELBAR in Venezuela. The of parameter estimate using evolutionary algorithms, parameter estimation using least-squares, and top oil temperature measurements are contrasted. These findings are explored, and the authors suggested this model as a useful tool for power transformer diagnostics.

W. H. Kersting et al. in, explored that a typical load on a distribution feeder comprises of a three-phase induction motor and a single-phase lighting load. A wye-delta transformer bank is capable of supplying this combo load. The issue is whether the wye connection should be left unground, linked to ground directly via a grounding resistor, or unconnected at all. Each connection has pros and cons under typical loading circumstances. A grounded wye-delta bank will, however, provide a 'backfeed' short-circuit current for an upstream ground fault in a short-circuit situation. The methodologies for analysing the backfeed currents for an upstream line-to-ground fault will be developed in this study.

Pagano et al. in, discussed that using ETAP software, a short circuit study of the IEEE 14-bus system has been done. For the purpose of determining the ratings of protective devices, the Maximum short circuit currents and the Minimum short circuit currents also known as Sub-Transient and Steady state fault currents are utilised. The maximum and minimum short circuit currents for three-phase and single line to ground faults applied at different buses in the IEEE 14-Bus system are determined using the ETAP programme [7]–[10].

DISCUSSION

The rotor, which moves, and the stator, which does not, are the two mechanical components of an electric motor. Additionally, it has two electrical components: an armature and a pair of magnets, one of which is fastened to the stator and the other to the rotor, producing a magnetic circuit.

Field magnets

A magnetic field produced by the magnets travels through the armature. These may be either permanent magnets or electromagnets. Normally, the armature is on the rotor and the field

magnet is on the stator, however in certain kinds of motors, the positions are reversed.

Bearings

By transmitting axial and radial stresses from the shaft to the motor housing over a contact with a low coefficient of friction, bearings support the rotor and enable it to rotate on its axis.

Rotor

The rotating component that generates mechanical power is called a rotor. The magnetic field of the stator puts stress on conductors that carry currents that are normally held in the rotor, turning the shaft. A few rotors, as an alternative, are equipped with permanent magnets, and the stator houses the conductors. High efficiency is available from permanent magnets across a wider range of operating speed and power. It may rotate because of an air gap between the stator and rotor. The electrical properties of the motor are greatly impacted by the gap's width. Generally speaking, it is kept as narrow as possible since a wide gap degrades performance. The low power factor at which motors run is mostly caused by this. Narrow gaps are preferable since they reduce the power factor while increasing the magnetising current. Conversely, in addition to noise and losses, gaps that are too tiny may cause mechanical issues. The load is applied to the motors outside through the motor shaft, which extends via the bearings. The load is referred to as being overhung when its forces extend beyond the farthest bearing.

Stator

The stator, which encloses the rotor, often contains field magnets, such as permanent magnets or electromagnets made of wire wound around ferromagnetic iron cores. These produce a magnetic field that travels through the rotor armature and pulls the windings in one direction. The laminations, or several thin metal sheets that are separated from one another by insulation, make up the stator core. Electrical steel, which has a predetermined magnetic permeability, hysteresis, and saturation, is used to create these laminations. When a solid core is employed, laminations are used to cut down on losses brought on by induced circulation eddy currents. The wires within the windings of mains powered AC motors are often immobilised by varnish impregnating them in a hoover. This stops the winding's wires from vibrating against one another, which would wear out the insulation on the wires and cause them to break sooner. Deep well submersible pumps, washing machines, and air conditioners all employ resin-packed motors, which encase the stator in plastic resin to stop corrosion and/or lessen conducted noise.

Armature

On a ferromagnetic core, wire windings make up the armature. The rotor is turned by the magnetic field of the field magnet acting on the wire while an electric current flows through it, producing a mechanical output (Lorentz force). When wires are energised with electricity, they are often wound around a laminated, soft, iron, ferromagnetic core to create windings, which produce magnetic poles. There are salient- and no salient-pole arrangements for electric devices. In a salient-pole motor, the ferromagnetic cores of the rotor and stator have projections called poles facing one another. A wire is wound around each pole below the pole face, and as current runs through the wire, the poles transform into the north and south poles of the magnetic field, respectively. The ferromagnetic core of a no salient-pole (or distributed field or round-rotor) motor is a smooth cylinder, and the windings are uniformly dispersed in slots around the circle. A shaded-pole motor features a winding around portion of the pole that delays the phase of the

magnetic field for that pole. This in poles in the core that revolve continuously when alternating current is supplied to the windings.

Commentator

An electrical rotary switch known as a commentator powers the rotor. As the shaft turns, it occasionally reverses the direction of current in the rotor windings. It is made up of an armature-mounted cylinder with several metal contact segments. A commentator is pressed against by two or more electrical contacts, known as "brushes," consisting of a soft conductive substance like carbon. As the commentator spins, the brushes make sliding contact with the following segments, giving current to the rotor. The segments of the commentator are coupled to the windings on the rotor. To ensure that the torque applied to the rotor is always in the same direction, the commentator periodically reverses the current direction in the rotor windings with each half turn (180°). Without this current reversal, the direction of torque on each rotor winding would reverse with each half turn, causing the rotor to stop. Commutated motors have been mostly supplanted by brushless direct current motors, permanent magnet motors, and induction motors because commentators are wasteful.

Transformers Have A KVA Rating

It is clear from the aforementioned transformer experiments that a transformer's Cu loss relies on current and its iron loss depends on voltage. Volt-ampere (VA) is hence a factor in overall transformer loss. It is independent of load power factor and does not rely on the phase angle between voltage and current. Transformers are rated in kVA for this reason.

Short circuit test

Copper losses are measured using a short circuit test, while core losses are measured using an open circuit test. The high voltage side is open circuited while the low voltage side undergoes an open circuit test.

Test for short circuit current

Tests for output short circuit current replicate the worst possible loading scenarios for a digital device's output pin. These tests may be performed on a variety of devices, including fully integrated consumer electronics products and digital semiconductor chips.

Rotor blockage test

An induction motor is subjected to a blocked rotor test. It is also referred to as the "short-circuit test" the "locked rotor test," or the "stalled torque test." From this test, the starting torque of the motor, the short-circuit current at normal voltage, the power factor on the short circuit, and the total leakage reactance can all be determined. The starting torque of a motor is crucial to know because if it is insufficient to overcome the initial resistance of the intended load, it will remain stationary while consuming an excessive amount of current and overheating quickly. The test can be performed at a lower voltage because at the standard voltage, the current flowing through the windings would be high enough to cause them to overheat and become damaged. The blocked rotor torque test is less significant on wound-rotor motors because the starting torque can be varied as desired, though it may still be used to characterise the motor. The test can still be performed at full voltage if it is brief enough to avoid overheating the windings or overloading the starting circuits.

The rotor is sufficiently locked during the blocked rotor test so that it cannot escape. At that moment, the current, voltage, and power input are measured. A low voltage is given to the stator terminals so that the stator winding is fully loaded. The IEEE recommends conducting the test at the rated frequency while the rotor is stationary since the rotor's effective resistance at other frequencies might vary. To make sure they are consistent, the test may be run again with various voltage levels. The test should be completed promptly since the current flowing through the stator may be more than the rated current. The motor circle diagram may be created by using the characteristics discovered by this test.

Electric drive

An electrical device that transforms electrical energy into mechanical energy is an electric motor. The majority of electric motors work by creating force in the form of torque imparted to the motor shaft via the interplay of the magnetic field of the motor and electric current in a wire winding. Although an electric generator and an electric motor are technically equivalent, an electric generator uses a reversed power flow to transform mechanical energy into electrical energy. Electric motors may be powered by alternating current (AC) sources like a power grid, inverters, or electrical generators or by direct current (DC) sources like batteries or rectifiers.

Considerations including the kind of power source, construction, application, and type of motion output may be used to categorise electric motors. They may be AC or DC driven, brushed or brushless, single-phase, two-phase, or three-phase, axial or radial flux, air-cooled or liquid-cooled, and can use any kind of cooling system. For industrial application, standardised motors provide practical mechanical power. The biggest have an output more than 100 megawatts and are used for pumped storage, pipeline compression, and ship propulsion. Industrial fans, blowers, and pumps, machine tools, home appliances, power tools, automobiles, and disc drives are just a few examples of the applications. Electric watches may have small motors. Electric motors may be used in reverse as generators to recover energy that could otherwise be wasted as heat and friction in certain situations, such as regenerative braking with traction motors. Electric motors generate torque, which is a rotational or linear force used to move a lift or other external device. The typical purpose of an electric motor is continuous rotation or linear motion over a large distance in relation to its size. While magnetic solenoids are likewise transducers that transform electrical power into mechanical motion, they have a restricted range of motion.

Control of motors

Power source

As previously mentioned, a split ring commutator is often used to supply a DC motor. A slip ring commutator or external commutation may be used to commutate AC motors. It may have synchronous or asynchronous control, fixed-speed or variable-speed control, or both. Both AC and DC may be used to power universal motors.

Motor management

By changing the voltage delivered to the terminals or by employing pulse-width modulation (PWM), DC motors may be run at different speeds. In most cases, the grid or motor soft starts are used to power AC motors running at a set speed. Different power inverter, variable-frequency drive, or electronic commutator technologies are used to power AC motors that are run at varying speeds.

Electric motor

An induction motor, also known as an asynchronous motor, is an AC electric motor in which the electric current in the rotor required to produce torque is obtained through electromagnetic induction from the magnetic field of the stator winding. An induction motor can be constructed without electrical connections to the rotor. Industrial drives often employ three-phase squirrel-cage induction motors because they are inexpensive, dependable, and self-starting. Smaller loads, such as trash disposals and stationary power tools, often employ single-phase induction motors. Single- and three-phase induction motors are increasingly used in variable-speed applications employing variable-frequency drives (VFD), despite historically exclusively being utilised for one-speed operation. Induction motors used in applications like fans, pumps, and compressors that have variable loads benefit greatly from the energy savings potential provided by VFDs.

CONCLUSION

Therefore, a transformer's short-circuit test is used to calculate the copper losses in the transformer when it is fully loaded. It is also used to determine the parameters for a rough equivalent transformer circuit. Copper losses are measured using a short circuit test, while core losses are measured using an open circuit test. The high voltage side is open circuited while the low voltage side undergoes an open circuit test. To ascertain the series branch parameters of a transformer's equivalent circuit, short circuit tests are conducted on transformers. The transformer's low-voltage (LV) side, also known as the secondary, is short-circuited, thus the test is done on the high-voltage (HV) side of the transformer. The goal of the test is to establish the copper loss at full load, which is used to calculate the transformer's efficiency. The short circuit test can determine the equivalent resistance, impedance, and leakage reactance. The high voltage winding of the transformer is connected to measuring devices like wattmeters, voltmeters, and ammeters. The applied voltage is gradually increased until the ammeter reads the HV side's rated current. The secondary or high voltage transformer winding is used for the short circuit test.

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SELECTION AND SIZING OF LT/HT CIRCUIT BREAKER

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ABSTRACT:

Testing techniques are provided for all high-voltage circuit breakers with voltage ratings exceeding 1000 V AC, including both indoor and outdoor versions with the desired specifications indicated. These standards typically apply to circuit breakers with maximum voltage ratings of 4.76 kV to 800 kV and continuous current ratings of 600 A to 5000 A related to the different maximum voltage ratings. The testing techniques confirm all prescribed ratings, including continuous current, dielectric withstand voltages, short-circuit current, transient recovery voltage, and capacitor switching, as well as related characteristics including mechanical endurance, load current, and out-of-phase switching. Generator circuit breakers are covered by hence they are not covered by this standard Understanding the graphics requires the use of colour.

KEYWORDS: *Circuit Breaker, Short Circuit, Lt/Ht Circuit, Air Circuit Breakers.*

INTRODUCTION

By switching, controlling, and protecting the electrical circuits, switchgear plays a key role in the functioning of a power system. The circuit breaker is one of the switchgear devices that they have. An electric system, such as those found in power plants, transmission and distribution lines, distributors, lighting circuits, etc., has to be protected, and that is the main function of a circuit breaker. An electrical device known as a "Circuit Breaker" has the ability to protect the circuit in the case of a failure and to remedy the fault condition. Power system protection includes a number of circuit breaker types. Based largely on the arc extinction or quenching medium, it is divided into five main parts. A vacuum circuit interrupter, an oil circuit breaker, a sulphur hexafluoride circuit breaker, and an air blast circuit breaker. For arc extinction, circuit breakers use compressed air, oil, sulphur hexafluoride gas or air[1]–[3].

Air circuit breaker

Air circuit breakers (ACBs) have low- and medium-voltage safety features built for them. Compressed air or gas is used as the circuit-breaking medium using an air circuit breaker. This circuit breaker is used in motor circuits, distribution systems, and lighting systems. It may be used to power AC or DC circuits for indoor applications. Air circuit breaker show in figure 1.



Figure 1 Air circuit breaker [ElectricalTechnology].

Circuit Breaker for Air Blast

The air-blast circuit breaker is necessary to stop current at high-pressure or high-voltage installations. This circuit breaker uses high pressure (or other gases like hydrogen, nitrogen, and carbon dioxide) as the arc quenching medium. Along the arc path, the air blast circuit breaker is separated into three groups. There are also axial and cross air-blast circuit breakers. In industrial settings, radial air blast circuit breakers are primarily used for primary power transmission and distribution. Circuit breaker for air blast

Oil Circuit Breaker

Oil circuit breakers use insulating fluids (like transformer oil) as the arc quenching medium. It is the most conventional kind of circuit breaker and has several benefits, such as excellent reliability, an easy-to-understand design, and an affordable price. Typically, this circuit breaker may be split into two halves. Simple break oil circuit breakers, self-generated pressure oil breakers, impulse oil breakers, bulk oil breakers (BOCB), and circuit breakers for low oil (MOCB) are all examples of oil circuit breakers.

An interrupter vacuum circuit

The vacuum circuit breaker (VCB) is structurally simpler than air and oil circuit breakers. In this circuit breaker, vacuum offers a good insulating strength between 10⁻⁷ and 10⁻⁵ torr. Two categories may be used to categorise the structure. There are two types of vacuum circuit breakers: permanent and mobile. VCB is used for medium-voltage ratings (such 11KV and 33KV). Substations often employ it to guard against overload or excessive current. Additionally, it is used in the switching of reactors, capacitor banks, transformers, etc.

Sulphur Hexafluoride Circuit Breaker

Sulphur hexafluoride (SF₆) gas is used as an arc quenching medium instead of oil, air, or a vacuum. It supports high and extra-high voltage. The three different types of SF₆ circuit breakers are often divided according to how they work. Single puffer piston, double puffer piston, and non-puffer piston variants of circuit breakers are available. The SF₆ circuit breaker is often used in power plants, transmission and distribution networks, electrical grids, and other infrastructure. These high voltage sulphur hexafluoride circuit breakers safeguard and regulate the electrical power transmission networks.

LITERATURE REVIEW

Valencia-Velasquez et al., explored that the circuit breakers (CBs) employed in direct current microgrids (DCMGs) for protection against electrical failures are the subject of this study, which focuses on their development and upcoming difficulties in the low voltage (less than 1.5 kV) and medium voltage (between 1.5 kV and 20 kV) ranges. New circuitbreaker feature proposals have increased over the past few years. Therefore, it is crucial to review the development of DCMG circuit breakers. The history of circuit breakers used in DCMGs is reviewed in general in this study, with a particular emphasis on fuses, mechanical circuit breakers (MCBs), solid-state circuit breakers (SSCBs), and hybrid circuit breakers (HCBs). Their development is shown, with each device's benefits and drawbacks highlighted. It was discovered that although some contemporary circuit breakers have entered the market, many of them are still in the development stage. Certain conventional fuses and MCBs are still often used in DCMGs, albeit with some limits or limitations. Future difficulties that might prevent the proper and effective integration of circuit breakers in DCMGs are also discussed.

Rostan Rodrigues et al. in, explored that new power distribution technologies and architectures, such as DC microgrids, call for improved interruption performance characteristics. Conventional electromechanical circuit breakers have a history of being effective and dependable devices for circuit protection. Research and development in the field of solid-state circuit breakers has increased of the need for quicker switching operation and the most recent advancements in sophisticated power semiconductor technologies. This article offers a thorough analysis of the numerous solid-state circuit breaker technologies that have recently been published in the literature. First, we group solid-state circuit breakers into different groups based on important characteristics and components, such as power semiconductor devices, primary circuit topologies, voltage clamping techniques, gate drivers, fault detection techniques, and commutation techniques for power semiconductor devices. Second, we go through the many difficulties involved in designing solid-state circuit breakers from the standpoint of general applications. Finally, we compare several solid-state breaker technologies based on important parameters. Finally, for a variety of new power distribution applications, we provide a helpful framework and point of reference for future solid-state circuit breaker development[4]–[6].

Jiawen Xiet al. in, discussed that due to their superior system operational performance and high power quality, MVDC systems have attracted a lot of attention for the integration of renewable energy and electrification of transportation. In comparison to mechanical equivalents, DC circuit breakers provide quick protection from fault circumstances, making them crucial for the development of MVDC systems. However, unlike AC systems, DC systems do not experience a zero-crossing of the current, which makes the design of DC circuit breakers more difficult. In order to boost the voltage and current ratings, a solid-state DC circuit breaker (SSCB) is designed in detail in this work employing series and parallel topologies of IGBTs. The SSCB's functioning, electrical design, and thermal design are discussed. For the purpose of simulating SSCB functioning, a PLECS model is created. The construction and experimental testing of a 1 kV SSCB prototype in both static and dynamic situations. In the testing tests, the prototype exhibits equal current sharing and voltage balancing. The prototype successfully interrupts 1 kA DC current and can sustain 150 A of current without overheating.

Mike Barnes et al. in, explored that as commercial multi-terminal high voltage DC (HVDC)

transmission becomes a reality, HVDC circuit breakers are becoming more and more significant. Numerous HVDC breaker technologies have been created, and proof-of-concept installations on actual networks have begun to appear. However, the literature is rife with information about them. This article examines the requirements and design of the component sub-assemblies, as well as the underlying problems and the top contender solutions. Its objective is to provide a thorough picture of the industry.

Kim et al. in, explored that when the market crash was imminent on January 4, 2016, China's stock market regulators put in place market-wide circuit breakers. This study investigates whether traders' herding behaviour contributed to the circuit breaker trigger and the market reaction's limited ability to be moderated. We demonstrate considerable herding on the event day's pre- and post-halt periods using intraday data. Herding and high market volatility, according to our research, are mutually causal. Importantly, we show that herding of both fundamentals and market attitudes around the circuit breaker trigger. The Chinese stock market is predominantly characterised by non-fundamental herding since it is a market dominated by individual investors. Nevertheless, the circuit breaker's unpredictable and disruptive effects caused a sharp decline in stock prices that supported the fundamental herding. Investors follow the crowd when making trades, which leads to self-enforced herding, increased market volatility, and the circuit breaker trigger.

Illia et al., explored that one of the most important components of the switching nodes in the power system are high-voltage circuit breakers. The circuit breakers' dependability in shutting off short circuit currents is a key factor in the localization of faults and the return of the power system to its normal operating state. In order to determine the priority of the maintenance schedule and estimate the dependability of high-voltage SF6 circuit breakers, a fuzzy logic-based technique is presented in this work. This technique, whose efficacy was examined using a MATLAB-Simulink model, combines a fuzzy inference system with a realistic mathematical model. For certain operating states and situations, a preventive maintenance approach for high-voltage SF6 circuit breakers may be suggested based on the simulation findings.

Amir et al. in, discussed that the power system is concerned about safeguarding delicate loads against voltage drops. A quick fault current limiter and circuit breaker may help sensitive loads quickly recover their voltage. The compound kind of current limiter and circuit breaker (CLCB) that this study suggests may restrict fault current and quickly break to correct voltage sags at protected buses can also limit fault current. It may also function as a circuit breaker to cut off the problematic line. The series L-C resonance, which includes a resonant transformer and a series capacitor bank, is the foundation of the proposed CLCB. A diode and an IGBT are also included in the CLCB, and they are coupled in series using bus couplers. The suggested structure was simulated in MATLAB to conduct a CLCB performance study. Additionally, an experimental prototype was created, put to the test, and they were documented. Comparisons demonstrate that experimental findings and simulation findings were generally in accord, confirming CLCB's capacity to serve as both a fault current limiter and a circuit breaker.

Sim et al. in, explored that the generating, transmission, distribution, and substation components make up the power system. To safeguard the system when a malfunction occurs, every component of the power system has to have the proper protective mechanisms. The circuit breaker has been chosen as one of the protective devices in a number of applications in this research. The kinds of circuit breakers that have been examined in this study include hybrid DC

breakers and solid-state DC breakers, as well as oil circuit breakers (OCB), air circuit breakers (ACB), sulphur hexafluoride (SF₆) circuit breakers, vacuum circuit breakers and DC breakers. The systems or circuits that the fault often disrupts or damages. Knowing the kinds of faults and their causes will help in implementing the protective system in the circuit or system. The substation is required to regulate the voltage delivered at high voltage from the producing station in order to give the consumer with the appropriate voltage. A substation must also include a protection system.

DISCUSSION

The greatest voltage that can be applied across all end ports, the kind of distribution, and how the circuit breaker is directly integrated into the system are used to determine the total voltage rating. It's crucial to choose a circuit breaker with sufficient voltage capability for the intended use. Frequencies between 50 and 120 Hz may be used with circuit breakers up to 600 amps. The breaker will need to derate for frequencies greater than 120 Hz. Because of the increased heating caused by eddy currents and iron losses during higher frequency projects, the breaker must be derated or carefully calibrated. Deration amounts vary according on the ampere rating, frame size, and current frequency. All breakers with greater ratings than 600 amps have a bimetal that has been heated by a transformer and are only acceptable for 60 Hz AC at most. There is often specific calibration available for applications requiring 50 Hz AC minimum. Solid state trip breakers are pre-calibrated for applications running at 50 Hz or 60 Hz. The frequency for a diesel generator project will either be 50 Hz or 60 Hz. Before beginning a 50 Hz project, it is important to confirm that calibration methods are in place with an electrical contractor. It is commonly understood that the interrupting rating is the maximum fault current that a breaker may interrupt without jeopardising the integrity of the whole system. It is possible to compute the maximum fault current that a system can provide at any particular moment. When selecting the right circuit breaker, there is just one unbreakable guideline that must be adhered to: the interrupting capacity of the breaker must be equal to or more than the maximum amount of fault current that may be provided at the system's application point. The breaker will get damaged if the proper quantity of interrupting capacity is not applied.

Moulded case circuit breakers are rated in amperes at a certain ambient temperature for continuous current rating. The continuous current the breaker will carry at the ambient temperature where it was calibrated is defined by its ampere rating. Manufacturers of circuit breakers often calibrate their standard breakers at 104° F. Any normal application's amp rating is purely dependent on the kind of load and duty cycle. The National Electrical Code (NEC), which governs ampere rating, is the main resource for data on load cycles in the electrical contracting sector. For instance, feeder and lighting circuits often need a circuit breaker rated for the conductor's maximum current carrying capability. Consult NEC table 210.24 to determine different standard breaker current ratings for various size conductors and the permitted loads.

Unusual Operating Situations

The end user location must be taken into consideration while choosing a circuit breaker. Each breaker is unique, and some are better suited for harsher settings. Consider the following possibilities when choosing which circuit breaker to use:

High ambient temperature

Standard thermal magnetic breakers must be derated or recalibrated to the environment if used at

temperatures over 104° F. at a long time, all breakers had to be derated since they were calibrated at a temperature of 77° F. Realistically, the majority of enclosures were about 104° F; for these kinds of conditions, a standard special breaker was employed. Industry standards were modified in the middle of the 1960s to require that all standard breakers be calibrated with a 104° F temperature in mind[7]–[10].

Corrosion and Moisture

Special moisture treatment for breakers is advised in areas where moisture is a constant. This treatment aids in preventing mould and/or fungus from damaging the unit. The best approach in environments with high humidity levels is to use space heaters within the enclosure. Breakers should ideally be taken out of corrosive environments. If this isn't feasible, corrosion-resistant breakers that were especially made are also available.

High Shock likelihood

A particular anti-shock device should be fitted if a circuit breaker is going to be put in a location where there is a high likelihood of mechanical shock. The trip bar is kept latching by anti-shock mechanisms, which comprise of an inertia counterweight above the centre pole. Installing this weight should avoid obstructing the ability of thermal or magnetic trip devices to respond to overload or short circuit situations. High shock resistant breakers, which are necessary on all combat boats, are primarily used by the US Navy.

Altitude

Circuit breakers must be certified for current carrying capability, voltage, and interrupting capacity in regions where the altitude is above 6,000 feet. In comparison to denser air found at lower altitudes, thinner air higher altitudes does not effectively transfer heat away from the current-carrying components. The thinner air also makes it more difficult for create a dielectric charge quickly enough to sustain the same voltage levels that occur at normal atmospheric pressure, which leads to overheating. The majority of commonly used generators and other power producing equipment might suffer from altitude problems. It is essential to consult a power generating expert before making a purchase.

Resting Position

For the most part, the tripping mechanisms and interrupting capability of breakers are unaffected by the mounting position, whether it be horizontal or vertical. It is essential to place the breaker in an enclosure (most units come enclosed) on a surface that sways somewhat with the wind in windy places. When a circuit breaker is fastened to a rigid surface, the circuit may get disrupted if strong winds are present.

Inspection and Testing

The customer must choose whether or not to purchase a circuit breaker that has undergone UL Testing (Underwriters Laboratories). It is advised that customers use UL-tested circuit breakers in order to ensure overall quality. Be warned that non-UL tested items do not ensure accurate breaker calibration. All low voltage moulded case circuit breakers that are UL listed have undergone two types of testing, called factory testing and field testing, in line with UL Standard 489.

UL Factory Testing

Based on UL Standard 489, all moulded case circuit breakers must pass thorough product and calibration testing before leaving the factory. Breakers with UL certification have calibrated systems that are factory sealed. The intact seal ensures that the breaker is accurately calibrated, has not undergone tampering or modification, and will function in accordance with UL requirements. Any warranties including the UL guarantee are null and invalid if the seal is damaged.

Field testing

It is common for data collected in the field to differ from information that has been published. Many consumers are unsure if the published information is out of sync with their specific model or whether the field data is inaccurate. Data are different because test circumstances at the factory are quite different from those in the field. Factory testing are designed to provide reliable findings. They are influenced by factors including temperature, altitude, a climate-controlled setting, and the use of test equipment made particularly for the product being examined. An excellent resource for infield testing is NEMA paper AB4-1996. The user is provided with a better version of the typical outcomes for in-field testing in the handbook. Some breakers are tested according to their own specifications. If there are no instructions, call a reputable circuit breaker repair firm.

Maintenance

Moulded case breakers typically have a great track record of dependability, mostly because the units are encased. The enclosure reduces exposure to contaminants such as dust, moisture, mould, and other containments as well as tampering. Making ensuring that all terminal connections and trip units are tightened to the appropriate torque value as defined by the manufacturer is a part of performing regular maintenance. These connections will need to be tightened again as they get looser over time. Breakers also need frequent cleaning. Excessive heating and breaker weakness may be brought on by improperly cleaned conductors, the incorrect conductors being utilised for the terminal, and loose terminations. All that is necessary for manually controlled breakers are clean contacts and freely moving connections. It is necessary to periodically restart circuit breakers to reenergize systems when they are not regularly utilised. Always seek the advice of a licenced electrician to find out precisely which kind of circuit breaker is suitable for your generator application. The variables that affect a power generators and a circuit breaker's safe and correct functioning differ from site to site, and only a qualified specialist can recommend the appropriate machinery.

Additional Classifications for Circuit Breakers

Circuit breakers are often categorised using attributes like voltage rating, working principle, current carrying capability, size, etc. A residual current circuit interrupter (RCCB), a small circuit breaker (MCB), a circuit breaker with moulded casings (MCCB), a circuit breaker employing solid-state (digital) technology, and an earth leakage circuit breaker (ELCB) are all examples of circuit breakers. The top 10 categories of circuit breakers used for mechanisms that turn on or off in unusual situations are mentioned below. This method takes less time to complete (between 30 and 150 milliseconds). There are several types of circuit breakers available depending on their needs, and each kind has advantages and disadvantages of its own. In a forthcoming piece, I'll provide a quick overview of each low tension (LT) circuit breaker's design, workings, and other characteristics.

Miniature Circuit Breaker

An automated electrical switch is known as an MCB. Small circuit breakers are intended to protect electrical circuits from overcurrent damage. They are designed to trip in the event of an overload or short circuit to prevent electrical issues and equipment failure. To minimise failures and false alarms, tiny circuit breakers use a mechanical mechanism that is relatively resilient. Overcurrent, which is electrical current that exceeds a set safe current, activates them. Due to an excessive current, the bimetallic strip within the MCB warms up, bends, and trips. The electrical contact points are separated when a switch is released, containing the arc (electrical discharge). An insulated metal strip called the arc chute separates and cools the arc. The contacts close again once the issue has been fixed and the MCBs have been reset.

An MCB safeguards against overloading and short-circuiting. They are identified utilising a variety of methods and techniques. While the tripping coil employs electro-magnetic function to defend against short circuits, the bimetallic strip uses thermal action to prevent overload. If the discharge is really high, the MCB will trip (activate) very quickly within one-tenth of a second. When the overcurrent approaches the safety limits, the component will respond more slowly.

Circuit breaker with a moulded housing

As installed system capacity in the Australian PV market continues to increase, it is crucial for system designers and installers to understand how moulded case circuit breaker's function and the relevance of their ratings. An electrical circuit is protected against excessive current, which might lead to overload or short circuit, using a device called as a moulded case circuit breaker (MCCB). MCCBs are suited for a range of voltages and frequencies because of their adjustable trip settings and current rating of up to 2500A. These breakers are used in lieu of small circuit breakers (MCBs) in large-scale PV systems for system isolation and protection.

Safeguards against overload

The MCCB's temperature-sensitive part employs overload protection. A bimetallic contact, which is what this component really is, is a contact comprised of two metals that expand at different rates when heated. Under normal operating conditions, the bimetallic contact will allow electric current to flow through the MCCB. When the current approaches the trip threshold, the bimetallic contact will start to heat up and bend away of the differing thermal rates of heat expansion within the contact. A certain amount of bending of the contact will finally cause it to physically push the trip bar and unlatch the contacts, breaking the circuit. The thermal protection of the MCCB will often include a time delay to account for a small period of overcurrent that is frequently seen during the operation of certain devices, such as inrush currents encountered while starting motors. The circuit may continue to operate properly in these circumstances without activating the MCCB because of the time delay.

Safety against electrical short circuit currents

MCCBs react immediately to a short circuit issue since they work on the electromagnetic principle. A solenoid coil within the MCCB creates a small electromagnetic field when energy travels through the device. When operating regularly, the solenoid coil's electromagnetic field is rarely perceptible. But when the circuit experiences a short circuit, a sizable current begins to flow through the solenoid. A strong electromagnetic field is thus produced, pulling the trip bar and opening the connections.

Solid-state digital circuit breaker

The solid-state breaker concept replaces the traditional moving components of an electromechanical circuit breaker with semiconductors and cutting-edge software algorithms to regulate power and interrupt extreme currents more swiftly than previously. Solid-state digital circuit breaker. Solid-state technology guarantees a very speedy interruption and corrects a flaw in a matter of microseconds. In contrast, a mechanical circuit breaker with the same frame size acts just briefly. A solid-state circuit breaker is 100 times faster in detecting and responding to a short circuit fault than a mechanical circuit breaker. Electrical grid services for energy storage systems and related systems are significantly impacted by the downtime in the case of an internal malfunction. The system may not shut down if the problematic zone is abruptly disconnected. Since there is no energy released during current interruption, the possibility of a dangerous arc flash emerging is almost non-existent. All electrical systems must be energy-efficient, especially those that use island networks, such as those found aboard ships with a built-in DC grid. Comparing solid-state circuit breakers to traditional semiconductor technology, power losses during the conduction phase are expected to be decreased by 70%.

Residual Current Circuit Breaker

Electricity still presents threats to both human life and property, despite the fact that it has become a necessary element of our existence. Electric shock and fire are the two primary dangers associated with electricity; thus one cannot afford to be reckless when it comes to insulating equipment. A Residual Current Circuit Breaker (RCCB) is a key element in the protection of electrical circuits. It is a current detecting device that may automatically measure and cut off the connection if a fault appears in the connected circuit or the current exceeds the stated sensitivity. RCCB, which is intended to protect people from the risk of electric shock, electrocution, and fires, is particularly helpful in cases involving quick earth fault. The RCCB's presence ensures that the circuit will rapidly trip under such conditions, sparing the sufferer from suffering an electric shock.

RCCB's underlying principle

RCCB is based on Kirchhoff's law, which states that an electrical circuit's incoming and outgoing currents must be equal. This is how RCCB compares the current levels that differ between live and neutral wires. It is ideal for the current flowing via the neutral wire to be equal to the current coming from the live wire and entering the circuit. In the case of a fault, the residual current the difference between the two currents decreases. When it detects a residual current, the RCCB is triggered to switch off the circuit.

Earth leakage circuit breaker (ELCB)

An earth-leakage circuit breaker (ELCB) is a safety device used in electrical systems with high Earth impedance to prevent shock. It checks the metal casings of electrical equipment for tiny stray voltages and cuts the circuit if one is detected. Residual-current devices (RCDs, RCCBs, or GFCIs), which were formerly extensively used, are now used in more recent installations since they directly detect leakage current.

CONCLUSION

Voltage, frequency, interrupting capacity, continuous current rating, unique operating circumstances, and product testing are some of the factors to take into account while choosing a

circuit breaker. A circuit breaker is essential for the upkeep and safety of a power supply system. Accidents involving electricity become nearly unheard of. Circuit switching systems employ various circuit breakers depending on the Low Tension (LT) and High Tension (HT). LT cables may be utilised in 1.1 kV range-related businesses including electricity distribution, power plants, trains, etc.

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ANALYSIS OF SUBSTATION AUTOMATION PLAN

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ABSTRACT:

Intelligent electronic devices (IEDs) and the communication infrastructure and protocols that allow their integration are advancing technologically at a fast rate. MidAmerican Energy Company created a substation automation (SA) strategy and is now putting it into practice at two pilot substations to guarantee that continuing internal efforts to integrate the IEDs have the correct direction given industry advances. MidAmerican decided to create a business case before moving forward with system installation efforts to make sure that the operational and strategic advantages that would be realized and the expenses to realize these benefits were clearly understood in advance. One of the main challenges to the effective implementation of electric utility automation projects has always been the absence of a strong business case. To guarantee that the financial and strategic costs and advantages of the automation project are properly understood in advance and complement the company's business objectives, a business case must be built.

KEYWORDS: *Automation Design, Control System, Electrical System Power Management, Substation Automation.*

INTRODUCTION

It is a capability for converting medium voltage to low voltage for end-user requirements. For various categories of end users, the low voltage level is separated into distinct branches. Secondary substations (SS) may be designed in a variety of ways, such as a cabinet and transformer mounted on a pole, metal container, concrete skeleton, or subterranean implementation in already-existing structures. SS may be of the node, loop, or end types depending on where it is in the network. A smarter, more reliable electrical grid is being created via substation automation, a term that has lately gained popularity. While technology is evolving quickly, maintaining the security of the electricity system has become essential. Nobody anticipates what will happen in the next minute, and the strong constant estimation has already occurred. The SCADA system is also quickly becoming a thing of the past, and synchronous phase's technology is gradually taking its place by adding PMUs (Phasor Measuring Units) for counting important substation and line limits. The term "substation automation" refers to the utilization of data from clever intelligent electronic devices (IEDs), control and robotization capabilities within the substation, and control instructions from remote users to regulate power system equipment.

This asset necessitated the use of IEDs such RTUs, recloses, PLCs, V meters, video for security or equipment status assessment, metering, exchanging, volt/VAR, wave structure, event

information, the executives, and so on. The programmed control of interlocks, global and local warning, and alarm, finding the location of distribution system faults, and equipment diagnostics are a few of the major advantages of substation automation. By equipping main equipment with current sensors and digitizing routine copper-based basic communication with secure, reliable, open-source fibre optic correspondence, substation digitization will significantly reduce costs, enhance operations, and increase safety [1]. So, substation automation is essential for getting more reliable power grids and moving towards innovation and new technologies to improve our daily lives.

Situational description

Automation on SS is continually being enhanced along with the progressive growth of automation in distribution networks. Power distribution businesses are able to learn more about a greater portion of the network, from the substation to the end customer, thanks to these expenditures. The LV level is also monitored after early investments in the automation of the main sides of the SS (MV level). The development of Smart Grids and the connection of more renewable energy sources are primarily responsible for the breakthrough [2]. Power quality metering, smart meters for monitoring distant power use and production, and self-healing grids, which utilize automation features to automatically reconfigure networks when lines fail to effect fewer customers, are additional emerging fields.

On the MV level, the power lines may be overhead wires or cables buried in the ground. It is advised to monitor both voltage and current in the case of overhead power lines, which are more environmentally sensitive, in order to assess any line defects. As it is believed that the voltage in cable networks is a fairly steady variable, problems on lines can only be found by current measurements. Due to the high cost of voltage sensors, this technique is much less costly. When the SS is in a strategic position, the voltage measurement on the MV level is also employed for the purpose of directional fault detection. This is beneficial when renewable energy sources are connected to the network or when the distribution node or loop may be powered from many directions. Another option is to monitor the voltage on the bus ones for all outlets and the currents at each outlet, which is a potential middle ground. This solution calls for a system that allows for the distribution of voltage data for the estimation of power (active, reactive, and apparent) at specific outlets.

Control history for substations

Conventional substations (mechanical relays, restricted sight, first RTUs with IO) an electrical firm has always placed a premium on an electrical substation's high availability and continuous functioning. Increased defects in more service interruptions for customers, which reduces income and is undesirable for any organization. Engineers and operators have been interested in gathering useful information on various devices in a substation since the beginning of electrical systems so they can better assess the health of their system, anticipate potential issues, and, in the event of a fault, analyses and troubleshoot the issue as soon as possible to protect their high-value assets and to improve their continuous service to their clients. Early substations were made comprised of mechanical relays and meters that could hardly be used for recording and had no communication capabilities. Reading and evaluating the information from fault recorders was a difficult procedure since the majority of the information was being recorded on paper charts. Any repair or troubleshooting made expensive and time-consuming since people had to be sent to substations that were sometimes remote and challenging to access.

LITERATURE REVIEW

Faraj et al.[3], discussed that the power communication service object is continually improved by the degree of modernization of the switches architecture created in the substation automation environment with the introduction of new information technologies. The communication network in the future design not only acts as a conduit for data between gadgets, but it also takes the communication network for the power system's dependability and effectiveness into consideration. In order to provide quicker and more reliable communication between control centres, Remote Terminal Units (RTUs), and Intelligent Electronic Devices (IEDs), several protocols are utilised. In applications like synchronised circuit breaker switching, distance protection, and overcurrent protection, these protocols facilitate the communication of a broad variety of potentially common data that is organised by a dataset. However, due to the significant volume of communication in the power system, these protocols do not perform as well as expected with conventional switch architectures.

Saeed Heidari et al.[4], explored that distribution companies (DISCOs) should create long-term strategies for this project since establishing distribution automation systems (DASs) requires a significant amount of resources. Similar to this, DISCOs have plans for network capacity expansion (NCX) that outline the method for building feeders and substations. The planner should alter the NCX plan via the DAS planning since taking into account DAS may in more effective NCX plans. On the other hand, an NCX plan must be taken into account for DAS planning in order to establish the date and place for the installation of automation equipment. The planner should thus be working on two plans at once since they are interdependent. This research introduces a unique way for integrated planning for NCX and DAS deployment to simplify this challenging planning process. The suggested approach creates a thorough strategy that specifies the best plan and timetable for building the lines, substations and installing automation technology. A genetic algorithm-based optimisation strategy is suggested to lessen the enormous computational strain. An example test network is used to assess the suggested strategy, and they are then presented and debated.

Irwan Eryket et al.[5], explored that the automation of substation monitoring systems, particularly in metering equipment, is the subject of this study. The goal was to design and install a substation that would be monitored by the SIMATIC WinCC programme. It made use of a three-phase power supply coupled to a number of loads made up of resistors, inductors, and capacitors. The outgoing load data that connected to and was stored to a personal computer (PC) was measured using the PM-710. The experiment made use of different loads. Based on the module, WinCC was used to mimic a power substation, and MOVICON was used to read metering data such as actual power, apparent power, power factor, and frequency, which were then shown on the PC monitor.

Rodrigo Pratet et al.[6], explored that to encourage quick setup and integration into the utilities automation system, international standards are being created. The international electro technical commission (IEC) has created and issued IEC 61850, a new worldwide standard for substation automation, in order to take use of contemporary technology and provide new advantages to substation automation users. The purpose of this article is to provide a fundamental technical overview of IEC 61850 and substation automation. It will go through the advantages of each key component of this standard and explain how these ideas may be used in the creation and usage of tools for substation automation. Data sharing inside the substation environment is made easier by

the use of communication standards and protocols, which is described. A small distribution system that intends to make use of cutting-edge communication technology in accordance with the IEC 61850 standard is also used to implement the concept. Finally, it suggests a collection of labs that would serve as the foundation for a course for undergraduates. The communication strategy recommended by IEC 61850 satisfies the real-time specifications for controlling and safeguarding the distribution system.

C. S. Chang et al.[7], explored that through the use of distributed and computer-based remote sensing, control and automation, and two-way communications, smart grid technology allows for the modernization of electricity delivery systems. The ability for the smart grid's central control to now manage and run several distant power plants, as well as to maximise overall asset utilisation, are potential advantages of the technology. In this study, we provide a novel method for the smart grid to manage risks brought on by power plant status monitoring and maintenance. The method manages operational differences that occur in each substation by using an adaptive maintenance adviser and a system-maintenance optimizer for creating and conducting optimised condition-based maintenance operations. By just taking into account the design or average operating circumstances, the system-maintenance optimizer develops the first maintenance plans for each substation. The substation will encounter ageing, control changes, shifting weather and load conditions, and unreliable measurements while it is in use. The maintenance adviser, who resides on each host substation, will evaluate the suitability of initial maintenance plans and, using a hierarchical fuzzy system, estimate the reliability changes brought on by operational fluctuations on the substation.

Peralta et al.[8], explored that electric distribution grids are still susceptible to natural disasters and because customers' expectations for the continuity of electricity service are rising in contemporary society, distribution network restoration is a recurring issue of interest to the power industry. By incorporating new technologies of control and automation as well as data conditioning and processing, the power distribution system has been modernised in response to the growing need for operational efficiency. Situational awareness of distribution networks is made possible by the integrated design of cutting-edge distribution and outage management systems. Fully automated restoration plays a key role in establishing the feeder loading and switching plan required to resume the interrupted service using data from the distribution state estimate. In active distribution networks, the study of switching for a completely automated restoration switches from a multi-objective model in which the operator selects the best switching plan to a single-objective optimisation model. The numerical analysis of a real-world substation is carried out in three steps, first by considering the multi-objective solution, then by considering the compromise solution under load forecasting, and finally by confirming the advantages of the automated switching operation.

Lai Daniel [9], discussed that digital substation automation solutions are the next step in the evolution of substation systems. The brains of today's digital substations are computers. In order to automate a substation, data from all IEDs (Intelligent Electronic Devices) and subsystems must be gathered and integrated into a strong, secure control system that can be used as a platform for device monitoring and sophisticated diagnostics. As computing technology advances quickly, more and more hardware-based substation functions (like PDC/PMU) can now be performed by software running on substation computers. Substations are increasingly moving towards software-defined substation design as this trend gains traction and they do so in order to save costs. The availability and controllability of the substation computer is a critical need for

establishing a software-defined architecture given the trend towards unmanned substations and the crucial role that computers play in a substation. Therefore, a crucial element for the effective operation of a substation is the availability and controllability of substation computers. The optimum technique for important substation equipment that involves computers is by far a predictive maintenance plan.

Chenet al. in [10], explored that as one of the pillars of a smart grid, automation is changing how people work, how businesses operate, and how the economy functions globally. To accomplish grid self-healing and raise dependability, it is essential to integrate automation systems into distribution networks. Smart secondary substations at each load point with installed automated sectionalize switches may be used to implement distributed automation (DA), but they need a significant financial outlay. In order to identify the ideal automation degree of Distribution networks bound by system reliability indices restrictions, this research offers a long-term strategy based on a cost/benefit analysis. DA planning is seen as a multi-dimensional, non-linear Mixed Integer optimisation issue. Therefore, it is not possible to directly search for all possible automation scenarios using numerical algorithms. The Hybrid Particle Swarm Optimisation and Gravitational Search Algorithm (HPSO-GSA) technology offers a binary-coded method to handle all the controllable variables and provide the best answer within the allowed constraints in order to tackle that challenge.

Contemporary substations

Digital protection and control devices gained intelligence with the development of microprocessor technology. Modern intelligent electronic devices (IEDs) may gather and store data on a variety of system characteristics, evaluate that data in a split second using complicated logic, and then decide if a condition is abnormal and send orders to switches and breakers to fix the problem switch and circuit breaker Modern substation devices may keep data in their internal storage for a certain amount of time and send it to outside applications for further research and analysis, in addition to having higher processing power. IEDs may now communicate information to a local or distant user using a variety of methods. In order to ensure a quick recovery period after a substation disruption, this allows operators additional freedom in how and when to handle the information.

New supervisory systems were created to simplify the work of a system administrator in the control center as more information became remotely accessible. A Supervisory Control and Data Acquisition (SCADA) system can gather data from various IEDs in an electrical system using a variety of communication channels, control and monitor them using a variety of visualizing technologies, and even automate the supervision process using predefined parameters and algorithms. In order to provide operators, the local control and monitoring capabilities often required during the setup, installation, or maintenance of the substation, a Human Machine Interface (HMI) is installed in each substation.

Standards, auto configuration, and digital substation

With the first introduction of digital devices, digital control and protection technology has been developing. The number of duties that tended to be moved from humans to machines increased as the gadgets' intelligence and capability increased. New technologies allow users to focus more on high-level aspects of the system architecture by taking care of the laborious task of defining every single detail in the system configuration, as opposed to early digital technologies, where an

operator had to work with bits and bytes on a primitive user interface to define every parameter of the system and make sure all elements of the system are correctly configured to make the processing and communication work.

Each manufacturer had a unique method for interpreting and implementing various components in an intelligent system at the dawn of the digital age. Vendor dependence and lack of interoperability were the of these diverse methods. To guarantee that devices from various suppliers would operate in the same prescribed manner, new standards have been devised. Users now have greater freedom and flexibility to choose the features that work best for them without having to pay close attention to the manufacturer. While remote information access gives operators significantly more system visibility, it also raises new issues and difficulties. Cyber security is one of the most crucial factors in any system deployment since it involves information exchanges with distant organizations, often through shared media.

Non-operational data processing and big data

Few data points were accessible on each device in the early days of digital technology, and it was impracticable to get a large quantity of data from each substation due to the high cost of connectivity and the sluggish data exchange rate. Communication lines were carefully configured to save bandwidth and communication costs, and only essential operational data was transferred to control centers. System administrators now have the luxury of polling progressively more operational and non-operational data points from their substations because to the quick development of communication and process technology. Using various software programmers, this data may now be processed in a number of ways to more effectively monitor an electrical system. The advancement in technology allows for a clearer view of overall health as well as helpful data for other applications like condition-based maintenance and asset monitoring.

System for automating substations

For local and remote monitoring and management of an electrical system, a substation automation system combines hardware and software components. To increase the system's overall productivity and efficiency, a substation automation system may automate processes that are repetitive, time-consuming, and prone to errors. Modern intelligent electronic devices (IEDs) may collect and store data on different system characteristics, analyses that data quickly using complex logic, and then determine if a state is abnormal and send commands to switches and breakers to correct the issue. Substation automation's (EEP) stated goals are to increase the effectiveness of operation and maintenance while also optimizing the management of capital assets.

System for managing power

The Power Management System (PMS), a crucial component of substation automation that regulates electrical generators, switchboards, and key users, is typically included into the IAS. The major duty of the power management system is to guarantee that power capacity is always per vessel and power demand. The fundamental duty of the power management system is to make sure that power capacity constantly matches vessel power demand. Moreover, it ensures that your electrical distribution systems and any linked assets run safely, effectively, efficiently, and in compliance with all regulations.

RTUs and a controller

RTU is a microprocessor-based device that connects to SCADA (supervisory control and data acquisition) or plant control systems while monitoring field equipment. It is sometimes referred to as remote telemetry or remote-control unit. An RTU solution, which is a framework for substation automation that is asset-compelled, gives your insight over remote sites that are crucial to your business. They work in a variety of fields, including as communications, utilities, and public safety. Remote control of industrial activities, including factory assembly-line machines, is possible with the use of electronic instruments like RTU and controllers.

System of communication

For local and remote monitoring and management of an electrical system, a substation automation system combines hardware and software components. Substation automation is the most sophisticated electrical engineering approach. It requires having a sophisticated, interactive electrical distribution network. Updates to substation automation provide the opportunity to reduce management and maintenance costs, increase plant production using enhanced schemes, and assess the condition of circuit breakers, power transformers, etc. Ethernet switches, one of the substation automation communication components that Schneider Electric offers, are simple to install and can be quickly incorporated into a broad range of electronic equipment.

Visual user interface

Using symbols, visual metaphors, and pointing devices, individuals may communicate with machines using a graphical user interface. The GUI interface, which is a component of substation automation, enables people to communicate with electronics like computers and mobile phones. GUIs show information and associated user controls visually, in contrast to text-based interfaces, which only display data and instructions as text.

SCADA and EMS gateway

Both EMS and SCADA are widely acknowledged as crucial strategic resources in the utilities business environment of today. Computers, networked data communications, and graphical user interfaces are used in a substation automation control system called SCADA to monitor equipment and procedures. It also comprises programmable logic controllers and other devices, such as sensors, that are connected to equipment or manufacturing facilities. Electricity conservation is the aim of typical industrial process automation.

A solution that satisfies your particular needs and maintains the long-term health of your substation systems will be designed and implemented by our experts with extensive industry expertise. The planning, administration, and execution of the project are all done in accordance with sequential, phased design decision processes and project procedures, which guarantee that we comprehend your system and what you want from it and that we are responsible to you at all times. Also, we provide very affordable, preconfigured system solutions for many common applications. These solutions were created using knowledge gained from more than 35 years of engineering innovation and field testing. They are adaptable to enable future expansion and work with a broad range of equipment interfaces. Substation HMIs and SCADA Integration HMIs are crucial parts of an automated substation because they provide operators access to crucial data and let them monitor and manage equipment and substation operations. At every size, from small substations to commercial buildings and large-scale grid operations, SEL Engineering Services develops and implements HMI, SCADA, and data integration systems.

Our experts will put in place a cost-effective, high-quality monitoring and control system for your substation that satisfies your particular operating needs. We can construct and commission whole SCADA systems that incorporate both new and old equipment, as well as integrate device-based solutions into already-existing systems. SEL automation controllers, which provide versatile RTU functionality with greater dependability, expanded I/O connections, and enhanced automation and control functionalities, may also replace old and noncompliant RTUs.

1. View and operate substation systems both locally and remotely using SEL SCADA integration, HMI installation, and automation controller solutions.
2. Use a Sequential Events Recorder to capture crucial data for root-cause investigation and advanced diagnostics (SER).
3. Improve grid stability and efficiency by employing synchrophasors and phasor measurement unit (PMU) data to assess and react to faults and failures and avoid future issues.
4. Control data reporting at the local and enterprise system levels.

System Control and Visualization

SEL creates reliable HMI systems that interface with IED settings for protection and control plans, monitor the status of communications lines and logic controllers, display power system data (such as real power, reactive power, voltage, and current), and incorporate alarm management and annunciation. To aid in troubleshooting and event analysis, Sequence of Events (SOE) reports and other nonoperational data may also be shown.

Network Operations

In addition to integrating new substation automation technologies with current SCADA systems, SEL Engineering Services installs SCADA for transmission and distribution networks. Additionally, we are skilled at creating and putting into practice special protection schemes (SPSs) and remedial action schemes (RASs), which assist transmission networks in enhancing their stability margins and overcoming the difficulties associated with integrating large renewable generation sources.

Automatic Control and Protection

At the substation level, the system and process level, and the grid operations level, SEL offers automated protection and control solutions. These technologies may be completely linked with SCADA systems and provide remotely accessible, secure monitoring. We use SEL technology to build rapid bus transfer and other high-speed automated transfer topologies, improving substation equipment protection and reducing the possibility of important loads losing power. We also use integrated arc-flash mitigation with SEL relays and high- and low-impedance bus differential protection techniques to ensure secure fault clearing.

These solutions enable operators to handle a whole facility's power system, including end devices, from a single HMI screen in industrial substations by seamlessly integrating with our MOTORMAX protection and control system, SEL POWERMAX power management, and power plant control systems.

Asset Tracking and Predictive Upkeep

Modern substation IEDs may already be able to provide the data required for asset monitoring

and preventive maintenance, and some of your primary equipment may even have been delivered from the vendor packaged with a CBM system. By combining CBM systems from different manufacturers into a single, complete asset monitoring and predictive maintenance system, we use tried-and-true techniques. This system is driven by the sophisticated data recording and processing capabilities of SEL automation controllers. These systems continually check the health and condition of switchgear and transformers used in substations, decreasing the likelihood of unexpected failures and allowing you to do maintenance exactly when and where it is required. They also provide information that may be used to risk assessment studies, capital asset management, efficiency improvement initiatives, and root cause failure mode analysis.

The earliest RTUs with IO, mechanical relays, and restricted visibility in conventional substations

An electrical firm has always placed a high priority on the continuous and high availability of an electrical substation. More defects in more service interruptions for customers, which reduces income and is undesirable for any organization. Engineers and operators have been interested in gathering useful information on various devices in a substation since the beginning of electrical systems so they can better assess the health of their system, anticipate potential issues, and, in the event of a fault, analyse and troubleshoot the issue as soon as possible to protect their high-value assets and to improve their continuous service to their clients. Early substations were made comprised of mechanical relays and meters that could hardly be used for recording and had no communication capabilities. Reading and analyzing the information from fault recorders was a difficult procedure since the majority of the information was being recorded on paper charts. Any repair or troubleshooting made expensive and time-consuming since people had to be sent to substations that were sometimes remote and challenging to access.

Contemporary substations

Digital protection and control devices gained intelligence with the development of microprocessor technology. Modern intelligent electronic devices (IEDs) may gather and store data on a variety of system characteristics, evaluate that data in a split second using complicated logic, and then decide if a condition is abnormal and send orders to switches and breakers to fix the problem. Modern substation devices may keep data in their internal storage for a certain amount of time and send it to outside applications for further research and analysis, in addition to having higher processing power. IEDs may now communicate information to a local or distant user using a variety of methods. In order to ensure a quick recovery period after a substation disruption, this allows operators additional freedom in how and when to handle the information.

New supervisory systems were created to simplify the work of a system administrator in the control center as more information became remotely accessible. A Supervisory Control and Data Acquisition (SCADA) system can gather data from various IEDs in an electrical system using a variety of communication channels, control and monitor them using a variety of visualizing technologies, and even automate the supervision process using predefined parameters and algorithms. In order to provide operators, the local control and monitoring capabilities often required during the setup, installation, or maintenance of the substation, a Human Machine Interface (HMI) is installed in each substation.

Automatic setup and digital substation

Since the first introduction of digital devices, digital control and protection technology has been

developing. The number of duties that tended to be moved from humans to machines increased as the gadgets' intelligence and capability increased. New technologies allow users to focus more on high-level aspects of the system architecture by taking care of the laborious task of defining every single detail in the system configuration, as opposed to early digital technologies, where an operator had to work with bits and bytes on a primitive user interface to define every parameter of the system and make sure all elements of the system are correctly configured to make the processing and communication work.

Each manufacturer had a unique method for interpreting and implementing various components in an intelligent system at the dawn of the digital age. Vendor dependence and lack of interoperability were the of these diverse methods. To guarantee that devices from various suppliers would operate in the same prescribed manner, new standards have been devised. Users now have greater freedom and flexibility to choose the features that work best for them without having to pay close attention to the manufacturer. Although remote information access gives operators significantly more system visibility, it also raises new issues and difficulties. Cyber security is one of the most crucial factors in any system deployment since it involves information exchanges with distant organizations, often through shared media.

Limited data points were accessible on each device in the early days of digital technology, and it was impracticable to get a large quantity of data from each substation due to the high cost of connectivity and the sluggish data exchange rate. Communication lines were carefully planned to save bandwidth and communication costs, and only essential operational data was delivered to control centers. System administrators now have the luxury of polling progressively more operational and non-operational data points from their substations because to the quick development of communication and process technology. Using various software programmers, this data may now be handled in a number of ways to more effectively monitor an electrical system. The advancement in technology allows for a clearer view of overall health as well as helpful data for other applications like condition-based maintenance and asset monitoring.

CONCLUSION

For local and remote monitoring and management of an electrical system, a substation automation system combines hardware and software components. Substation automation employs data from Intelligent Electronic Components (IEDs), control and automation capabilities within the substation, and control instructions from distant users through SCADA to operate power-system (switch yard) components. Benefits of automation in substations are necessary for the cooperative's member-owners to get their energy. Power plants create high-voltage electricity, but substations transform it into a form that can be transmitted to homes and businesses.

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SHORT CIRCUIT ANALYSIS BASED ON TEMPERATURE RISE

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ABSTRACT:

The terminating of the superconducting cable includes a current lead, which is crucial. The temperature distribution of the current leads will change when a short circuit fault occurs because of the significant quantity of heat that is produced in a little length of time. In this study, a theoretical calculation-based thermal field simulation model of current leads is developed. Based on the HTS cable's optimised characteristics, the impact of the short circuit fault's impact on temperature increase in various locations is also examined, as are the effects of the short circuit fault's size and timing on the temperature distribution of the current lead. The obtained findings demonstrate that the short circuit current's duration and amount have a significant impact on the current lead's temperature distribution. The hot end's temperature distribution is more affected by short circuit current than the cold end.

KEYWORDS: *Circuit Temperature, Ion Battery, Temperature Rise, Switchgear, Substation Infrastructure.*

INTRODUCTION

In order to calculate the short-circuit ratings of new switchgear and substation infrastructure equipment that will be purchased and installed, short-circuit current calculations are made during the system design phase. System reinforcements may be brought on by network expansion or the installation of more power-generating units. Regular calculations are also done to make sure the current equipment is still adequate when system operating parameters change. In order to achieve precise and well-coordinated relay operations, calculations of minimal short-circuit currents are also performed and employed in the computation of protective relay settings [1]. To prevent generating units losing synchronism and significant outages of the power networks, short-circuit currents in transmission lines must be immediately removed. For the aim of developing substation earth electrode systems, calculations of the maximum short-circuit current are made to calculate the short circuit temperature rise. The first power quality evaluations also involve a short-circuit study to connect disruptive loads to electrical power networks[2].

Voltage and temperature curve. Voltage flicker, harmonic analysis, and voltage imbalance are a few of these evaluations. The modification of an existing system or the early stages of the design of new electrical power installations, such as an offshore oil platform, a petrochemical processing facility, or the auxiliary electrical power system of a new power station, are further uses for short-circuit analysis. Finding out the short-circuit ratings of the upcoming switchgear purchases and other infrastructure components for substations is the goal. Circuit breakers with melted cases are only used in LV applications. They are always three-phase devices and are essentially an improved version of the micro circuit-breaker. Each design includes a built-in

thermal overload and short-circuit safety mechanism, and some of them also have cut-off capabilities similar to those of a current-limiting fuse. They typically have current ratings of 100 to 2500 A and can withstand short-circuit currents of up to 50 kA at 415 V. Additionally, protection against ground leaks might be offered.

P1 and P2 are the two subcategories of short-circuit performance. Circuit breakers in Category P1 must be able to conduct both an open (O) operation and a close/open (CO) activity in the event of a short circuit. The circuit breaker has to be changed after this job since it may not be able to maintain its usual standards. To qualify for Category P2, the circuit-breaker must pass a second CO test without having its conductivity now affected. When using melded-case circuit breakers, care must be taken to consider the chance of a fault occurring as well as the circuit's susceptibility for short-circuiting [3]. A category-P1 melded-case circuit breaker is likely to be insufficient for circuits with a high rate of failure.

If a design does not include mechanisms for contact maintenance, a contact degradation will only be discovered via an unintentional trip brought on by overheating [4]. As the name indicates, merged-case circuit breakers are always entirely enclosed in melded casings. The device generally has an on/off operational toggle on the front, and the top and bottom of the device typically have three-phase terminals. The tiny circuit breaker often uses an over-centre spring mechanism to function. Melded-case circuit breakers are often used for three-phase LV load protection and motor starting[5]. They provide a similar purpose as fuse switches in these situations. The common circuit breaker with a plastic housing cannot be utilised to replace a contactor in situations where frequent starting is anticipated to be necessary since they are unable to function remotely or often.

When a motor is first switched on, before the shaft has a chance to pick up speed and begin spinning, the stator coil acts as a short circuit. The motor thus starts to draw extraordinarily high current levels. The magnetic field produced by this current causes the motor shaft to rotate, and the ensuing counter-EMF (CEMF) limits the current to its usual working value. Inrush current, often known as the initial high value of current, may cause substantial line interruptions and unpleasant tripping if fuses and circuit breakers are not constructed properly. A motor draws more current than it should, often up to six times the rated current, and this causes an "overload," which is a gradual and mild rise in the value of current over a long period of time. This is the overworked motor. Relays for systems that provide overload protection. Even while short overloads, which might last for several minutes, are allowed, prolonged overloads will use thermal action to activate a protective system.

Overcurrent

Overcurrent, commonly referred to as a short circuit or ground fault, is the term used to describe an abrupt and fast rise in current over a brief period of time. Equipment and circuits are protected against overcurrent situations using fuses or circuit breakers. The current value in these circumstances may be anywhere between six and many hundreds of times more than the average rated current value and is much higher than the nominal line current. An overcurrent may occur for a variety of causes. When a line to line or line to ground fault is bolted, for instance. This causes a very large amount of current to be pulled since a circuit's resistance and current drawn are inversely correlated.

Short circuits may also occur when an induction motor starts for less apparent causes. Three-

phase induction motor's stator windings start off with a very low resistance path. This draws a significantly larger inrush current than a standard short circuit, but it quickly drops to the motor's rated current draw. That is the sole difference between both. This is caused by the CEMF (counter-electromotive force) generated by the rotating motor shaft. While the motor is operating, a CEMF controls the current to maintain safe levels. While the motor is not moving, a massive quantity of electricity is collected from the source. This quantity of current, also known as locked-rotor current, must be carefully managed by motor starters and overcurrent prevention mechanisms[6].

Effects of short-circuits

Two of the main negative impacts of overcurrent are as follows:

1. **Thermal energy:** Excessive heat produced by high current levels might damage cables and other equipment. Thermal energy may be described by the equation I^2t (current squared times time); the longer a fault persists, the greater the possibility of thermal damage.
2. **Mechanical forces:** Bus bars and other equipment may be subjected to intense magnetic fields and magnetic stress from high-fault currents, which can sometimes in deformation and other problems.

Since huge levels of fault current may cause damage very quickly, overcurrent protection devices must act quickly to eliminate the fault. The two main subcategories of overcurrent protection devices are fuses and circuit breakers. A fuse is a simple device that prevents damage to a circuit's components and conductors brought on by fault values that are higher than normal. It's designed to be the fuse wire in a circuit that breaks easily. A fuse is a conductive metal strip with a lower melting point than copper or aluminium that is encased in an insulated tube. In the fuse connection, small, resistive components concentrate the current and increase the temperature in the vicinity. During a short circuit, the fuse components burn open in a matter of seconds. As the fault current level rises, the fuse will react more rapidly. In a situation of overload, the fuse components may take many seconds or even minutes before heat processes force the fuse link to melt open. The two kinds of fuses are time-delay fuses (Type D) and fast-acting fuses (Type P). Because they must withstand the strong inrush current that occurs when a motor is started, time-delay fuses, also known as "dual-element fuses," are used in motor circuits.

Standard scores

It is necessary to operate all overcurrent devices within their rated values. Three of the most important rating categories are voltage, current, and interrupting capacity.

Rating of power

The voltage of the circuit that they are designed to safeguard must be at least as high as the rating of the circuit breakers and fuses. When a fuse or circuit breaker cuts off a fault current, the arc has to be securely extinguished and prevented from flaring up again. Thus, the voltage ratings of the circuit breakers and fuses must be equal to or greater than the system voltage. For instance, a 120V circuit may employ a fuse with a 240V RMS rating. However, it would go against the fuse's voltage rating to use it in a 600V circuit.

For continuous duty rating

The greatest defined amount of RMS current that an overcurrent device is designed to sustain

without tripping is referred to as the device's continuous-duty rating. In certain circumstances, such as some motor circuits, the fuse or breaker's ampere rating may be more than the circuit's capacity to transmit current.

Being able to interrupt

When a short circuit or ground fault occurs, the circuit resistance almost drops to 0 ohms, allowing for extraordinarily high current levels to flow. Considering that it might overheat and damage wires and other equipment, this abnormally quick spike in fault current has to be extinguished right away. The interrupting-capacity (IC) rating of an overcurrent device indicates the maximum fault current it can interrupt without causing a person injury. Most circuit breakers and fuses have an IC rating of 10,000 amps. In systems equipped to handle higher fault currents, high-rupture capacity (HRC) fuses may stop currents up to 200,000 amps by using an arc-quenching filler, such silica sand, to help stop the fault.

Hardware observation is crucial for a wireless sensor network to operate. Significant displacement may be correctly confirmed by wireless sensor networks. The Internet of Things is needed to build a complex network. Modern society's growing use of power is causing fault current levels to rise. Urban modernization and the expansion of industrial facilities have led to a steady increase in the size of industrial and commercial electric power networks. One clear of this rise in power system capacity is an increase in fault current levels, which may also be made worse by nearby power plants, scattered output, and the connectivity and growth of electric networks. Instead, short-circuit currents could be restricted to prevent the need to change already-installed equipment or swap it out for apparatus with a high short-circuit current capacity. A common strategy is to imitate SFCL devices using streamlined power systems, such as systems used in lab tests, single-source systems, line systems, or systems with two sources coupled by a bus connection.

Systematic analyses of the behaviour of SFCL devices in a sophisticated model of power systems are required in order to increase the application of this novel technology in commercial and industrial power systems. The temperature of the R-SFCL element soon rises over its critical temperature of losses during the current-limiting scenario. To manage the restricted current and divert some of it away from the R-SFCL element and towards the shunt, SFCL designers often include a predetermined resistive shunt element. The superconducting component doesn't burn out as a consequence. These operating parameters are related to the E J (electric field versus electrical current density) curve of the R-characteristic SFCL. Only temperature and current density have an impact on a superconducting element's properties. If a cable must endure the impacts of a short circuit, its performance under fault circumstances must be taken into consideration while making the selection.

The heat produced by cables in a fault situation and any possible harm this may bring to the insulation are the main worries. The protective device will isolate the fault in time to prevent a significant increase in cable temperature, which is the foundation for the fault rating. Both the conductor and the screen/armor wire have cable short circuit ratings that are published by Prysmian. Screen/armor fault level is referred to as asymmetrical or single-phase (phase to earth) rating, while conductor fault level is known as the symmetrical or three-phase rating. Prussian obtains short circuit ratings using the procedures defined in IEC standard 60949. The reported values are accurate. This worst-case scenario is based on the assumption that the heat that would be transported to the insulation and sheath in the event of a short circuit is not taken into

consideration.

Priscian employs temperature rises of 90–250°C for cables with thermosetting polymer insulation and 70–150°C for cables with thermoplastic insulation for predicting conductor failures. Insulation with a fault has a higher limit temperature. The cable's maximum working temperature for both cable types is the lower temperature. Since a failure is very unlikely to occur while the cable is operating at its maximum load and temperature, the number shown at the lower temperature will, in principle, be conservative. The cable is once again taken into account to be at its maximum operating temperature for the computation of the screen/armour fault. This will often be 90°C for cables that have screens or armour, with the temperature within the screen or armour being around 10°C lower. With PVC and LSOH sheaths, the insulation can withstand temperatures up to 200°C, which causes a temperature increase of 80–200°C. With a temperature increase of 80–250°C, the insulation's limiting temperature of 250°C determines the fault rating for MDPE sheaths.

We use the most often requested value of one second for computing faults. The 1-second fault rating may be multiplied by the square root of the necessary amount of time in seconds to create other fault ratings. This computation may be accurate to within 0.2 to 5 seconds.

MV cables with a fault-sharing shield made of aluminium

For their medium voltage armoured cable range, Prysmian states the fault rating of the armour layer in line with their requirements. These cables are made of one or three stranded copper conductors, one or three circular layers of aluminium wire armour, extruded cross-linked polyethylene (XLPE) insulation, a metallic screen made of overlapping copper tapes, and one or three stranded copper conductors. Steel's MV cable features three stranded conductors as opposed to aluminium's single conductor MV cable.

At each place, the copper screens and armour wire will be linked and terminated such that external fault currents will gravitate towards the parallel armour route. The breakdown arc will link through to the armour wires in the event of an internal cable earth failure and transmit the electricity to earth. The conducting arc created by the breakdown of the XLPE insulation would vaporise the cable armour bedding at the location of the fault, and the armour wires would be brought into the circuit by a parallel channel.

MV cables with screens made of copper wire

Direct Network Operators (DNOs) often use copper wire screened cables produced in compliance with BS7870-4.10 in place of armoured cables. The wire screen's required fault level will be determined by each DNO. On its network, each DNO has a designated fault level. When making cables, a range of copper wire screen sizes are often used, with 50mm² being the most common size. The rating for a one-second adiabatic test is for medium voltage power cable, assuming an MDPE sheath with an ultimate sheath temperature of 250°C.

Preeminent base scores

International standards and cable manufacturers give basic current ratings for various cable types in tables like the one on the right. These tables each relate to a certain cable construction (copper conductor, PVC insulated, 0.6/1kV voltage grade, etc.) and a fundamental set of installation requirements. Remember that the current ratings only apply to the cables and installation circumstances stated in the quotations.

Ratings as of the present

Derating (or correction) factors may be added to the base current ratings in order to get the actual installed current ratings when the projected installation circumstances deviate from the basic conditions. For a variety of installation situations, such as ambient / soil temperature, grouping or bunching of cables, soil thermal resistance, etc., international standards and cable manufacturers will provide derating factors. Multiplying the base current rating by each derating factor yields the installed current rating.

Types of Circuit Breaker Tests

Type tests are performed to demonstrate the functionality and validate the rated characteristic of the circuit breaker. These tests are carried out at the testing lab that was especially constructed. Type testing may be roughly categorised as mechanical performance tests, thermal tests, dielectric or insulating tests, and short circuit tests to verify the making and breaking capacities as well as the operational duty and short time rating current.

Mechanical exam

This exam involves repeatedly opening and shutting the breaker to assess mechanical abilities. A circuit breaker must operate mechanically faultlessly, open and shut at the proper rate, and carry out its intended function.

Thermal Tests

Thermal tests are performed to examine the circuit breakers' thermal behaviour. The test breaker is designed to withstand steady-state temperature increases brought on by the passage of its rated current through one of its poles under specified conditions. If the typical value of the current is 800A or more, the temperature increase for the rated current should not be more than 50° and should not exceed 40°.

Dielectric test

This test is used to determine the ability to tolerate impulse voltage and power frequency. On a brand-new circuit breaker, power frequency tests are maintained; the test voltage varies with the rated voltage of the circuit breaker.

The test voltage is delivered as follows at a frequency of between 15 and 100 Hz. (1) With the circuit breaker closed between the poles, (2) with the circuit breaker open between the pole and the ground, and (3) with the circuit breaker open across the terminals.

In impulse testing, the breaker is subjected to an impulse voltage of a certain magnitude. Both dry and wet testing are performed on outdoor circuits. Circuit breakers are exposed to abrupt short-circuits in short-circuit test labs, and oscillograms are recorded to understand the behaviour of the circuit breakers during contact breaking, during the moment of switching in, and after the arc extinction. The producing and breaking currents, as well as the symmetrical and asymmetrical restricting voltages, are analysed specifically in the oscillograms, and switchgear is sometimes tested under rated circumstances [7]–[10].

Standard Circuit Breaker Tests

Additionally, routine testing is carried out in accordance with the norms of the Indian Engineering Service and Indian norms. On the premises of the producers, these testing are

conducted. The circuit breaker is confirmed to be operating correctly by routine testing. The usual testing show that the circuit breaker is operating correctly.

The millivolt drop test is carried out to ascertain the voltage drop inside the current route of the breaker mechanism since the power frequency voltage test is the same as specified under the topic of type testing. The breaker is put through an operational test by simulating its trip by forcibly shutting the connections on the relays.

CONCLUSION

The performance of a solar cell degrades with temperature because the open-circuit voltage strongly declines while the short-circuit current rises very modestly (nearly not visible in the image). When a short circuit occurs, the system's current rises to an unusually high level while the voltage drops to a low one. Due to the strong current generated by the short circuit, there may be an explosion or fire. The conductor will be heated more intensely of an increase in current because the conductor will absorb energy at a faster pace. In conclusion, the greater current produces more energy, which raises the temperature.

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MEASUREMENT OF EARTH LOOP IMPEDANCE

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ABSTRACT:

The efficiency of automated supply disconnection in low-voltage networks is evaluated using earth fault loop impedance measurements. Particularly in a TN low-voltage network, such a test is carried out at startup and periodic inspection. These tests are challenging in many circuits nowadays because residual current devices (RCDs) are widely used and function throughout testing. With the main switch in the OFF (open) position and the means of earthing disengaged, the earth loop impedance is generally measured using an earth fault loop impedance tester. When using an external earth probe or a socket outlet, a loop tester is plugged into the outlet to measure the overall earth fault loop impedance. With the main switch open and all circuits isolated, the Z_e earth fault loop impedance is measured on the supply side of the distribution board and the primary earthing point. The applicable typical maximum value announced by the electrical distributor may not match the value of external earth loop impedance (Z_e) measured or otherwise determined in line with Regulation.

KEYWORDS: *Distribution Board, Earthy Loop, Fault Loop, Impedance Testing, Test Current.*

INTRODUCTION

Earth loop impedance testing for new installations should proceed easily during the first verification stage since the system hasn't been put into operation yet [1]. For a functioning installation, there could be serious consequences for the user if, for example, computer data is lost or a home life support system is turned off due to an unintentional interruption of supply during the test, such as that which could happen of an RCD's accidentally operating. A circuit, group of circuits, distribution board, or even the whole system might be unintentionally disconnected if an RCD triggers during an earth fault loop impedance test. Several methods have been developed to lessen the likelihood that an RCD may activate during such a test [2]. The next section explains calculating as one such method. Another method is to measure the earth loop impedance using a loop test equipment [3]. In order to prevent the RCD from being triggered, the test current should be maintained below 15 mA [4].

Earth loop impedance calculation

According to Regulation, earth loop impedance may be estimated using techniques other than measurement. Therefore, it is permissible to determine a circuit's loop impedance using the formula $Z_s = Z_e + (R_1 + R_2)$. This is accurate provided that the external earth loop impedance (Z_e) and the line and protection conductors' loop resistance ($R_1 + R_2$) have correct measured values [5].

However, using a Z_e value that has previously been measured or determined by contact with the electrical distributor does not ensure that the necessary means of earthing are available and have the needed low ohmic values. The only way to determine Z_e 's value is to use a loop impedance test equipment after the installation has been disconnected from the power supply and all earthing techniques have been disconnected from the installation's safety bonding wires[6]. The value of the earth loop impedance measured at the distribution board from where a distribution circuit or final circuit originates (Z_{db}) may be used in lieu of Z_e in larger, more complex systems. Furthermore, because any RCDs defending the affected circuit are on the supply side during the loop test, they shouldn't normally trigger while Z_e or Z_{db} measurements are being taken. However, anybody using this method has to make sure that there isn't another RCD upstream of the circuit being checked, such as one protecting a sub-main circuit.

Careful safety measures

The use of specialised plug-in adaptors is indicated for doing high or low current loop impedance testing, which ordinarily necessitates the use of test probes and partial disassembly (for instance, to test lighting circuits in home premises). When probes are utilised to do live testing, the risk of electric shock might increase. According to Regulation 14 of the Electricity at Work Rules of 1989, no person shall do any work activity on or so close to any live conductor unless it is acceptable to do so and suitable precautions have been taken to prevent injury from electric shock. Electrical testing is included in the concept of "work," which includes all job-related activities and is not only restricted to electrical labour[7]

Earth loop impedance in the final circuits

Each final circuit and distribution circuit must have its line-earth loop impedance (Z_s) value verified to guarantee that, in the event of an earth failure, the automatic supply disconnection to the circuit will occur within the appropriate maximum time stipulated in Regulation Group[8]. Earth loop impedance show in Figure 1.

For instance, 230 V as the nominal voltage to ground (U_0) offers the longest intervals for final and distribution circuits that may be removed in TN and TT systems. When calculating if the value of Z_s is low enough to achieve disconnection within the stipulated maximum time impedance of the circuit, the characteristics of the protective device employed for automated disconnection must be taken into account. For commonly used overcurrent devices, this is often achieved by ensuring that the measured value of Z_s at the circuit's electrically furthest component does not exceed 80% of the applicable maximum value. For overcurrent devices not covered by those tables, the manufacturer's data or another reliable source of information on the limiting values of Z_s should be consulted.

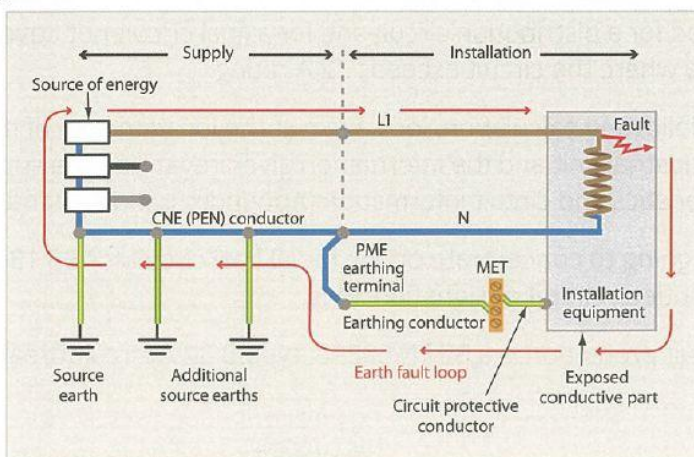


Figure 1 Earth loop impedance [ElectricalAxis].

When the protective device is a non-delayed RCD, the greatest value of Z_s may be calculated. The Z_s values in the table may be utilised with a TN system even though they were created for a TT system. These Z_s values meet the disconnection time requirements of BS 7671 as well as the criterion RA In 50 V outlined in Regulation 411.5.3 (ii) for a TT system. I_{in} is the rated operating residual current of the RCD, and RA is the sum of the resistances of the shielding conductor to the exposed conductive part and the earth electrode to Earth.

Impedance of the Earth Fault Loop

Each circuit must be checked to make sure the actual loop impedance does not go beyond the limit specified for the applicable protective device. Due to the risk of touching an electrical fault, it is essential to have your electrical installations and power points assessed for earth fault loop impedance. Maintaining the circuitry in your systems is crucial for the life and effectiveness of your business. To offer basic shock protection, most homes set up an earthing circuit with automatic switches in the interior electrical circuits. When a problem occurs and the touch voltage rises beyond the acceptable limit, the power to an earthing circuit is immediately cut off[9].

To ensure the security of all guests and employees, you must conduct a loop impedance test on your property in compliance with the most current national safety rules. You must inspect the electrical earth of all your electrical installations and power points to detect any problems in your electrical circuit. A working earth return circuit facilitates the detection of circuit issues and speeds up the response time of your MCB (miniature circuit breaker). A Care labs expert will measure the resistance level in your earth return circuit and inform you whether it is too high or low for the circuit breaker to function correctly. You are assuring the safety of your employees as well as your accountability by hiring Care labs to inspect your electrical wiring. It's essential to abide with national regulations to avoid paying harsh penalties[10].

The required values of impedance and duration will vary depending on the installation type (TN/TT, etc.) and the kind of protection, such as a micro circuit breaker (MCB), cartridge fuse, or re-wire able fuse, for example. Since the fault current might be in either the line-neutral or line-earth circuit, it is important to verify the loop impedance of each circuit. During the Earth Fault Loop, Impedance. It is generally accepted that where the measured earth fault loop

impedance of a circuit is not greater than 80% of the relevant limit specified in BS 7671, the impedance can be expected to be sufficiently low under earth fault conditions to meet the relevant limit specified in BS 7671 and for the protective device to automatically disconnect within the time specified.

The TT wiring system is properly protected from the risks of electric shock when it satisfies the equation $R_a \times I_a \leq 50$, where "Ra" denotes the total resistance of the earth bars and protective conductors and "Ia" the maximum current of the protection system. When Ra is multiplied by Ia, the maximum voltage that a human may come into contact with in an earth fault should not be more than 50 V. The distance between the active conductor and the ground is checked for fault loop impedance. An earth loop impedance tester that is plugged into the power outlet (GPO) will be used by our expert to determine the loop impedance. Our highly qualified team of experts offers earth loop impedance test services throughout the nation.

It is best to start by doing the External earth loop impedance (Z_e) test. The loop impedance of the circuit is calculated using this distribution board test without taking the installation into consideration. The system loop impedance test (Z_s), which incorporates both the installation resistance and the circuit that was scrutinised in the Z_e test, is the next phase. The fault loop impedance is measured at the same frequency as the normal mains frequency (50 Hz) because to the potential that an electrical circuit's AC impedance might differ from its DC resistance, particularly for circuits rated at more than 100 A. The Z_e earth fault loop impedance is measured on the supply side of the distribution board and the primary earthing point with the main switch open and all circuits isolated. The connection between the installation's earthing system (earth rods) and the methods of earthing will be severed during the test. The Z_e measurement will confirm that the earth fault loop impedance is equal to the sum of the resistances.

DISCUSSION

An earth loop impedance test is done to make sure that the fault current in an electrical circuit will be strong enough to trigger the circuit protection. If a problem current is not found in time, circuits might overheat and ignite. The least-resistant path is used by electricity to reach the ground. Electrical wire systems in buildings are often grounded. Here, we are discussing an earth return circuit. The grounding wire may experience electrical current flow during a short circuit. Resistance is a gauge of the impact a current's path has on it. In order for the fault current to pass into the ground without harming the system, low resistance is needed in the grounding wire. If the earth return circuit resistance is too high, the fault current may be too low to be detected, in which case it may continue to loop through the main circuit in a short circuit. The circuit protection senses activity along the earth wire and turns on when it detects it. If the resistance is too high, the circuit protection could not function properly. Impedance testing so important if the circuitry in your building's ongoing quality concerns you, it is essential. To prevent overheating and fires, the loop impedance must be maintained at a certain level. The only way to maintain this level at its optimal state is by regular testing.

Two-wire high current test as a loop impedance measurement technique

This is how the traditional loop impedance test looks. With a test current of up to 20 A and a simple 2-wire connection, it is by far the fastest and most accurate test that is currently available on a daily basis. Most commonly used loop impedance testers will provide this kind of test.

Readings are often unaffected by outside factors and provide constant, steady findings in the majority of situations because of the relatively substantial test current.

Two-wire No-Trip DC saturation test

Before doing a standard 2 wire high current test, the circuit was examined with a DC test current. This DC test's objective was to thoroughly saturate the RCD's monitoring coil so that the high current AC test could proceed. However, this method only has a limited number of applications today that there are more electronic RCDs.

Three-wire No-Trip test

This test method circumvented even the most advanced electronic security systems by offering a degree of precision while using a low current Line-Earth test current. Since the RCD/RCBO did not need to be bypassed, time was saved. The testers were also able to confirm the presence of all three by connecting to Line, Neutral, and Earth as well as determine if reverse polarity existed at the test location. Additionally, there were no issues activating the MCB since the test current was regulated.

With these, the majority of RCDs and RCBOs may be checked without having to be bypassed. They still work as true 2-handed devices without the requirement for a neutral connection, but they no longer warn of a missing neutral or indicate reverse polarity. Even while the physical test is quicker than the 3-wire method, it is still more accurate since the RCD is not circumvented. The use of a four-wire Kelvin connection, which removes internal lead and contact resistance, improves the test's accuracy. Test currents up to 1000 A may be used to successfully complete measurements down to 10 MOhm. There is no "No-Trip" option for this test process. The test engineer may use this tester to get accurate data for specialist applications like measurement in sub-station or switch room settings.

A circuit protected by an RCD will need additional caution since the earth-fault loop test will draw current from the phase that returns through the protective mechanism. Testing RCD-protected circuits has made it difficult for instrument manufacturers to provide test that are equivalent to those of testing non-RCD protected circuits without activating the RCDs. Any RCDs must be short-circuited in order to be bypassed during earth-fault loop testing. It is important to make sure that these connections are severed after testing, of course. Care labs uses an earth loop impedance tester that prevents the RCD of the circuits we are testing from being activated. Our experts will conduct all tests and inspections in compliance with the most current safety rules. Testing is necessary for everyone's safety on the workplace. Get tested as soon as possible to ensure the safety of your job. We can assist you in meeting all of your compliance requirements.

Since the test conclusion relies on the supplied voltage, even little adjustments will have an effect. The test should be repeated several times in order to get reliable. When establishing contact and doing the test, everyone on the property must keep away from shock dangers. When buying a loop tester, ask for distribution board test leads so that you may do Z_e and Z_s measurements.

Value of Deflection

An electrical system that has been completed must go through earth fault loop impedance testing to make sure it conforms to BS 7671 (IET Wiring Rules) regarding fault prevention. This testing

is typically carried out as follows. Circuits that are only protected by fuses or circuit breakers, with a test current of approximately 23A, or circuits that are protected by 30mA or other RCDs, with a test current of about 15mA to prevent unintentional tripping. The test findings for high current (23A) testing generally have a resolution of 0.01 and vary from 0.1 to 1.0. They are also quite dependable. For low current (15mA) testing, the resolution was 0.1, but attempts to drop this to 0.01 have often failed to provide the same trustworthy for readings of less than 1.0.

In a recent examination, one of the leading instrument makers in the UK employed equipment from seven different manufacturers under controlled conditions and found significant variances in the instrument. Further investigation revealed that the low-test currents seemed to be the main cause of the problem, which was caused by variations in the quality of the power supply caused by changes in the amplitude of the voltage, transients, harmonics, etc. Similar tests using a stable power supply and a clean 50Hz waveform produced more reliable findings. However, it must be underlined that these variations, which are often on the scale of 1.0 or less, have little impact on how well an RCD performs.

When testing is finished, we will provide you a date for a follow-up earth loop impedance test that meets national standards. When it's time for the retest, a member of our team will notify you. Each client will get a comprehensive report outlining. In this report, your equipment will either get a pass or a failure grade. We'll keep a copy of this document on file in case you need to refer to it later to verify compliance. We provide clients with a wide range of inspection and testing services so that we may secure your whole business in a single visit. After you've had your impedance test, we could offer you extra inspection services. We provide such a wide variety of services, so there is no need for you to go elsewhere for your safety testing requirements.

You may confirm that your ground connection is adequate, low in residual resistance, and electrically safe using earth fault loop impedance testing. Testing the earth loop impedance is essential because, in the event that a live conductor were to accidentally connect to a defective device or circuit's earth conductor, the resulting short-circuit current to earth could easily be high enough to electric shock or produce enough heat to start a fire. There is a chance that the installation defect may in an insufficient amount of genuine short-circuit current, which will delay the activation of the protective system. Usually, the circuit protection mechanism will trip or the fuse will burst. Delays might have disastrous consequences for both lives and property. It is necessary to ascertain if the impedance of the path that any fault current would travel is low enough to allow adequate current to flow in the event of a failure in order to guarantee that any installed protective device would work within a safe time limit.

CONCLUSION

When a low impedance fault develops between the phase conductor and earth, fault current travels via the earth fault loop impedance. An earth fault loop impedance test ensures that there will be sufficient current to activate the fuse or circuit breaker protecting the defective circuit when an electrical fault occurs. The fault loop impedance between phase to neutral and phase to earth is measured using fault loop testers. Additionally, this equipment provides anticipated fault current so that a system's protective mechanism may be chosen.

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EXPLORING THE ROLE OF LOW VOLTAGE SWITCHGEAR

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ABSTRACT:

Low voltage switchgears are often housed and mainly function to safeguard, isolate, and regulate electrical circuits for commercial or industrial utilities when equipment is operated below 1 kV. Standard low voltage switchgear systems are challenged technically by arcing, which necessitates the use of upgraded protection methods to prevent arc faults and to guarantee a reduced arc fault time and incident energy. This study describes the construction of an internal arc protection system for low voltage switchgears that can recognize a pressure and light signal after the arc fault has ignited. By offering electrical protection against the mechanical and thermal strains of short circuit currents, low voltage switchgear, in general, plays a crucial function in electrical distribution systems. Circuit breakers, changeover switches, fuses, overload relays, and disconnectors are examples of LV switchgear components. Isolation, protection, and switching-based system modification are the basic tasks of LV switchgear in an electrical power system.

KEYWORDS: *Air Gap, Circuit Breaker, Voltage Switchgear, Short Circuit Current.*

INTRODUCTION

Circuit breakers, fuses, and switches also referred to as circuit protection devices are together referred to as electrical switchgear and are used to protect, control, and isolate electrical equipment. In metallic frames, the circuit protection equipment is placed. A collection of one or more of these structures is referred to as a "switchgear line-up" or "assembly". In medium- to large-sized commercial or industrial structures, as well as in the transmission and distribution networks of electric utility companies, switchgear is often found. Electrical switchgear standards are set in North America, the IEC in Europe, and other parts of the world [1]. Low-voltage metal-enclosed switchgear, a kind of three-phase power distribution device, is designed to provide electric power reliably, efficiently, and safely at voltages up to 1,000 volts and currents up to 6,000 amps. The typical ANSI/NEMA (American National Standards Institute, National Electrical Manufacturers Association) switchgear has a continuous current main bus rating of up to 10,000 amps (for providing power from parallel sources) and is capable of withstanding voltages up to 635 volts [2].

Low-voltage switchgear is often installed on the secondary (low-voltage) side of a power distribution transformer. This combination of switchgear and a transformer is known as a substation. Low-voltage switchgear is often used to provide different branch and feeder circuits, low-voltage motor control centers (LV-MCC), and low-voltage switchboards. In heavy industry, manufacturing, mining and metals, petrochemical, pulp and paper, utilities, water treatment,

datacenters, and healthcare, it is utilized to supply energy for important power and essential process applications. Typically, each breaker compartment may hold up to four power circuit breakers that are arranged vertically. Different compartments are used to divide up the power circuit breakers. Circuit breakers are segregated in the same way as the bus compartment, which is kept off from the circuit breaker compartment behind it by sturdy barriers[3].

There is an insulation-based barrier between the neighboring bus compartments. It is optional to use vented or unvented barriers to separate the cable compartment from the bus compartment, which is situated beneath the switchgear section. There are detachable covers or doors that open to show landing lugs for connecting line and load cables in the cable compartment. The most common compartment layout, which requires access to the switchgear enclosure's back, may be referred to as rear-accessible switchgear. Front-accessible switchgear, which has the cable compartment adjacent to the breaker compartment and the cable compartment doors on the front of the equipment, is a variation of this compartmentalization. With this arrangement, a switchboard-like design that doesn't need rear access and allows the switchgear to be installed up against a wall is created[4].

The extensive compartmentalization of low-voltage switchgear aims to increase the switchgear's safety, dependability, and serviceability by, for example, preventing unintentional contact with specific conductors during maintenance, such as the main bus or circuit breakers in nearby cells. Additionally, the compartmentalization may be able to limit some of the potential damage caused by an arcing fault and stop it from spreading to adjacent switchgear parts [5]. Power is sent to the low-voltage switchgear enclosure through a copper bus that has been silver- or tin-plated. A finger cluster that extends horizontally into the breaker cells in a switchgear section connects the feeder breakers' line sides to the breaker stabs. These vertical copper bus runs, often known as "risers," connect the two varieties of breakers. A horizontal (main) bus connects nearby switchgear components electrically.

By flowing back horizontally from the load side of each feeder breaker via the bus compartment (without connecting to the vertical or main bus), runbacks provide lug landings for terminating load wires. Between the three bus phases, a suitable air gap often offers insulation or dielectric strength. Bus insulation is utilized in places where the bus cannot retain the necessary dielectric strength due to inadequate clearances. Low-voltage switchgear is protected against overload and short circuits by low-voltage power circuit breakers (LV-PCB) with integrated trip units [6]. For low-voltage circuit breakers, these draw-out, through-the-door devices are often utilized. A circuit breaker's faceplate and any controls located on it may be accessed "through-the-door" without having to open the switchgear. The term "draw-out" describes a circuit breaker's capacity to be completely removed from the switchgear for maintenance as well as moved quickly into the test and disconnect positions without requiring the switchgear to be opened. Low-voltage circuit breakers prevent overload and short-circuit issues through primary contacts that separate outside. These circuit breakers are sometimes known as air circuit breakers (ACB) because they employ vacuum interrupters instead of medium-voltage circuit breakers, which typically use vacuum interrupters[7].

SCCR, or short-circuit current rating the short-circuit current rating (SCCR) is the maximum short-circuit current that a component or assembly may safely withstand while being protected by one or more specific overcurrent protection device(s) or for a defined amount of time[8]. Based on a fire and shock danger outside the enclosure, ratings for short-circuit current indicate

the maximum fault current that a component or piece of equipment may withstand safely. Without knowing the available fault current and short-circuit current rating, it is difficult to determine if components or equipment may be installed safely.

Each panel component has an SCCR, or interrupting rating, given to it. The component with the lowest SCCR limits the overall panel assembly rating for the panel assembly. This SCCR rating, which must be written on the nameplate, is normally determined by the control pane's maker or assembler. The future operating conditions of the switchgear (feeding transformer, type, and length of the cable network, change in conductor resistance due to temperature change, extra power to the grid, induced by motors, etc.) are often unknown to the manufacturer[9].The consultant or electrical design engineer is responsible for installing all industrial control panels such that their SCCR is greater than the system's available fault current. The manufacturer of industrial control panels is responsible for supplying the consulting engineer and authority with pertinent SCCR information using required labels and available technical information.

LITERATURE REVIEW

L. Wanget al. in [1], discussed that to ensure the security of the power system, low-voltage switchgear reliability study is crucial. Due to its capacity to fully use historical data, Bayes theory is a technique for dependability assessment that is often utilised. Therefore, when the Bayes technique is used to assess the reliability of the low-voltage switchgear, the accurate prior knowledge is essential to ensuring the accuracy of the reliability analysis findings. A workable prior information fusion approach was suggested and a trustworthy prior distribution function was constructed in order to acquire the prior knowledge of low-voltage switchgear with high reliability. First, several types of historical information and useful data were gathered from producers and consumers. The compatibility of the gathered historical data, the effective information, and the field information was then tested using the parametric and nonparametric test technique in order to get a more accurate prior distribution. Finally, the prior distribution and the expert experience were combined, leading to the construction of the conjugate prior distribution of reliable low-voltage switchgear, which provided the theoretical foundation for increasing the accuracy of the low-voltage switchgear reliability assessment.

Francoise Molitoret al. in [2], carried a research about thermal design of a low-voltage switchgear based on a laminated bus plate construction is described. The major objective was to give the scientific validation of the new bus plate idea. It was carried out within the framework of building a new generation of low voltage switchgear system. In order to comprehend the thermal behaviour of the various components of the system and to design and size the conductors, the effort included thermal network and finite element simulations. Temperature rise testing have validated the thermal performance.

MichałSzulborskiet al. in [3], discussed that Maxwell 3D, Transient Thermal, and Fluent CFD are three advanced coupled analyses that are presented in the text at the moment when a rated current occurs on the main busbars in the low-voltage switchgear. The simulations were bought to help with the design of these enclosures. The study provided the switchgear busbars' rated current flow, allowing measurement of their temperature values. The simulation's primary assumption was that observations of temperature increase under rated current settings would occur. Designing improved solutions for energy distribution equipment requires the use of simulations of these settings. The switchgear prototype's exact depiction was captured in the simulation model. Experimental study was used to verify the outcomes of simulations. It was

shown how heat was dissipated by air convection in the housing of switchgear and busbars. The temperature distribution for the halogen-free polyester insulators in the rail bridge was taken into consideration. The simulation's enabled a thorough examination of switchgear design and the drawing of appropriate conclusions from both theoretical and practical perspectives.

Sârbu et al. in [4], discussed that A number of domestic and foreign businesses make up the Turkish low voltage switchgear market. In order to compete with the competition that places a higher priority on quality, local businesses working in this sector often aim to gain a competitive edge by manufacturing low-cost goods. International firms also carry out excellent operations while being organised and governed by senior executives from elsewhere. Despite being a regional manufacturer, VIKO is one that is ready to spend more on quality as well as on R&D. The VIKO Company is the subject of this self-assessment study because it sits at the intersection of businesses that operate in this industry and because it is a local business that engages in a variety of quality-improving initiatives. The authors also believe that this research would be helpful in providing a comprehensive picture of the Turkish low voltage switchgear market. In order to determine the company's strengths, shortcomings, and areas that need development, the assessment of the business and its main operations was based on nine criteria from the EFQM Excellence Model. This research, which is the first of its kind to be conducted in the low-voltage switchgear industry, aims to inspire other Turkish businesses involved in the industry to adopt the excellence model of the european foundation for quality management.

Zhang et al. in [5], explored that the maximum entropy multisource information fusion approach was suggested to gain the prior knowledge of low-voltage switchgear and then assess the reliability while studying the reliability of low-voltage switchgear using the Bayesian method. Low-voltage switchgear historical data was gathered and organised from a manufacturer. The Smirnov test technique was used to give the creditability analysis and the compatibility test in accordance with the data and expert experience. The determination of previous information is the outcome of the maximum entropy multisource information fusion approach, based on the high creditability and compatibility. The maximum entropy approach was used to validate the distribution type of the prior information, and the bootstrap method using MATLAB was used to get the parameter of the prior information. The posterior distribution was then collected in order to assess the low-voltage switchgear's MTBF. In order to demonstrate the maximum entropy multisource information fusion approach and determine the MTBF of low-voltage switchgear, historical data from the years 2007 to 2010 were used as previous knowledge.

DISCUSSION

The capacity to utilise electricity in daily life is one of humanity's greatest blessings, but generating that power must be done securely. Maintaining the level of distribution's security through safety measures is quite difficult. Various tools are available to help protect electrical equipment and its connections in a range of scenarios, including industrial, home, etc. This is overcome by using a switchgear device because of its various features and capabilities. This device is intended to support weight distribution and carrying while maintaining electrical connections. Identifying the weaknesses and connections between failures helps in limiting damage.

Operation of switchgear

Maintaining the on/off condition of a device, such as a fuse, switch relay, or circuit breaker, is

one of the key functions of switchgear. Utilising tools like electrical generators, distributors, gearbox lines, etc. is made feasible by this. In the event of a short circuit in the power supply, a significant current will flow from the device. By employing it to spot a power system weakness and protect the machine or any other electrical equipment from damage, this problem is averted. This acts as a switch to shut off the power. If the control system has a part like a control panel transformer, let's talk about control. Circuitry that links current protection relays with power management components and controls, monitors, and secures those components.

Switchgear for Lower Voltages (LV)

Electrical systems that handle voltages up to 1KV are referred to as low voltage switchgear, or LV switchgear. The most typical products in this category are switches, LV circuit breakers, HRC fuses, earth leakage (EL) circuit breakers, unload electrical isolators, MCBs (miniature circuit breakers), and MCCBs (moulded case circuit breakers), among others.

Low-Voltage Switchgear (MV) MV designates a power system with a maximum 36 kV handling capacity. (Switchgear for medium voltage). They are available in a number of forms, such as indoor and outdoor kinds with metal enclosures, as well as outdoor versions with and without metal enclosures. This type of substation equipment includes products such as minimum oil CBs, bulk oil CBs, SF6 gas-insulated, air magnetic, gas-insulated, hoover, etc. Vacuum, SF, or oil may all disturb this kind of switchgear. When there are issues with the system's operation, this kind of power network must be able to stop the flow of electricity. This is used in a variety of unusual applications and has the ability to interrupt short circuit current, switch ON or OFF, switch capacitive current, and switch inductive current.

High voltage switchgear

When a power system can generate more than 36 kV, it is referred to as high voltage, or HV. When the voltage level is increased during the switching operation, arcing occurs. HV circuit breakers must thus possess a number of qualities to guarantee reliable and safe operation. The HV circuit seldom switches between processes. These CBs often remain in the ON state and may be utilised later. They must be reliable in order to provide secure operations when necessary. Its design must be carefully considered while making such a device. The main element of the gadget is high voltage. Indoor-type switchgear is only meant to be installed inside of buildings, such as residences, businesses, and factories, as well as other enclosed spaces. In these situations, the equipment is often placed in a special room known as a switchgear room. The main difference between indoor and outdoor switchgear is that the former is protected from the elements, while the latter is not and is vulnerable to wind, dust, rain, snow, and other weather conditions. In terms of indoor switchgear vs outdoor switchgear, the former offers a number of benefits due to its environment. It's important to understand the many types of indoor switchgear and what they all represent before discussing these advantages.

Main Types of Indoor Switchgear

There are several types of indoor switchgear made. They consist of switchgear with various design ranges, insulating materials, and variable voltage ratings. Indoor switchgear is often available in metal-clad or metal-enclosed styles. They have a variety of design features.

With Metal Enclosure Switchgear

The devices are located within the indoor switchgear that is totally covered in a metal sheet and

surrounded in metal. This protects both the switchgear hardware and people. To allow for component monitoring and inspection as well as ventilation openings, the enclosure is therefore often fitted with doors or removable covers.

Metal-Constructed Switchgear

The different parts of indoor metal-clad switchgear are kept in distinct compartments that are separated from one another by metal walls. These compartments are then earthed to ensure safety. The breaker chamber of metal-clad switchgear is often detachable.

Issues with indoor switchgear

Although indoor switchgear has numerous benefits, the biggest disadvantage is that installation costs are higher, according to the tower light suppliers in the UAE. The cost of installing the interior switchers is high, and the state of the economy has a big impact. The air-insulated system or the outdoor system are often the most cost-effective choices. However, there are a number of diesel generator suppliers in the UAE that give the most trustworthy and cost-effective solutions for interior switchgear. Indoor switchgear system arrangements are more trustworthy and safer than outside switchgear system configurations. Even if the cost can be higher, it is ultimately the better choice. It works well in any location and can withstand harsh weather conditions. Regarding indoor switchgear systems, it's crucial to consider both the high voltage levels and practical considerations. Rest certain that the indoor variation is effective.

A switchgear might be insulated by something else or it can be a straightforward open-air isolator switch. The gas-insulated switchgear (GIS), which insulates conductors and contacts with pressurised sulphur hexafluoride gas (SF₆), is a reliable but more expensive kind of switchgear. Switchgear that is vacuum or oil insulated are additional frequent kinds. They are able to stop fault currents of tens of thousands of amps thanks to the combination of devices within the switchgear enclosure. The main element that stops fault currents is a circuit breaker (located within a switchgear enclosure). It takes careful design to quench the arc when the circuit breaker pulls apart the contacts and disconnects the circuit. Circuit breakers may be divided into six categories.

Oil circuit breakers use the vaporisation of portion of the oil to shoot an oil jet in the direction of the arc. Hydrogen gas is the main component of the arcing's vapour. Air is less effective as an insulator than mineral oil. When current-carrying contacts in oil separate, an arc in the circuit breaker is initiated at the same time. This arc, the oil is vaporised and breaks down into mostly hydrogen gas, which eventually forms a hydrogen bubble around the electric arc. After the current reaches the cycle's zero crossing, the highly compressed gas bubble surrounding the turn prevents the arc from being struck again. One of the earliest varieties of circuit breakers is the oil circuit breaker.

The magnetic force of the arc itself or compressed air (puff) may be used by air circuit breakers to extend the arc. The extended arc will ultimately exhaust itself since the length of the sustainable arc depends on the voltage that is available. As an alternative, the arc may be extinguished by quickly swinging the contacts into a tiny, airtight container. Depending on the device's age and design, circuit breakers may normally stop all current flow in less than 30 to 150 milliseconds. When applying a magnetic field to extend the arc, Gas (SF₆) circuit breakers depend on the SF₆ gas's high dielectric strength to quench the stretched arc.

In order to create hybrid switchgear, classical air-insulated switchgear (AIS) and SF6 gas-insulated switchgear (GIS) technologies were combined. It is distinguished by a small and modular design that combines several functions into a single module. As there is just the contact material to ionise, vacuum circuit breakers with vacuum interrupters have low arcing characteristics, which causes the arc to quench when it is extended by a tiny distance (between 2 and 8 mm). The gap can tolerate the increase in voltage when the current stops because the arc is no longer hot enough to sustain a plasma near zero current. Modern medium-voltage switchgear is commonly equipped with vacuum circuit breakers up to 40,500 volts. They are fundamentally unsuited for interrupting DC faults, in contrast to the other varieties. Vacuum circuit breakers shouldn't be used to break high DC voltages since there is no "current zero" period with DC. The contact material may continue to gasify, allowing the plasma arc to sustain itself.

Dioxide of carbon

Similar to sulphur hexafluoride (SF6) breakers, those that employ carbon dioxide as the insulating and arc extinguishing medium operate on these same principles. Because SF6 is a more powerful greenhouse gas than CO₂, switching from SF6 to CO₂ throughout the life of the product may cut greenhouse gas emissions by 10 tonnes.

Fuses and circuit breakers

When current surpasses a certain safe level, circuit breakers and fuses cut off. They are unable to detect other severe failures, such as imbalanced currents, which might occur when a transformer winding makes contact with the ground, for instance. Circuit breakers and fuses by themselves are unable to discriminate between short circuits and excessive electrical demand.

Circulating current Merz-Price scheme

Kirchhoff's current law, which stipulates that the total current flowing into or out of a circuit node must be zero, is the foundation of differential protection. Any portion of a conductive channel may be thought of as a node when applying this approach to differential protection. Transmission lines, transformer windings, motor windings or the stator of an alternator might all be considered conductive paths. When the two endpoints of the conductive line are physically near to one another, this kind of protection works well. Charles Hester man Merz and Bernard Price created this plan in the United Kingdom. For each winding of a transformer, stator, or other device, two identical current transformers are utilised. The opposing ends of a winding are surrounded by the current transformers. The same current should flow through both ends. Any imbalance in current is detected by a protection relay, which trips circuit breakers to shut off the gadget. The circuit breakers on the main and secondary of a transformer would both open in this scenario.

Remote relay

Because the transmission line's impedance restricts the fault current, a short circuit at the end of a lengthy transmission line resembles a typical load. By measuring the voltage and current on the transmission line, a distance relay may identify a defect. A problem may be identified by a high current and a voltage drop.

CONCLUSION

A switchgear is made up of electrical disconnect switches, fuses, or circuit breakers that are used

in an electric power system to regulate, safeguard, and isolate electrical equipment. Switchgear is used to fix problems downstream as well as to de-energize equipment to allow for work. A vital part of several electrical distribution networks around the nation is low voltage switchgear. They are essential to the dependability, efficiency, and safety of the electric supply. Low-voltage power circuit breakers (LV-PCB) with integrated trip units are used in low-voltage switchgear to provide short-circuit and overload protection. These draw-out, through-the-door appliances are low-voltage circuit breakers.

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ANALYSIS OF MAXIMUM PERMISSIVE VOLTAGE DROP

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ABSTRACT:

A potential method to assess the worst-case voltage fluctuations without extensive knowledge of circuit activity is provided by vector less power grid verification. To acquire the worst-case voltage fluctuation throughout the grid, vector less verification is often necessary, which is very time-consuming for large-scale verification. For effective vector less verification, a maximum voltage drop location estimate technique is put forward in this study. The power grid nodes are divided into disjoint groups, and an estimating approach is used to approximately identify the nodes in each group that have the worst-case voltage drop. Compared to correct verification, the verification issue size may be greatly decreased. This chapter explores the analysis of maximum permissive voltage drop.

KEYWORDS: *Current Density, Current Flow, Power Loss, Voltage Drop.*

INTRODUCTION

These voltage-drop constraints only apply under normal steady-state operating conditions; they do not apply, for example, when a motor is beginning, many loads are switched at once (accidentally), diversity and utilisation factors, etc. When voltage dips exceed, the problem must be rectified by using larger cables (wires). A motor's beginning current may be between 5 and 7 times that of its full-load value, and steady-state voltage requirements for excellent motor performance generally vary from 5% to even more than that. At start-up, the voltage will drop by at least 40% if there is an 8% voltage loss at maximum load current. When this happens, the motor will either stall (i.e., remain still because there isn't enough torque to overcome the load torque) or it may finally trip out due to overheating.

Alternately, accelerate very slowly to extend the high current loading (and any low-voltage effects on other equipment) beyond the usual start-up period. Last but not least, a voltage drops of 8% indicates a persistent power loss, for continuous loads in a significant loss of (metered) energy. It is recommended against circuits that are prone to under-voltage problems exceeding the maximum value of 8% under steady operating conditions for these reasons. The National Electrical Code states that a 5% voltage drop at the furthest receptacle of a branch wiring circuit won't affect normal performance. This means that for a 120-volt 15-amp circuit, there should only be a 6-volt loss at the furthest outlet when the circuit is completely loaded. According to the NEC, the overall maximum voltage drop shouldn't be more than 5%, and the maximum voltage drop on either the feeder or branch circuit shouldn't be more than 3%. Every branch circuit carrying fragile electronic equipment is only permitted to endure a voltage drop of 1.5% of the supply voltage, under this NEC article. Instead, there should be no more than a 2.5% active

reactive power loss from the combined maximum voltage dips on the feeder and branch circuits that support fragile electronic equipment.

The allowable voltage drop is calculated as follows: voltage drop per 100 feet = $\frac{3}{4} = 0.75$ volts per 100 feet. When we divide 100 feet by 400 feet, we obtain $\frac{1}{4}$ times 3 volts, or 0.75 volts per 100 feet. Dr. Michael S. Morse, an electrical engineering professor at the University of San Diego, contends that although 10,000 volts may be fatal in certain circumstances, it is also possible for something to have 10,000 volts behind it and yet be rather safe. The copper's resistance (measured per foot) causes a voltage drop when a cable reaches 50 feet or more, which causes heat to build up. The heat buildup from the voltage drop may cause the cable to melt if it is longer than 50 feet, which would then spark an electrical fire.

LITERATURE REVIEW

SelahattinKucuket al.[1], explored that due to the demands of heavy application, electrical motors in contemporary industrial systems are becoming bigger. Even when compared to the whole load capacity of the industrial facility, certain electric motors are regarded as enormous. Electrical motors may be severely disrupted when they are started, together with other locally linked loads, buses, and other electrically distant loads. Prior to connecting a big motor to an industrial electrical system, it is ideal to conduct a motor starting study in order to implement the appropriate corrective measures as needed. The impact of electric motor parameters on the industrial power system is examined using static and dynamic analysis. The voltage drop that occurs across an industrial power system as a direct consequence of starting big motors is the most well-known and extensively researched motor starting effect. Using motor ratings and previously estimated short circuit power, this research examined the impact of voltage fluctuation on the power system and applied the voltage drop during motor starting to the industrial electrical system. Although there are many computer-aided motor starting studies, this research will be useful for people who need precise and straightforward voltage drop checks when starting a motor. It does this by utilising an accessible and available motor, a transformer, and computed short circuit power.

Khalil Benmouizaet al.[2], explored that fuel cells are machines that use electrochemical processes to transform hydrogen into electric power. Understanding the underlying dynamics of proton exchange membrane (PEM) fuel cells is crucial for maximising their efficiency. This work examines the analysis of the voltage drops caused by activation, ohmic, and mass transfer. Simulated effects of various operational parameters on the voltage-current density curve include the influence of temperature, electrolyte thickness, transfer coefficient, exchange current density, and cell usable area. The findings indicate that the voltage dips reduce the cell's voltage and efficiency. In high current densities, activation voltage drop lowers the voltage by around 0.2V, ohmic voltage drop by up to 0.8V, and mass transfer by about 1V. High pressures of hydrogen, oxygen, and water further increase the output power of the cell. Additionally, the temperature has an impact on the cell's performance, which is decreased under low operating temperature settings.

Djamel et al.[3], explored that in recent years and even in the near future, it has become increasingly crucial to integrate decentralised generation into medium voltage networks. This growth has a number of unfavourable implications on the network's stability at the same time, with very few exceptions. Because of this, this paper examines how ambient temperature affects several radial distribution network metrics, such as voltage drop and stability voltage level

(index). Different evaluations of the effects of distributed generation (DG) insertion on voltage drop in the radial distribution feeder and the impact of environmental factors like ambient temperature on network characteristics are based on the MATLAB programme. In particular in radial distribution feeder, the integration of photovoltaic DGs in MV networks may play a significant role in lowering the global warming impact. Furthermore, if its location and power source are carefully chosen, it safeguards the network's specifications.

Tae HoEom et al.[4], explored how to compensate for voltage drops in a hybrid hydrogen fuel cell battery system that powers a forklift with hydrogen recirculation. Impurities may mix with the hydrogen fuel while it is being circulated to recycle hydrogen that has not yet sufficiently reacted in the system. This in low hydrogen concentration and a decrease in the fuel cell system's output voltage. The fuel cell system may be shut off if there is a significant voltage drop. In order to avoid system shutdown, this study suggests a voltage drop compensation technique employing an electrical control algorithm. Technically, there are three different types of parameters that might affect voltage drop: (1) the quantity of pure hydrogen supply; (2) the temperature of the fuel cell stacks; and (3) the current density to the fuel cell's catalysts. By generating compensation signals for a controller of a DC-DC converter connected to the output of the fuel cell stack, the suggested compensation method identifies voltage drop induced by those variables and reduces output current, therefore reducing voltage drop. The batteries are now supplying a load with inadequate output current. In this study, the voltage drop brought on by the three elements described above is examined, and the workings of the suggested compensating mechanism are laid forth. Experiments are carried out by applying the proposed approach to a 10-kW hybrid fuel cell battery system for a forklift to confirm this operation and the viability of the suggested method.

Tack Hyunet al. [5], explored that low-voltage direct current (LVDC) systems are being studied more and more as more efficient electric power converters are developed. Voltage control techniques to account for the voltage drop and restrict the voltage imbalance are crucial for the deployment of LVDC distribution systems. The load current and the fluctuation in the quantity of power provided to the poles might generate a voltage drop and voltage imbalance in a bipolar LVDC distribution system. On the other hand, not enough study has been done on LVDC distribution system voltage control techniques. This work suggests a voltage control approach based on the neutral to line drop compensation (NLDC) method, which uses a modified LDC to determine the sending-end reference voltage, to lessen the voltage drop and the voltage imbalance. The neutral current and neutral line impedance are taken into account in the NLDC technique to account for the variation in neutral line potential and voltage drop on the pole. The voltage imbalance factor is checked to calculate the next sending-end voltage, which is then changed to keep it within the permitted range.

Zeng et al.[6], discussed that the common voltage-drop issue in pulse width modulation high step-up converters using a transformer-based voltage multiplier is precisely derived in this article. An isolated interleaved full-bridge high step-up converter is used as an example to illustrate the suggested and analysed solution. The enhanced converter addresses the voltage-drop issue brought on by the leaky inductor's reverse recovery process by including a resonant capacitor. In the meanwhile, the resonance between the leaking inductor and the resonant capacitor allows output diodes to attain the zero-current switching state. The suggested technique may also be used to other voltage-multiplier high step-up converters that use transformers or linked inductors. The operational principles and steady-state analysis of the upgraded converter

are examined after a thorough investigation of the voltage-drop issue. The correctness of the theoretical analysis is confirmed by experimental findings based on a 450-W laboratory prototype at a 25-kHz switching frequency.

HaoQiang et al.[7], suggested to use a single-phase full-bridge voltage-boost type non-voltage drop inverter linked to a switched capacitor structure. In order to manage the lead and break of the active switches, the pulse width modulation of a DSP controls the inverter's output voltage. While the other switches operate at high frequency, full-bridge switches operate at low frequency. To avoid a voltage, drop on the inverter's output side during the transition from series capacitor discharge to parallel charge, the inverter alternately charges and discharges two capacitor modules. The capacitor charge-discharge cycle may be altered to change the output voltage within a certain range by examining the charge-discharge characteristics of the RC charge-discharge circuit. The simulation findings are well-verified by the outcomes of the physical construction, showing good performance that backs up the aforementioned theory's verification.

Kim et al. [8], explored that the drawback of induction motors is that they produce a voltage drop upon starting from a high current. The voltage loss must be minimised within a specified range since it can negatively impact other loads. The voltage loss may be minimised by improving the beginning procedure, but the capacity and % impedance of the transformer is also crucial. Transformers' % impedance varies based on its voltage and capacity. The voltage drops and % impedance is connected. The percent impedance of a transformer increases with increasing capacity whereas decreasing capacity decreases the percent impedance. In this research, the transformer capacity was determined by taking the % impedance into account in order to keep the voltage drop while starting the induction motor directly within the permitted range.

Hasan et al., explored that the tunnel junction voltage loss was minimised in tunnel junction devices manufactured monolithically via metal organic chemical vapour deposition. An all-GaNhomojunction tunnel junction and a graded In GaNheterojunction-based tunnel junction were the two device architectures that were investigated. This research reveals a de-embedded tunnel junction voltage drop of 0.17 V at 100 A/cm², which is a record-low voltage drop in the graded-InGaNheterojunction-based tunnel junction device construction. The theoretical model was created by technology computer-aided design (TCAD) simulations, which provide a physics-based method to understanding the main elements of the design space and in a more effective tunnel junction. The experimental were compared with the theoretical model.

DISCUSSION

There is a constant resistance to current flow, or impedance, in wires carrying current. The amount of voltage lost across all or a portion of a circuit of impedance is known as voltage drop. A garden hose is a typical example used to demonstrate voltage, current, and voltage drop. Voltage is like the water pressure that is sent to the hose. The flow of current is like the flow of water through the hose. Much as an electrical wire's kind and size affect its resistance, the type and size of the hose affects its inherent resistance. An excessive voltage drop in a circuit may make heaters heat inefficiently, lights flicker or burn weakly, and motors operate hotter than usual and eventually fail. With less voltage forcing the current, the load must work harder under this circumstance.

According to the National Electrical Code, the voltage drop for electricity, heating, or lighting

should not exceed 3% of the circuit voltage from the breaker box to the furthest outlet. This is accomplished by choosing the appropriate wire size, which is described in further detail under A battery produces a voltage i.e., a difference in electric potential across its two terminals as it transforms chemical energy into electrical energy. A component known as a resistor produces a certain level of resistance to electric current. Electric current is the phrase used to describe the flow of charge carriers across a circuit when the two terminals of a resistor are connected to the two terminals of a battery.

Voltage expresses the capacity to move a charge from one place to another. For instance, a 5 V battery has a 5-joule work capacity per coulomb of charge. We may calculate the effort (per unit charge) necessary to maintain a current flow through a resistor while current is flowing through it. Here is how voltage drop works. A battery (or voltage source) provides the energy needed to move the charge. Components like resistors use energy as current flows through them, and the voltage drop of a component is the amount of work per unit charge that is linked with the current running through that component. A part of the voltage produced by the battery is offset by the voltage lost by a component. In other words, the circuit's components share in the work that the battery does. It goes without saying that it will take more effort to push a certain quantity of electricity through higher resistance. The resistor with higher resistance has a bigger voltage drop if two resistors are connected in series, which means they have the same current flowing through them. The voltage divider circuit functions on the basis of this.

A resistor is usually an energy-consuming component known as a load. The voltage drop across a resistor is positive where the current enters the resistor and negative when the current departs if we use the usual current flow paradigm, in which current flows from higher voltage to lower voltage. The source voltage is "opposed" by this polarity; if a battery were attached with the same polarity orientation, current would flow in the other direction. Since capacitors and inductors store energy, they may serve as a load or a source. They have the same voltage-drop polarity as a resistor when they are operating as loads. As a capacitor starts to discharge, the polarity of the voltage drop remains constant. Even though it is operating as a source, it generates current that flows in the opposite direction from the current used for charging. Nonetheless, an inductor makes an effort to keep the current flowing after it discharges. Since it is producing current that is flowing in the same direction as the charging current supplied by the source, the polarity of the inductor's voltage drops changes.

Drop in resistive DC voltage

The DC voltage drop may be calculated using Ohm's Law by multiplying the current by the resistance. Furthermore, according to Kirchhoff's circuit principles, the supply voltage is equal to the total of the voltage drops across all of the circuit's components in any DC circuit. Consider a direct-current circuit with a nine-volt DC supply, three 470-ohm, 100-ohm, and 67-ohm resistors connected in series, as well as a light bulb. The DC source, the conductors (wires), the resistors, and the light bulb (the load) all have resistance; each uses and wastes part of the energy given. How much energy depends on their physical qualities. For instance, a conductor's DC resistance is influenced by its length, cross-sectional area, type of material, and temperature.

The voltage potential at the first resistor will be little under nine volts if the voltage between the DC source and the first resistor (67 ohms) is measured. From the DC source to the first resistor, the current flows via the conductor (wire), but because of the conductor's resistance, part of the energy given is "lost" (not accessible to the load) during this process. A circuit's supply and

return wires both experience voltage loss. If the voltage drop across each resistor is measured, a significant number will be found. That is an illustration of the resistor's energy use. The voltage drop across a resistor increases with resistor size and consumes more energy.

Reactive decrease in AC voltage

Reactance is a second kind of resistance to current flow that also exists in AC voltages. Impedance is the total of resistance and reactance. Commonly, the variable Z is used to describe electrical impedance, which is quantified in ohms at a certain frequency. Electrical resistance, capacitive reactance, and inductive reactance are added together to form electrical impedance. The magnetic permeability of electrical conductors and electrically isolated parts (including surrounding elements), which varies with their size and spacing, affects the amount of impedance in an alternating-current circuit. This impedance is also dependent on the frequency of the alternating current. The equation $E = I Z$ may be used to define electrical impedance, which is similar to Ohm's law for direct-current circuits. In an AC circuit, the voltage drop is the of the circuit impedance and current.

ACSR Conductors made of aluminium

Because they must assure efficient and dependable transmission while also making a significant financial contribution to the line's overall expenditures, conductors are considered to be the most crucial part of an overhead power line. Selection of HV Conductors and Earth Wires (conductor types on picture include traditional ACSR and contemporary ACCC. Aluminium and its alloys have been the standard conducting material for power lines for a long time because of its affordable price, light weight, and need for certain minimum cross-sections. There are several various designs in use for aluminium conductors. The best conductivity for a given cross-section is found in all-aluminium conductors (AAC), however because to their limited mechanical strength, they can only be used for short spans and modest tensile stresses.

However, conductors made of a single material, such as those made of all aluminium or an aluminium alloy, have shown eolian vibration sensitivity. This drawback is avoided by composite conductors with a steel core, sometimes known as aluminium conductor, steel-reinforced (ACSR) conductors. An affordable alternative is a 6.0 or 7.7 aluminium to steel ratio. For lines erected in places with significant wind and ice loads, conductors with a ratio of 4.3 should be utilised. The conductivity is greater in conductors with a ratio of 7.7. However, since the sags are greater due to lesser conductor strength, larger towers are needed. The most significant factor determining the voltage drop, the energy losses along the line, and therefore the gearbox costs is the electric resistance caused by the conducting material and its cross-section. The cross-section must be chosen to ensure that the permitted temperatures are not exceeded during normal operation or in the event of a short circuit.

The line costs rise but the expenses for losses fall as the cross-section increases. A cross-section that in the lowest transmission costs may be established depending on the length of the line and the power to be carried. The conductor temperature is determined by the heat balance of ohmic losses and solar radiation against convection and radiation. In the majority of situations, a current density of 0.5 to 1.0 A/mm² depending on the aluminium cross-section has shown to be a cost-effective option. DC lines have a greater maximum surface voltage gradient than AC lines. It is advised to use a maximum value of 25 kV/cm. One of the key elements affecting the surface voltage gradient is the line voltage and conductor diameter. The conductor may be split into sub

conductors in order to maintain this gradient below the limit value.

CONCLUSION

This is the steady-state voltage drop for a typical load. Volts and amps both decrease of circuit restriction caused by corrosion, weak connections, or other sources of resistance. The maximum allowable voltage drop varies overall based on the installation type and situation. Depending on the kind of installation, the maximum voltage loss can be either 5% or 7% across the installation. According to the National Electrical Code, the voltage drop from the source to the utility shouldn't be greater than 3%. To the farthest connected load or outlet, the maximum combined voltage drops on both installed feeder conductors and branch circuit conductors shall not be greater than 5%. This chapter provides a detailed analysis of maximum permissive voltage drop.

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INVESTIGATING THE NECESSITIES FOR POWER SYSTEM PROTECTION

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ABSTRACT:

A crucial component of electrical power engineering is power system protection, which deals with shielding electrical power systems from problems by cutting off faulty components from the rest of the network. A protection scheme's goal is to maintain the power system stable by isolating only the faulty parts while keeping as much of the network operational as feasible. In conventional power systems, it becomes challenging to meet the protection needs due to changeable operating circumstances. Adaptive protection, which may adjust its parameter settings or operational features in reaction to changes in the power system, is one approach to solving this issue. Utilising such adaptive protection helps to fix the flaws in the conventional protection system, improving it and making it more dependable, sensitive, and quick. By carefully planning the electrical system and the protection systems, these qualities and functions may be attained. Therefore, the development of adaptive protection strategies is required due to the energetic structure of the power system and their various operating situations.

KEYWORDS: *Electrical Power, Power System, System Protection, Backup Protection.*

INTRODUCTION

The most significant recent developments have been made in modern power systems. WPM can provide a real-time picture of the dynamic behaviour of a power system that updates once every cycle because to the development of phasor measurement units and improvements in synchronised measuring technologies. This information has shown to be a practical tool for creating new applications that could improve the management and protection of the power system. Blackouts were later examined, and it was discovered that some of them were brought on by errors in the protective systems. The potential contribution of WPM to enhancing power system protection is of great interest.

Wide area measurements are not feasible due to the excessively quick primary protection reaction. Additionally, primary protection has a limited demand for large-area measurements since it only protects one part of the power system. Wide area measurements may be used to track the effectiveness of power system protection elements with laxer response time requirements (like backup protection) and less discriminating behaviour. Wide area measurements may also serve as the basis for the creation of distinctive system integrity protection strategies, adaptive system protection, or even completely novel protection concepts[1]–[3].

Wide area measurements by themselves are insufficient to realise the possible advantages.

Because of the introduction of digital relays, the substation now has access to previously unimaginable amounts of computer power, considerably extending the variety of duties that any protective system may be able to do. The new protection concepts discussed here are an extension of the better capabilities' higher intelligence and decision-making that is now taking place between the control centre and the substation.

In addition to having broad area measurements and more processing power, a suitable communication infrastructure must be available to support any wide area application. It's possible that different wrap concepts have quite different communication needs. Others may need measurements from several locations to be supplied at a rate of once per cycle (for example, intelligent controlled islanding), while others may just require binary signals to be broadcast at lower rates, such as monitoring of backup protection. Beyond only bandwidth, the communication infrastructure is subject to other pressures. Maintaining cyber security will be vital to avoiding malicious third parties from employing wrap as a weapon to attack the power system. A trustworthy, quick reaction time may necessitate minimum latency and jitter. Therefore, the design of any large area protection strategy should include a comprehensive evaluation of the communication needs.

The reason for this increase in relevance is the way that power systems are changing. The complexity and variety of transmission technology and control, the growing in feeds from neighbouring systems, the narrowing operating margins of economic constraints, and the expanding connectivity of power systems are the key contributing causes. Changing generation mix and demand side involvement (e.g., HVDC, thruster-controlled series compensation, increased interconnectivity), these three elements combined broaden the range of feasible operating situations. These advancements are making it more difficult to choose protection settings that would provide a suitable balance for all conceivable system circumstances and scenarios. Additionally, large-scale outages are more likely to occur in modern power networks. Wide-area disturbances need a coordinated, cross-system response that is tailored to the needs of the whole system, not a local response that is inconsistent, mistaken, and reliant on the local observations of each system.

At some point during the origination or advancement of 70% of wide-area disturbances, relay dysfunction was apparently a contributing element. These errors may be attributed to either incorrect relay settings or weaknesses in the covert protection mechanism. The role of relay maloperation in wide area disturbances must be taken as a significant source of concern because wide area disturbances have been a significant contributing factor in several recent blackouts and their management falls outside the purview of the majority of existing protection.

These factors have inspired the development of innovative, warmly endorsed protective concepts. Due to the multiplicity of challenges facing protection, these novel solutions range widely in complexity and ambition. Novel system integrity protection schemes (sips), adaptive system protection (such as adaptive under frequency load shedding), supervisory schemes that boost the security of current backup protection, and techniques that don't change how system protection behaves but do deepen our understanding of it are a few examples (e.g., alerting system operators to the risk of false relay characteristics penetration) are a few others.

AboutalebHaddadiet al. in, explored that when compared to conventional synchronous generators (SGs), inverter-based resources (IBRs) display distinct short-circuit characteristics. The efficacy of conventional protective relay systems designed on the premise of an SG-

dominated power system is thus anticipated to be impacted by the rising uptake of IBRs in the power system. To ensure the efficiency of system protection at increased levels of IBRs, protection engineers must research these issues and offer corrective solutions. In order to meet this need, this paper investigates the effects of IBRs on a range of protective relay schemes, including line distance protection, memory-polarized zero sequence directional protective relay element, negative sequence quantities-based protection, line current differential protection, phase comparison protection, rate-of-change-of-frequency, and power swing detection. Potential disoperation situations are identified for each protective function, and suggestions are made to resolve the problem. As a first step in creating future corrective measures to provide effective protection under large shares of IBRs, the goal is to offer a better understanding of how IBRs may adversely influence the performance of conventional protection schemes.

Xinlong Zhenget al. in, explored that submarine cable burying depth is crucial for preventing damage from anchors being dropped on or dragged along the line. This research concentrated on the real technical requirements for laying and protecting underwater power cables. In this work, numerical simulations, theoretical analysis, and physical model testing were carried out to look into the buried depth protection index of submarine cable. We analysed and looked at how anchor mass, falling energy, and bottoming velocity affected the depth of the anchor penetration. To analyse the forces and energy acting on the anchor, an analytical model based on the impact and drag mechanism is provided. The theoretical analysis and numerical simulation confirm the correctness and dependability of the model test findings, suggesting that the buried depth protection index of the submarine cable in the research region is advised to be 3 m. The findings of the study may serve as guidelines for the safety and operation of underwater cables.

Muhammad RameezJaved et al. in, explored that for utilities, the production and transmission of energy must be safe and dependable. This necessitates the use of protective devices like relays in the power systems. Recent studies have shown that conventional relays are unable to give power systems the protection they need, which has led to the development of various artificial intelligence (AI) techniques, including (i) artificial neural networks (ANN), (ii) adaptive neuro fuzzy interface systems (ANFIS), and (iii) fuzzy logic-based relays. This paper proposes a protection strategy for transmission lines that compares the performance of several AI-based distance relays to a traditional numerical distance relay (NL). By creating a test model in the MATLAB/Simulink environment and comparing "response time" against the identical fault occurrence for all relays, the comparative analysis has been carried out. In terms of reaction time and accuracy level against the defects, the comparative study revealed that AI-based relays beat traditional relays.

NavidBayati et al. in, explored that due to the advancement of DC loads and increased efficiency of DC systems, a direct current (DC) microgrid has recently emerged as a more effective power system. Protection is one of the difficult operational issues with DC microgrids, and because of its peculiarities and the absence of standards in DC protection, it continues to be a particular source of worry. This paper examines protection issues and strategies that must be addressed in contemporary power systems using DC microgrids in light of the steadily growing interest in DC microgrids. This paper examines and provides a thorough analysis of the most current development in the protection of DC microgrids. Additionally, the discussion covers the fault characteristics of DC microgrids, the effect of steady power demands, protection devices, and several suggested solutions to the protection issues. Also mentioned are the variations among the suggested DC microgrid protection strategies[4]–[6].

Michael Stadler et al. in, discussed that with the potential to boost local dependability, lower costs, and raise penetration rates for distributed renewable energy, micro grids are a typical component of changing power networks. Micro grids' added complexity often in higher investment costs, which poses a hurdle to their wider implementation. These expenses may be directly attributable to unique requirements for islanding detection, protection systems, and power quality assurance that may have been avoided in more straight forward system setups. Micro grids provide alternative revenue streams, nevertheless, which may offset their higher costs and boost the deployment of these systems' economic feasibility. In order to help counterbalance the higher investment costs, this report assesses the literature presently in print on studies pertinent to value streams that occur in micro grids. Additionally, an overview of studies on certain micro grid needs is provided.

DISCUSSION

Anybody who happens to be close when an electric arc form might be instantaneously and badly burned. In this case, incorrect switchgear operation is often the cause of arc occurrences. Arc flashes cause flames to spread fast, causing secondary damage from smoke and discoloration in addition to the direct destruction that they do. People who reside near a burning electrical device are more susceptible to the fire gases that the device releases.

Time-dependent equipment fault susceptibility

Equipment used in distribution networks often has a long useful life. In order to achieve their financial goals, industrial and network enterprises try to extend the equipment's operational lifetime. Although electrical equipment has a lengthy lifespan, both its operational environment and the customers it serves are constantly evolving. The rules and regulations may change during the course of the equipment's operating life. For example, a switchgear system that was originally intended to provide a small population centre with a limited quantity of power may later need to supply power to a shopping complex that serves thousands of people each day. It's conceivable that the switchgear system's role has grown in significance. Such power outages might cause the users to suffer large financial losses. The demand on the switchgear has grown, thus a second power transformer has been built in tandem with the first one. Under situations of heavy load, the transformers may be run in parallel, which further boosts the short circuit power. Both the arc fault's energy and the potential damage it may do are rising simultaneously.

Hardware maintenance challenges

In power systems, the essential system hardware often needs minimal maintenance. Equipment maintenance intervals may sometimes be rather long. Furthermore, it is seldom essential to undertake local control of components like breakers and switches. Under these circumstances, the employees won't acquire the necessary competence to work with power system components. The employees will be more prone to mistakes while executing maintenance activities and fault-finding processes because of their inexperience. Unintentional arc faults are more likely to occur when the utility's work crew changes. When the current maintenance staff of the network firms approaches retirement age, the new workforce's local level familiarity with the network systems decreases. The hazards of human error are increased by the necessity that network companies subcontract maintenance jobs. With time, the devices' functional conditions worsen. The equipment is exposed to dust, moisture, temperature changes, and rodents due to the ageing and degradation of protective structures and further outfitting. High loads and stress factors may

loosen joints and cause bushings to deteriorate, which has an impact on the switchgear system's quality as well.

Risk evaluation

When deciding on the optimal arc fault prevention system, starting with is a wise move since it takes into account both the potential effect of an arc fault and the possibility that one would occur. The quantity and kind of spending necessary to increase the reliability of the power distribution as well as the safety and security of the power system may be determined through risk analyses. When choosing an arc fault prevention solution for an existing switchgear system, consideration must be given to how long it is expected to last. There are two other strategies available. The working life of the switchgear system may be increased by additional spending; alternatively, the whole switchgear system may be replaced. Arc failures have a relatively low chance of causing harm to modern switchgear systems. However, for technical and assembly reasons, it could be wise to provide the switchgear panel with a system-wide monitoring solution that will support the switchgear system over its entire working life. Contact your local product or service sales to perform a risk assessment for an arc incidence in your power system installation.

Systems for protecting electrical power systems

The electric power grid has received significant investment. As we work to find more reliable power, the need for electricity preservation becomes increasingly pressing. Protection is essential to avoid any equipment or worker harm caused by an electrical imbalance or fault condition. Continue reading to learn more about the objectives of power system protection, different types of protective systems, and strategies used to guarantee complete safety for an electrical power system. Protection mechanisms accomplish their purpose by preventing a malfunctioning portion of the system from interfering with the operation of the remainder of the system. The goal of a protection system, as its name suggests, is not to prevent issues; rather, because it only acts after a problem has already happened, it minimises repair costs as it identifies flaws.

Protection zones in the electrical system

Every defence tactic defends a certain area known as a protective zone. A safety zone encircles each piece of electrical equipment. When a problem occurs in any of the zones, just the circuit breaker in that zone trips. The remainder of the system is unaffected and just the malfunctioning component is disconnected. Since a system may support up to six distinct types of protective zones, we employ the concept of selective coordination in this situation.

1. Generator-transformer units, which are used in power plants.
2. Transmission, sub-transmission, and distribution lines for transformers
3. Buses
4. Using tools (such as motors, static loads, or others).
5. Reactor or capacitor banks that have independent protection.
6. Fuse

The self-destructive device is known as fuse. It makes a sacrifice by blowing itself up under peculiar conditions while continually moving the electricity via a power circuit. They are independent protection components in an electrical system, as opposed to a circuit breaker,

which is dependent on other parts at all times. Transformer for instruments accurate protection cannot be offered without a precise assessment of a system's normal and abnormal conditions. Instrument transformers function as a transducer in electrical systems. Measurements of voltage and current provide details about how a system is functioning. Voltage and current transformers are used to measure these essential properties.

The current transformer has two responsibilities. Second, it lowers the current to levels that are easily controlled by the relay current coil. Second, there is an isolation between the relay circuitry and the high voltage of the high voltage system. A primary is connected in series to the line where current will be measured. The voltage transformer lowers the high voltage of the line to a level that is safe for both employees and the pressure coil of the relaying system to handle. An additional primary is connected in parallel if a measurement is necessary.

Relay

Relays serve as sensors, and since they are able to detect when a malfunction has occurred, they are referred to be the brains of power systems. In order to isolate the circuits, they are acting on, relays function by continuously monitoring voltage and current measurements, converting them into digital and/or analogue signals, and then opening the troublesome circuits. When an anomaly is found, the relays normally serve two purposes: to trip and to notify. In previous years, the relays' capacities and dimensions were severely regulated. However, relays today keep track of a wide range of elements thanks to developments in digital technology, giving the whole history of a system. Take a look at the fundamentals of power system protection. The topic of "types of protective relays & design requirements" was briefly discussed in this course. We started out by giving a general overview of how a relay, which is based on a protective system, is built and functions. The discussion of the factors to consider while developing a relay-based protection plan then went on. Then, we covered reverse power flow relays, directional relays, distance or impedance relays, and overcurrent relays in more detail.

A switch that is electrically driven and capable of safely opening and closing circuits is a circuit breaker. The circuit breaker is driven by the accompanying relay's output. While the circuit breaker is in the closed condition, the contacts are kept closed by the closure spring's tension. A latch is released when the trip coil is triggered, releasing the closing spring's accumulated energy and allowing the door to open swiftly. Opening faulty circuits takes some time; fault currents may be carried by the circuit breakers used to separate the circuits until the fault currents are cleared. Circuit breakers may be classed based on a variety of design elements, including the arc quenching medium, working mechanisms, voltage levels, etc.

A surge protector is a device that lowers voltage spikes and protects electrical equipment. This gadget tries to limit the supply voltage to an electrical equipment by making sure that it remains below a safe level. Every protective system that makes considerable use of the aforementioned components must carefully analyse and choose them in order to function at their best.

Overcurrent protection system

An over-current protection technique is the most obvious kind of protection since it may detect a sharp rise in current magnitude that is assumed to be a fault effect. However, the amount of fault current depends on the kind of issue and the source impedance. The source impedance fluctuates throughout time depending on the number of producing units that are running at any one time. From fault to fault, there are variations in the over-current protection's working time as well as

the set point for dividing the amount of fault current from the normal current. Protection engineers are increasingly taking additional principles into account[7]–[10].

Scheme for varying levels of protection

Differential protection is based on the idea that the current entering and leaving a protected area must be equal. If there is a difference between the two ends of a single segment, there is a fault. We may compare the phase, magnitude, or all of the two currents. This method of fault discovery is particularly popular if the two ends of a device are physically close to one another. It should remain steady and only trip if an internal issue arises in the case of an external fault or via a fault that is outside of its protective zone. The stability of this protection depends on its ability to differentiate between internal and external defects. But since a transmission line's ends are so far apart, it is impracticable to utilise this method because it is difficult to equalise the information.

CONCLUSION

Protection mechanisms serve their goal by separating a defective area from the rest of the functioning system, enabling it to function without interruption. As its name suggests, a protection system's purpose is not to avoid failures; rather, because it only responds after a fault has already occurred, it minimises repair costs as it detects errors. The basic goal of power system protection is to keep the operating power system reliable. To prevent equipment and workers from being damaged in any way by an electrical unbalance or fault state, protection is crucial. There is a maximum voltage or amperage for each electrical circuit. In the event that this value is surpassed, the wire will overheat, the insulation on the wire will melt, and a fire will start. A protection scheme's goal is to maintain the power system stable by isolating just the faulty parts while keeping as much of the network operational as feasible. Protection devices are those that are used to safeguard power systems from errors.

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ROLE OF VOLTAGE CONTROLLER IN ELECTRICAL POWER SYSTEMS

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ABSTRACT:

Various facilities are employed to improve the voltage control in the electric power transmission system. Automatic voltage regulators are included into generators to handle erratic and rapid voltage variations brought on by load fluctuations or malfunctions in the natural world. On the network put additional devices like capacitors, inductors, and transformers with on-load tap changers. Electricity utilities are becoming more and more interested in comprehensive and coherent control systems, whether automated or not, of the growth of the network and operational circumstances. In the event of increased voltage and VAr changes, these systems are anticipated to coordinate the activities of local facilities for better voltage management (more steady and quick response) within various network locations. They allow for better utilisation of already available reactive resources. Additionally, installing new equipment might be avoided to save money.

KEYWORDS: *Power System, Voltage Control, Reactive Power, Voltage Regulation, Transmission Line.*

INTRODUCTION

The majority of the power system's conventional voltage control is composed of the primary, secondary, and tertiary levels of voltage management. An on-load synchronous motor, static voltage regulator (AVR), static voltage generator, static var compensator, and a static voltage generator are all components of the reactive voltage control device that serves as the primary voltage controller. A tap switch, etc. A multi-objective gravity search technique was created, and the dynamic performance of each type was evaluated, in order to determine the producing costs of two wind turbines with permanent magnet synchronous generators and doubly fed induction generators[1].

Using a selfish group optimisation technique, we improved the frequency and voltage regulation of isolated multi-source hybrid micro grids and looked at the system management under five different harsh Scenarios the usual proportional-integral-derivative approach is then utilised (PID). When combined with a number of algorithms, a controller may enhance the AVR's capacity to regulate itself and provide dependable voltage output. An innovative time-domain performance criteria cuckoo search approach for automated voltage regulator (AVR) PID controller parameter tuning was proposed after investigating its anti-interference and robust performance[2]

The analysis of the anti-interference and resilient performance of the PID controller based on this

technique has shown that it has a favourable effect on tuning optimisation. Utilising the water wave optimisation approach, the optimal PID controller of the automated voltage regulator system was developed in order to boost the step responsiveness of the AVR system with increased efficiency and durability[3]. The most accurate power loss research, by employed polarity reversal technology to evaluate the restoration capabilities of PID. This an improved renal excitation algorithm-based unique approach of target function changing the design of PID controller. Nevertheless, the voltage controller's PID settings must be reset whenever system parameters are changed and modified. This kind of control voltage regulation in the power system reduces the controller's operational efficiency[4].

The traditional secondary voltage regulation and tertiary voltage regulation are two different power system optimisation techniques. Because the voltage management of these two stages is often insufficient, the corrective effect is insufficient. The dynamic power system process may employ reinforcement learning to overcome the tension between operational effectiveness and control performance. A Grid-Mind is an autonomous control framework for the reliable operation of the electrical grid. Modern artificial intelligence technology is the foundation of it. The link between deep deterministic policy gradient, deep Q-network simulation at a large scale, and the actual power grid environment is shown in this research.

A closed-loop control with simply a data disc and no model serves as the study's agent. The PID controller provides a specific system model for simulation and acts as the data source for the emotional deep-learning programming controller proposed in this work. To enhance the control strategy of autonomous voltage and to boost its learning capacity, deep neural networks (DNNs) and emotional components are incorporated to the Q-learning algorithm. Deep learning and other technologies are now being combined by researchers in an effort to improve scalability, intelligence, incentive mechanisms, and agent decision-making in real-world challenges. Batch reinforcement learning is a method that effectively lowers the voltage deviation of the entire system. The authors proposed a single-user power consumption forecasting system based on recursive graphs and deep learning to accurately anticipate short- or medium-term demand.

Large volumes of data may be used to prolong the reinforcement learning algorithm's training time. To solve the problems caused by random interference and to improve the utilisation of new energy, a win-or-learn fast strategy climbing network based on strategy dynamics was proposed. This article provides some prior knowledge to aid the agent in learning more rapidly during the early phases of the algorithm. Once the matrix dimension was achieved, further data could not improve reinforcement learning's performance as one of the established machine approaches. This study proposes an emotional deep neural network (EDNN) with significant nonlinear mapping capabilities to improve the accuracy of voltage control. The number of training layers and neurons in each layer may have an effect on how well DNNs are trained. It is challenging to completely and accurately capture the features of the input since too many layers and neurons may impede training while too few may reduce learning accuracy.

In order to decrease the influence of the amount of training layers and neurons on system control, the Q-learning algorithm with fake emotion was developed. We introduced a Q-learning method based on the nearest sequence memory in order to enable online learning and attack to manage the normal behaviour of power systems. Studied significant applications and current research trends using the Q-learning approach. In other words, the agent consists of two parts: a logical part and an emotional one. They all collaborate, with the emotional element operating on the

output action, to ensure the output of the minimal voltage regulation instructions. Emotional decision-making is used to change the agent's experience-based knowledge acquisition in order to counter the ineffective learning caused by the limited trial and error procedures. In the current context, this quickens the agent's convergence rate.

For the emotional deep learning programming controller (EDLPC), which makes use of several neural layers to lessen voltage variance in the power system, an EDNN is developed in this work. The DNN and Q-learning methods both have drawbacks when building a control plan. If the DNN is too small (underfitting) in contrast to the training set, the rule model cannot sufficiently match the data and cannot capture the characteristics of the data. If the DNN is too large (overfitting), it will remember far too many rules. Since it is too specialised and rigid to remember the training set, it could not be adaptable enough to correct the system's possibly aberrant data.

With the integration of a Q-learning algorithm, it may flexibly finish formulating the action in accordance with the reward state and environment state. However, the Q-learning approach could not always guarantee that all pairs of States and actions are investigated. Due to this flaw, the reward matrix was modified to incorporate the emotional factors to assist in choosing actions that were more appropriate. Since a PID controller makes data collecting simpler, it is used in this research as the source of simulation data. The disadvantage of this technology is that it requires more training time than PID controllers and other direct online control systems since actual data must be obtained prior to online control. In the step wave experiment, EDLPC has less of an influence on voltage deviation control.

Control performance is improved by the control framework. The EDLPC created in this research is built on the Q-learning algorithm and deep neural networks. The genetic algorithm is used to decide the PID controller's settings while the PID controller generates the training set. The DNN and Q-learning techniques are used to control the voltage of power systems, however they have several issues that cannot be resolved by simply combining them. We combine the two aforementioned algorithms and separately add the "emotion" component to each one in order to fix this problem. This improves the efficiency and precision of the control algorithm. The experiment show that the emotional component may greatly increase the algorithm's capacity for exerting control.

LITERATURE REVIEW

Giuseppe Fusco et al. [5], outlines a methodical design process for self-tuning regulators using shunt power electronic devices (SPEDs) to manage nodal voltage waveforms in electrical power networks. Three key tasks make up the framework of the suggested method. In the first, a Kalman filtering approach is used to estimate the voltage and current phasors at fundamental and harmonic frequencies beginning from sampled measurements of the nodal voltage and of the current, which are injected into the power system by the SPED. The second job uses these estimations to identify the parameters of the Thevenin equivalent circuits, which represent the electrical power system at each phasor frequency, online. The closed-loop voltage regulator is modified in the third job to meet the design specifications specified in terms of the required closed-loop pole placements. The suggested method has been used to develop a self-tuning regulator for the regulation of an active filter (the SPED) in an IEEE-test industrial electrical system after presenting the algorithms and the design requirements connected to each of the aforementioned tasks. The precise numerical simulations that were conducted indicate the

viability of the suggested strategy[6].

JoabeChavesNogueira et al.[7], explored to implement corrective voltage management measures for electrical power systems operating in an unsafe manner, or when voltage limitations have been breached, this article compares the use of optimum load flow and decision tree methodologies. In order to perform control measures that are more successfully employed to remove the voltage restrictions violation in each instance of contingency analysed, the decision tree approach is used in combination with a technique of sensitivity analysis. The control actions proposed by the decision tree and the best load flow strategy for the same operating situation are compared, and the success of applying these actions in a real power system is discussed. The demonstrated the practical use of both techniques in power system monitoring and control centres.

Ayodeji Stephen Akinyemiet al. [8], explored that renewable distributed generation (RDG) is increasingly being included into power systems, and this has both good and negative effects. With the incorporation of RDGs into a power system, the incidence of undervoltage at the far end of a traditional electrical distribution network (DN) may no longer be of concern. RDG penetration into the power grid, however, might in issues like voltage surge or over-voltage and reversal of power flows at the Point of Common Coupling (PCC) between RDG and DN. This study examines the effects of the voltage rise effect and the restriction on reverse power flow in a power system with a significant amount of RDG. The most crucial situation, such as low power demand in DN and a high-power injection by RDG, is taken into consideration while conducting the study on a sample DN, or IEEE 13-bus test system, with RDG penetration. A DN integrated RDG mathematical model is built to examine the effects of voltage increase and reverse power flow. Additionally, it is suggested that a controller with an advanced control algorithm be placed at PCC between DN and RDG in order to minimise the voltage rise effects and to limit the reverse power flow while operating under the worst-case scenario of maximum RDG production and minimal load.

Fei Gao et al. [9], explored that the examination of a single DC bus multi-generator electrical power system (EPS) for upcoming more electric aircraft is the main topic of this article. The work presents a stability analysis based on the derivation of the output impedance of the source subsystem and input impedance of the load subsystem, including control dynamics, within such a single bus paradigm. It also suggests a complete control design technique within such a single bus paradigm. When delivering continuous power loads, the stability characteristics of the EPS are examined, and the single bus characteristic is analysed. The report also emphasises the effect of the power sharing ratio and the number of parallel sources on stability. Using the theoretical analysis, an ideal single DC bus EPS may be created.

DaivaStanelytė et al.[10], explored that the transition and evolution of conventional energy systems are being accelerated by the quick development of renewable energy sources and power storage technologies. To offer increased dependability and flexibility, it is intended to integrate the various energy networks inside and across nations. To get there, however, one must overcome obstacles including the complexity of the power grid, system management, voltage fluctuations brought on by reverse power flow, equipment overloads, resonance, erroneous island configuration, and a wide range of user demands. In order to facilitate real-time information exchange between the generator and the customer, the power grid digitalization in the market also necessitates the installation of smart devices. Grid voltage may be managed

using distributed generation (DG) powered by inverters. Only technological limitations on smart PV inverters prevent them from providing both inductive and capacitive reactive power to regulate the voltage at the point of connecting with the grid. Reactive power control is a technical-economic issue that has to do with guaranteeing the quality of voltage in the energy distribution network and correcting reactive power flows.

DISCUSSION

Everyone on the planet must now utilise electricity. AC transmission systems were created for easier power transfer, more efficiency, and more control over energy than DC transmission systems. The high cost, lack of a DC transformer to increase the voltage, and absence of a DC circuit breaker for DC equipment are the key barriers to the transmission of DC electricity. Voltage and frequency must be maintained in AC transmission systems in order to guarantee the reliability and security of the efficient operation and management of power systems. When managing and controlling power systems, the total generation must always match the total load demand while accounting for transmission line losses. The operating points of the power system differ in respect to highly dynamic loads. The frequency, voltage, and power transfer capabilities to another part of the power system will thus be affected by unwanted power system operations. Depending on the load demand and the stability of the power system, the regulation of the generators' excitation affects the amount of power produced.

By controlling voltage and current, the generator's field winding, also known as the exciter, keeps the generator's output in line with load demand. The exciter is regulated and controlled by the automated voltage regulator. Power Ampere a reactive compensation technique used with increased reactive power improves network voltage stability and power system efficiency. By maintaining a healthy voltage profile, improving gearbox effectiveness, improving power factor, and improving power system stability, reactive power management improves power quality. Series and shunt VAR compensators have been put on transmission lines to boost the capacity of the power system network for load transfer. Series compensation changes the relevant power system load impedance, while shunt compensation changes the reactance of the transmission line net. Work The effectiveness of both compensation systems was shown in their ability to increase reactive power in the network and the overall effectiveness of the power system network. Delivering adequate electricity to meet demand is the main objective of the power system's operations. This is achieved by providing suitable reactive power compensation, ensuring the smooth operation of the power system, and employing AVR to maintain voltage and frequency.

Power transmission across lines may now be done quickly and efficiently thanks to innovative power electrical equipment development. Dynamic Alternating New gearbox innovations increase the capacity of gearbox lines while enhancing thermal and electrical system stable limits. FACTS technology makes it feasible to expand the capacity of both the upgraded gearbox systems and the existing gearbox lines, opening up new avenues for better power system management and operation. Over the last few decades, FACTS technology has been included into the power system network for the goals of efficient energy use, better demand side management, strong voltage stability constraints, improved power quality, greater power factor, and harmonic abatement.

Additionally, FACTS devices enhance voltage management, boost power conditioning and quality, more effectively account for reactive power, offer higher steady-state stability, and lower gearbox loss. Despite the massive increase in power use, there is a paucity of resources and

infrastructure. The current transmission line systems are used at their maximum temperature and load capacity during times of high load. The infrastructure and resources of the power system network cannot significantly increase due to political, environmental, regulatory, and social constraints. The FACTS controller provides intricate and sophisticated control of power system transmission lines. FACTS devices make it feasible for better power flow, increased load transfer capacity for new transmission lines, and enhanced performance of the existing transmission lines itself. For the operation and management of power systems, solid-state devices provide the fast response requirements of conventional transmission networks. Solid-state equipment substitutes conventional equipment when limiting power systems, increasing the effectiveness of power system operations.

One of the main duties of the voltage regulator is to increase the stability of the electrical transmission system. An improvement in the stability of the power system indicates an increase in the maximum power transfer capacity for the existing power system network. Due to the involvement of the TCSC, the network admittance fluctuation is substantial, which affects system stability. The use of FACTS and TCSC has improved the grid's user side overall, which boosts the grid's transmission capacity. These advantages include greater load sharing with parallel transmission lines, improved voltage management, higher injection of reactive power, less transmission losses, and others. The TCSC and a number of connected FACTS devices are used to improve power flow with less losses and to increase stability margin there are several compensatory ranges available with these devices. Additionally, they limit the fault current, which supports the network security system. The TCSC always acts in the capacitance region when there is no difficulty, but when there is a problem, it operates in the inductive region.

This paper outlines the use of a thyristor control series capacitor (TCSC) and an auxiliary control system to improve the voltage profile and execute reactive control depending on system performance. The speed deviation Dx serves as the input control signal. TCSCs with auxiliary controls are used for rotor relative motion transients. It is evident that the network voltage profile and system performance have been enhanced by the TCSC, with auxiliary control, in case of abnormal operation scenarios. A two-area technique is used to evaluate the offered strategy's potential. Simulated from a range of operational situations demonstrate how well the proposed strategy improves the system's post-fault conditions and reduces system oscillations.

The field voltage in static excitation systems is created by swiftly rectifying the main synchronous generator's output voltage. The generator in these systems is mainly self-excited, despite station batteries being briefly employed to create some starting voltage. When a change in reactive power is required, an operator may slowly alter the reference value while a regulator maintains the voltage close to the reference value. Usually, the voltage at the generator terminals is controlled by an exciter. In a typical excitation system, the reference voltage is altered by limiting signals to keep the generator within its reactive power capabilities.

Controlling power flow for TCSC requires identifying overcrowded parallel channels in order to reroute power flow to the TCSC compensated line. As a consequence, the current of the parallel tie line is measured. If the current magnitude in the parallel tie line exceeds the permissible value due to the thermal limit, increase the power (or current flow) in the TCSC compensated line by increasing the capacitive reactance of the TCSC. Given that its effective impedance has been reduced, the TCSC-adjusted line will receive a larger proportion of the total power flowing between the two sites. The current limit of the tie line, which is parallel to the TCSC

compensated line, is referred to as a feedback control system that is capable of performing this Limit.

A TCSC's lowest and maximum regulated reactances in the capacitive domain are denoted by the letters X_{max} and X_{min} , respectively. The integrator's minimum and maximum values are 0 and X_{max} . This suggests that if the integrator's output beyond these boundaries, integration is terminated and only resumes if the integrator's input has a sign that guarantees that further integration will bring the output back within the range of 0 to X_{max} . The current exceeds the limit I_{Limit} , the controller's output will increase the value of TCSC reactance over its intended value. Instead, if the limit is not exceeded by TCSC, the integrator output will settle to its lower limit, which is zero.

Improved auxiliary control for angular stability: One might use a TCSC's quick response capability to lessen the relative angular deviations between the aftershocks of the two zones in order to halt the transient angular oscillations. To put it another way, we want to speed the system's transition to a steady state while also preventing any possible loss of synchronisation. If the angle between the voltage phase at the area 1 end of the transmission tie lines and the area 2 end widens, increasing the electrical power flow from area 1 to area 2, this would be a simple, straightforward control approach. The greater electrical power transmission between the two parts decreases the relative movement of the generator rotors in one region compared to the other when angular deviation increases. To enhance power flow, the TCSC's capacitive reactance may be increased according to the angular difference.

Keep in mind that the rotor's angular swings are the same as the oscillations in a spring mass system. Because of a retarding force that is generally proportionate to speed, oscillations in a spring mass system come to an end. We may try to create equivalent retarding forces in a power system by making the electrical power flow a function of the rate of change of angular difference. Thus, in order to reduce angular difference and have the system "settle down" quickly, the TCSC reactance may be made a function of angular difference and rate of change of angular difference to achieve this, a controller schematic illustration may be employed.

Only when signals are present that correspond to the relative motion of the rotor (typical oscillation frequencies fall between 0.2 and 2 Hz) should this auxiliary controller come on it doesn't have a mechanism for steady-state control. The previously described relatively slow control functions shouldn't be "interfered" with. The controller's output must be gradually reduced until it reaches zero in a steady state. Consequently, this controller is used together with a washout transfer function, which has a steady state gain of 0.

CONCLUSION

Transformers with tap-changing capabilities are often used to manage voltage in transmission and distribution systems. By modifying the transformer's secondary EMF by altering the number of secondary turns, the voltage in the line may be changed using this technique. A voltage regulator produces a fixed output voltage of a predetermined magnitude that is unaffected by changes in the input voltage or the load circumstances. Voltage controllers, in general, are essential in electrical power networks because they manage the voltage at the terminals of consumers. To protect the interests of the consumers, voltage control is crucial in power systems. Some methods of voltage control in power systems include the use of voltage regulators or excitation controls at generating stations, tap-changing transformers, induction regulators, shunt

reactors, shunt capacitors, and synchronous condensers.

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INVESTIGATING DIFFERENT TYPES OF LOAD PROTECTION EQUIPMENT

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ABSTRACT:

The most well-known electrical devices for protection involve the electric fuse, which is utilized for industrial applications as well as home ones. In compared to other electrical protection devices, they offer various benefits such compact overall dimensions, quick response, and low cost. They separate the load from the primary source of power from a protection standpoint. The idea of controlled fusing was established in order to change the time-current characteristic into an adjustable one since the time it takes for a defect to clear is the key parameter. This study describes the controlled fusing idea as it applies to large breaking capacity fuses. Using the suggested controlled fuse, the safety of electronic equipment, particularly for power semiconductors, may be extended to other crucial parameters from the protected electrical infrastructure.

KEYWORDS: *Electrical Circuit, Overcurrent Protection. Protection Device, Power Supply.*

INTRODUCTION

Consistency and protection are the two main goals of electrical circuit protection devices. By cutting off the power supply in a circuit, overcurrent protection guarantees safety by reducing the possibility of fire and electrocution. It could also be important for certain objects to adhere to organisational norms on proper safeguarding. The numerous circuit protection devices must be known to designers. Protection devices shield circuits from high voltages or currents. Electronic circuits address the many types of protective devices used in electrical and electronic circuits as well as the definition of a protection device. By stopping excessive current flow, an electrical device known as a circuit protection device prevents short circuits. For the highest degree of security, there are many different protection devices on the market that provide you access to a comprehensive range of circuit protection tools, such as fuses, circuit breakers, RCCBs, gas discharge tubes, thyristors, and more[1]–[3].

Overcurrent and protective devices are not recent issues. Soon after Volta constructed his first electrochemical cell or Faraday spun his first disc generator, someone graciously furnished these pioneers with their first short circuit loads. The first undersized wire connecting a generator to a load in the late 1800s established the concept of a fuse, and patents on mechanical circuit-breaking devices date back to that period. We might argue that, realistically speaking, no improvement in electrical science can happen without a corresponding breakthrough in protection science. An electric utility provider would never attach a new transformer, generator, or electrical load to a circuit that can't be opened right away by a protective system. In a similar vein, no new electronic power supply should be created by a design engineer that does not

immediately protect its solid-state power components in the case of a short output. Every improvement in electrical technology must have built-in safeguards against overcurrent damage. Anything less makes the component or circuit more vulnerable to harm or quick destruction.

Examples include electromechanical circuit breakers and solid-state power switches. They are used in any electrical systems that one can think of that an overcurrent might harm. As an easy example, think of the electrical system found in a typical industrial laboratory. The utility distribution substation serves as the starting point on a one-line diagram of the radial distribution of electrical energy, which is then followed by an industrial facility and a little lab computer. The system is referred to as being radial since all branch circuits, including utility branch circuits, radiate from central tie points. There is just one feed line per circuit. There are several utility distribution networks, some of which mirror specific feed lines. However, the radial system is the most common and the simplest to protect.

To offer overcurrent protection, cascading current-interrupting devices are linked in series. A dual-element or slow-blow fuse is included at the input of the power supply for the personal computer, starting at the load end. This fuse will enable the 120-volt circuit to be opened in the case of a serious computer malfunction. The large inrush current that occurs briefly when the computer first switches on is hidden by the fuse's slowing element. The fuse's fast element quickly locates and dissipates very large fault currents. The plug strip is protected from an excessive load by the thermal circuit breaker included into the plug strip. The thermal circuit breaker's mechanism is based on the differential expansion of different metals, which in the mechanical opening of electrical connections.

The 120-volt single-phase branch circuit that supplies the plug strip has a branch breaker in the laboratory's main breaker box or panel board. It is a thermal-magnetic combination branch breaker in issue. It has a bi-metallic element that, when heated by an overcurrent, will trip the circuit breaker. Additionally, it has a magnetic-assist winding that, when exposed to large fault currents, accelerates the response in a manner similar to a solenoid. All branch circuits on each phase of the three-phase system of the laboratory merge and pass through the main thermal magnetic circuit breaker for that phase. Just as backup security, this main breaker. If, for whatever reason, a branch circuit breaker fails to halt overcurrent on that particular phase of the laboratory wiring, the main circuit breaker will open shortly after the branch circuit breaker should have opened.

The avoidance of overload requires backup. In a purely radial system, like the laboratory system, we can see the cascade process by which each overcurrent protection device backs up the devices that are downstream from it. If the computer power supply fuse fails, the plug strip thermal breaker will respond after a short period of coordination. The branch breaker would sustain them both, although with significant coordination latency, if it were to fail as well. To provide the primary protection device, which is electrically closest to the overload or fault, a chance to operate first, the backup device needs this coordination lag. The coordination delay overload prevention is the primary method used by a backup system to choose which systems to protect.

The selectivity feature of a protection system enables it to alleviate an overcurrent problem by only turning off the absolute minimum of system functions. A power supply system that is selectively safeguarded will be far more reliable than one that is not. For instance, the lab system's thermal breaker should be the only one capable of handling a short in the computer power cord. All other loads on the branch circuit should also continue to be serviced, along with

the remaining loads in the lab. Even if the plug strip breaker in the main breaker box is forced into interruptive action due to the computer power cable failure, just that particular branch circuit will be de-energized. The other branch circuits in the laboratory can still deliver the loads they have. For a problem with the computer power connection in a total blackout in the lab, two series-connected breakers would have to malfunction at the same time, which is very improbable to happen. Whether an overcurrent can be stopped at a given level depends on the sensitivity of the overcurrent protection mechanism. Regardless of their design or working principles, all overcurrent protection devices generally respond more rapidly as overcurrent levels increase.

Ravi Ponnala et al. in, explored that the primary goal of this article is the construction of a tiny micro grid test bed system with a few sources, a few loads, and several kinds of lumped resistive (R), capacitive (C), and inductive (L) components. Every load was supported by its own electromagnetic before to the development of the electric smart grid. Numerological relays gradually emerged as protective systems advanced. A coordinated protection system was developed of the connection between numerical relays and the ability to communicate with a central computer. Many of the numerical relays have been replaced with clever electronic devices for the monitoring and protection of systems in dynamic states. With the advancement of data connections and the integration of artificial intelligence into the power system, it is now feasible to regulate the power system from a central location. This study describes the use of a fuzzy based expert system (FBES) for fault monitoring and prevention against several fault kinds, including frequency fluctuations, voltage variations, and other fault circumstances.

Kim et al. explored that residential series arc fault detection is difficult and complex due to the vast diversity of arc faults caused by various load types. If not quickly identified, series dc arc faults might in fire incidents and have a negative impact on power systems. The low arc current, lack of a zero-crossing duration, and numerous anomalous behaviours depending on various power load and controller types make them difficult to identify in actual power systems. In instance, when they happen, standard protective fuses may not be engaged. Arc faults that go undetected might in faulty power system performance, property damage, and even fatalities. To ensure the dependable and effective functioning of such systems, it is essential to create a detection system for series arc faults in DC systems. Five time-domain current parameters were selected for arc fault detection in this study: average value, median value, variance value, RMS value, and distance between maximum and minimum values. Several common loads, particularly nonlinear and complex loads like power electronic loads, were selected and analysed. Arc defect detection was carried out using a variety of machine learning techniques, and their detection accuracy was evaluated.

Ankur Srivastava et al. in, provides the experimental verification of a dynamic state estimation-based transmission line protection method for various fault kinds and situations. The protection system makes use of high-frequency real-time sampling readings from sophisticated sensors to assess the transmission line's operational status and create a tripping signal in the event of a malfunction. A physical scaled-down model of a power system, including a transmission line, transformer, synchronous generator, and loads, is used to accomplish the validation. During the validation, the following faults are checked: unbalanced faults under various load situations, high impedance fault, fault current supplied from both ends, concealed failure, external fault, and load change conditions. The findings demonstrate that the method operates as planned and hence demonstrate its effectiveness to find different kinds of flaws. The highest fault detection time is estimated to be 42.5 MS, and the maximum fault clearance time is 82.5 MS, which is

comparable to the protection techniques now in use. The collected show that the technique can identify various fault kinds under various settings and prevent possible relay coordination problems.

DISCUSSION

An electrical component known as a fuse is used in electrical circuits to stop overcurrent. It is made of a metal strip that liquefies when a strong current flows across it. Various fuses with different voltage and current ratings, applications, response times, and breaking capabilities are currently available on the market. Electrical equipment like fuses is essential. The length and current of the fuse are designed to provide enough protection without creating an unnecessary disruption.

Switch circuit

To safeguard an electrical circuit against overloads and short circuits caused by an excessive current source, a kind of switch known as a circuit breaker is utilised. A circuit breaker's main responsibility is to stop the flow of electricity when an issue arises. Unlike a fuse, a circuit breaker may be automatically or manually reset to restore normal operation. Circuit breakers may be used to protect both high-voltage and low-current circuits. They come in a range of sizes, from microscopic devices to large switch gears.

A poly switch or a resettable fuse

A resettable fuse is a passive electrical device that protects electronic circuits against over-current problems. This item is sometimes referred to as a multi fuse, poly fuse, or poly switch. These fuses, which depend on mechanical transformations rather than charge-carrier processes in semiconductors, perform in certain situations similarly to PTC thermistors. Resettable fuses are used in numerous areas where it is difficult to replace components, such as computer power supplies, nuclear applications, or aerospace applications.

RCCB or RCD

When a problem with your home's power supply is discovered, a safety mechanism called a residual current device (RCD) or residual current circuit breaker (RCCB) instantly turns off the energy to avoid electric shock. Since a fuse does not provide protection from overloads or short circuits in the circuit, we cannot replace an RCD with one. To protect the circuit against overload current, RCDs often include a circuit breaker, such as an MCB (miniature circuit breaker) or a fuse. A human cannot be identified by the residual current detector either because they may mistakenly touch both conductors at once. It is possible to test and reset these devices. When an error state has been cleared, a reset button reconnects the conductors, and a test button safely induces a tiny leak condition.

Current Inrush Limiter

This is an illustration of an electrical part designed to lower inrush current to lessen the risk of normal equipment damage, circuit breaker trip page, and fuse blowing. The best inrush current limiters include fixed resistors and NTC thermistors. First of all, when switched on, they have a strong resistance that limits the passage of huge currents. Large current flows are possible during normal operation because NTC thermistors warm up from the current flow. These thermistors are often much better than measurement-type thermistors since they are created expressly for

power applications[4]–[6].

Visitors with Metal Oxide

A varistor, also known as a VDR (voltage-dependent resistor), is an electrical component with a variable resistance that is affected by the applied voltage. The name "varistor" is derived from the term "variable resistor". As the voltage increases, this component's resistance decreases. Much like how resistance will rapidly decrease when a very high voltage increases. They acquire the skills necessary to safeguard electrical circuits throughout this performance's voltage fluxes. Electrostatic discharges and lightning strikes are two examples of flow sources. The most common kind of voltage-dependent resistor (metal oxide varistor) is the MOV.

Gas Discharge Tube

The term "gas discharge tube" or "gas-filled tube" refers to a collection of electrodes encased in a temperature-resistant insulating tube and immersed in a gas. The fundamental Townsend ejection phenomenon, which is connected to electric discharge within gases, is used in these tubes to ionise the gas and generate electrical conduction. Electrical devices that use tubes filled with gas as expulsion lamps include metal halide lamps, fluorescent lights, neon lights and sodium vapour lamps. Three different types of gas-filled tubes thyatrons, ignitrons, and cryotrons are used as switching elements in a range of electrical systems. The voltage required to initiate and maintain discharge is influenced by the force, tube form, and fill gas composition. Although military tubes and power tubes generally utilise glass-wrinkled metal and ceramics, respectively, coverings are typically constructed of glass gas discharge.

Clamping

It's customary to refer to how transient occurrences impact overvoltage protection systems as "crowbar vs. clamping". The system's operational voltage is reduced below that using a crowbar protection device. The crowbar device retunes and enables regular circuit functioning after the temporary is finished. Just a little bit over the functioning voltage of the system, a clamping mechanism briefly traps the voltage[7]–[10].

Defence ESD

This device protects an electrical circuit against an electrostatic discharge (ESD) to avoid a gadget failure. A wide variety of ESD protection products are available from Murata, some of which are very small, designed for high-speed communication, and have noise filters built in. ESD protection devices may also be used in lieu of suppressors, visitors, and Zener diodes (TVS).

Surge prevention device

SPD, or surge protection device, is one kind of component used in an electrical fitting security system. The SPD device is connected in parallel to the power supply circuit, which may be used at all levels of the power supply system. The surge protection device is the most common and well-organized kind of over-voltage protective device. This is all about many types of protective equipment. By deliberately including different protective mechanisms to stop excessive current flows in an electrical circuit, a circuit may be safeguarded. To maintain the highest level of safety, this page offers a description of circuit protection techniques, including circuit breakers, electronic fuses with ESD protection, gas discharge tubes, thermistors, and others.

CONCLUSION

In order to guard against electrical harm and preserve the security of electrical systems, various types of load protection devices are utilised in power systems. These load protection equipment types are listed. An electrical safety device called a fuse works to protect an electrical circuit from overcurrent damage. The device is made out of a metal filament or wire that melts when too much electricity passes through it, breaking the circuit. A circuit breaker is an automatic device that, as a safety measure, interrupts the flow of current in an electric circuit. It is intended to guard against overload or short circuit damage to an electrical circuit. A form of resettable fuse called a polyswitch is used to safeguard electronic circuits from overcurrent situations. When the current rises over a certain threshold, it is a thermally sensitive device that opens the circuit, and it resets when the current falls below that threshold. As a safety measure, residual current circuit breakers (RCCBs) guard against electric shock. It operates by identifying the current imbalance between an electrical circuit's live and neutral wires. An electronic device's protection from overvoltage circumstances is provided by a metal oxide varistor (MOV), a kind of voltage-dependent resistor. When a voltage is applied that is higher than the rated voltage, it is made to conduct a sizable current. A sort of safety measure used to shield electronic circuits from voltage spikes is a gas discharge tube (GDT). It functions by transferring a high voltage surge to ground, shielding the circuit from harm.

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ORGANIZING FOR ADVERTISING AND PROMOTION: THE ROLE OF AD AGENCIES AND OTHER MARKETING COMMUNICATION ORGANIZATIONS

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ABSTRACT:

Organizing for advertising and promotion plays a crucial role in the successful execution of marketing communication efforts. This study explores the significance of ad agencies and other marketing communication organizations in coordinating and implementing effective advertising and promotion campaigns. Through an extensive review of literature, this research examines the theoretical foundations of organizing for advertising and promotion. It explores the roles and responsibilities of ad agencies, in-house marketing teams, public relations firms, media agencies, and other specialized communication organizations in managing and executing marketing communication strategies. An integrated marketing communications program's development and implementation are often labor-intensive processes requiring the work of several people. As consumers, we often pay little attention to the people or businesses behind the imaginative commercials that catch our eye or the competitions.

KEYWORDS: *Account Management, Advertising Agencies, Brand Management, Campaign Coordination, Client Servicing, and Creative Strategy.*

INTRODUCTION

It is crucial for people working in the marketing process to comprehend the nature of the sector as well as the structure and roles of the businesses involved. The introductory vignette illustrates how the advertising and promotion industry is evolving as marketers look for more effective methods to engage with consumers. These modifications are having an effect on how marketers plan their marketing communications as well as how they interact with advertising agencies and other communication experts [1]–[3]. This looks at the numerous organizations involved in the IMC process, their functions, and how they interact with one another. We talk about how businesses set up their internal structures for advertising and marketing. The majority of businesses have an outside advertising firm plan and carry out their advertising. Other IMC skills are provided by many large firms, such as direct marketing, sales promotion, and public relations. As a result, the function of the advertising agency and the entire connection between the firm and agency will get special attention from us.

As more businesses adopt an integrated marketing communications strategy to promotion, the role of other players in the promotional process grows in importance. We also look at these specialist marketing communications companies' function in the advertising process. The article's discussion of whether marketers are better off employing the integrated services of a single, sizable agency or the individual services of several communications professionals serves as its conclusion. The main players in the process are the advertising, or clients. They own the goods,

services, or causes that need to be advertised, and they also provide the money needed to cover advertising and marketing costs. Additionally, the advertisers take on a significant amount of responsibility for creating the marketing strategy and making the final choices on the advertising and promotion strategy to be used. The majority of these tasks may be carried out internally by the company, either via an internal advertising agency or through a department inside it.

The conception, production, and/or placement of the communications message is a specialty of an outside company known as an advertising agency, which is used by many businesses. The agency may also provide additional services to help with the marketing and promotion process. Particularly when marketing a variety of items, many major marketers use the services of many agencies. For its numerous brands, Kraft Foods, for instance, employs up to advertising agencies, while Procter & Gamble employs agencies and two significant media purchasing services firms. Ad agencies are becoming more and more involved in the development of marketing and promotional strategies as partners with advertisers. Another significant player in the advertising and promotion process is the media. The main purpose of the majority of media is to inform or entertain its viewers, readers, or subscribers. However, from the standpoint of the promotional planner, media's function is to provide a setting for the company's marketing communications message. In order for advertisers and their agencies to wish to purchase time or space with the media, they must offer editorial or program content that appeals to consumers. A medium's main goal is to promote itself as a means for businesses to efficiently reach their target audiences with their messages, even while it serves many other purposes that aid marketers in understanding their markets and consumers.

Organizations that provide specialist marketing communications services make up the next category of players. They consist of public relations businesses, interactive agency, direct-marketing firms, and sales promotion firms. These businesses provide services in their specialties. While sales promotion firms create and execute promotional programs like contests and sweepstakes, premium offers, or sample programs, direct-response agencies create and implement direct-marketing campaigns. In order to create websites for the Internet and support marketers as they delve farther into the world of interactive media, interactive firms are being hired. In addition to focusing on a business's connections and interactions with its relevant publics, public relations firms are employed to create and manage publicity for a company, its products, and services.

Almost every corporate organization makes use of marketing communications in some way. But how a business sets up for these initiatives relies on a number of variables, including its size, the number of items it offers, the place of advertising and promotion in its marketing mix, the money allocated for advertising and promotion, and the marketing organization structure. The decision-making process for promotions may include several people from throughout the business. The marketing team has the closest contact to advertising and often participates in numerous decision-making processes, including agency selection, campaign planning, and program assessment. Top management is often concerned with how the advertising program portrays the company, and this may also include participating in advertising choices even if those decisions are outside of its regular duties. Although many individuals both within and outside the organization contribute in some way to the advertising and promotion process, someone inside the company must directly be responsible for running the program. Many businesses have an advertising department run by a communications or advertising manager who reports to the marketing director. A decentralized marketing system is an option that is used by several major multiproduct companies. A separate agency, or in-house agency, might be established inside the business as a third alternative. The

following examines each of these options in further depth.

DISCUSSION

The Centralized System

Advertising is often grouped with other marketing operations like sales, marketing research, and product planning in businesses that split marketing activities along functional lines. With the exception of sales, the advertising manager is in charge of all promotion-related operations. In the most typical illustration of a centralized system, the advertising manager is in charge of budgeting, coordinating the creation and production of advertisements, setting media schedules, and overseeing and managing the sales promotion programs for all of the company's goods and services. The size of the company and the value it puts on promotional activities will determine the precise responsibilities of the advertising manager. The management and personnel carry out the following basic duties.

Planning and Budgeting

The advertising department is in charge of creating advertising and promotion strategies that management will accept as well as suggesting a promotion program based on the overall marketing strategy, objectives, and budget. Annually or whenever a program is being considerably updated, such as when a new campaign is launched, formal plans are provided. While the advertising department creates the promotional budget, upper management often decides how much money should be allocated.

Administration and Execution

The manager is responsible for organizing, supervising, and controlling the operations of the advertising department. The manager is also in charge of overseeing how the strategy is carried out by employees and/or the advertising firm. Working with the production, media, art, copy, and sales promotion divisions is necessary for this. The advertising department is spared of a lot of the operational duties if an outside agency is utilized, but it is still required to examine and approve the agency's plans [4]–[6].

Interdepartmental coordination

The manager is responsible for coordinating the operations of the advertising department with those of other departments, especially those involving other marketing-related duties. For instance, in order to decide which product attributes are significant to consumers and should be highlighted in the company's communications, the advertising department must consult with marketing research and/or sales. Before choosing broadcast or print media, research may provide the media department profiles of product consumers and nonusers. The advertising department may also be in charge of creating tools for sales promotion, advertising materials, and point-of-purchase displays that the sales team may utilize while calling on clients.

Bringing Together External Organizations and Services

Despite having an advertising department, many businesses still employ a lot of other services. Companies could design their advertising campaigns internally while using media buying services to place their advertisements and/or using agencies for collateral services to create brochures, point-of-purchase materials, etc. The department chooses which outside service providers to engage and acts as a liaison between the business and them. The manager will collaborate with

other marketing managers to coordinate efforts and assess results after outside services have been contracted.

When businesses do not have many separate divisions, product or service lines, or brands to market, a centralized organizational structure is often employed. For instance, centralized advertising departments are present in airlines like Southwest, American, and Continental. Because planning and organizing advertising campaigns from a single place makes it simpler for senior management to participate in decision-making about the marketing program, many businesses choose to have centralized advertising departments. Because fewer individuals are engaged in the program choices and as their expertise with making such judgments grows, the process gets simpler, a centralized system may also lead to a more efficient operation.

A centralized organization has inherent drawbacks, however. The advertising staff struggles to comprehend the brand's overarching marketing plan, to start. The department could take a while to react to a product or brand's unique demands and issues. The centralized method may become unworkable when organizations become bigger and create or acquire additional products, brands, or even divisions.

System Decentralized

It may be quite challenging to run all the advertising, promotional, and other duties via a centrally organized department in huge firms with several divisions and a wide range of goods. These enterprises often feature a decentralized organizational structure with independent production, R&D, sales, and marketing departments for different divisions, product lines, or businesses. Many businesses with a decentralized structure, like Procter & Gamble, Gillette Co., and Nestlé, appoint a brand manager to each product or brand. This manager is in charge of the brand's overall management, which includes planning, budgeting, sales, and profit performance. The strategy, execution, and management of the marketing program are under the purview of the brand manager, who may have one or more assistant brand managers.

The advertising manager may study, assess, and discuss with the brand managers the many components of the program. The brand manager's judgments about advertising may be overruled by this individual. The advertising manager may coordinate the efforts of the many agencies in certain multiproduct companies with significant advertising budgets to get media reductions for the company's numerous media purchases.

Each brand gets focused management attention, which is a benefit of the decentralized structure and leads to quicker reaction to both opportunities and challenges. As an illustration, General Motors started using a brand manager system in 1996 in order to strengthen identities and positioning platforms for its 40+ models of cars, trucks, minivans, and sport utility vehicles. The brand manager system is also more adapt and makes it simpler to adjust various aspects of the advertising and promotional program, such as creative platforms and media and sales promotion schedules. The brand managers are fully in charge of the marketing of their cars, which includes determining the target audiences and creating integrated marketing communications strategies that will set the brand apart.

The decentralized method has certain disadvantages. Brand managers often lack both experience and training. A brand manager who lacks a thorough understanding of the capabilities and limitations of advertising and sales promotion may establish the promotional plan for a brand. Brand managers could put too much emphasis on day-to-day operations and administrative

activities while ignoring the creation of long-term initiatives.

Another issue is that individual brand managers often find themselves in a struggle for management support, marketing budgets, and other resources. This may result in unproductive rivalries and even budget misallocation. Budgets may start to be more heavily influenced by the manager's persuasiveness than by the brands' potential for long-term profit. These kinds of issues played a major role in Procter & Gamble's choice to use a category management system. Some businesses have addressed this issue by increasing the responsibilities of advertising and sales promotion managers and their team of specialists. Individual brand managers get advice from staff experts, and decisions about advertising and/or sales promotion are made in collaboration with the brand manager, the advertising and/or sales promotion manager, and the marketing director.

Internal Agencies

Some businesses have internalized their own advertising firms in an attempt to save expenses and keep more control over agency operations. An advertising firm that is established, owned, and run by the advertiser is known as an in-house agency. While some in-house agencies are hardly more than advertising departments, in other businesses they are given a distinct identity and are in charge of spending significant amounts of money on advertising. Calvin Klein, The Gap, Avon, Revlon, and Benetton are a few well-known brands that use in-house agencies. Many businesses just utilize internal agencies; other businesses mix internal and external efforts. For instance, No Fear handles the majority of its advertising in-house, although it does sometimes contract with an outside agency for creative projects. The ability to save money on advertising and marketing is a key benefit of having an internal agency. Companies with substantial advertising expenditures fork out a sizeable sum in the form of media commissions to outside firms. These commissions go to the in-house agency in an internal framework. For less money than outside firms, an internal agency may also handle associated tasks including package design, public relations, and sales presentations and sales force materials. Research by M. Louise Ripley discovered that although merchandising and sales promotion were more likely to be carried out internally, creative and media services were more likely to be conducted outside.

Companies utilize in-house agencies for a variety of reasons, including cost savings. Time savings, negative experiences with outside agencies, and better market knowledge and understanding that result from working on advertising and marketing for the product or service day by day are other factors. Additionally, businesses can better oversee the process and more easily synchronize promotions with their entire marketing strategy. Some businesses use an in-house agency simply because they think it can do the task more effectively than an outside agency could.

In-house advertising companies are criticized for lacking the variety of services and the impartiality and experience of an outside agency. They contend that external firms provide a corporation a more diversified view on its advertising difficulties and better flexibility since they attract the greatest creative talent and have more highly qualified professionals. While working on the same product line in-house, employees may get limited or become stale, but outside agencies may have a range of individuals with diverse experiences and ideas working on the account. Flexibility is higher since an outside agency may be fired if the business is unhappy, as opposed to changes at an inside agency that can take longer and be more disruptive. These factors must be taken into account when evaluating the cost savings of an internal agency. The main factor in

deciding whether to utilize in-house services for many businesses should be the importance of high-quality advertising to their marketing success. In recent years, businesses like Rockport and Redken Laboratories have outsourced their internal labor to external firms. Redken said that this was due to the necessity for a "fresh look" and objectivity, stressing that management becomes too familiar with the product to come up with original, innovative ideas. As businesses develop and their advertising demands and budgets expand, they often use outside firms. In order to manage its advertising, Gateway, for instance, recruited a full-service outside agency in the 1990s as the personal computer business expanded quickly.

Ad agency's function

The tasks carried out by advertising agencies may be carried out by the clients themselves using one of the models covered previously in this, although the majority of big businesses use outside corporations. Here are a few explanations on why advertising work with outside firms. Reasons to Hire an Agency Probably the most important factor in hiring an outside agency is that it gives the customer access to highly qualified professionals who are experts in their industries. The workforce of an advertising agency may consist of creatives, writers, media analysts, researchers, and others with specialized training, expertise, and experience who may aid in promoting the goods or services of the client. Many organizations focus on one sort of company and help their customers by using their industry expertise. The market and its business may be seen objectively by an outside agency since it is not constrained by internal corporate prejudices, rules, or other constraints. The firm may draw on its extensive expertise working on a variety of marketing issues for different clients. For instance, a marketing firm managing a travel-related client may employ people with experience from the airline, cruise ship, travel agency, hotel, and other relevant sectors. The agency can have prior expertise in this field or possibly have handled the advertising account for a rival of the client. As a result, the agency may provide the client industry knowledge [7]–[9].

Agencies for advertising

The services provided and tasks carried out will vary as ad agencies may range in size from a one- or two-person company to huge organizations with more than 1,000 people. This article looks at several agency kinds, the services they provide to customers, and how they are set up.

Full-Service Agencies

Many businesses use so-called full-service agencies, which provide their customers with a complete range of marketing, communications, and promotion services, including planning, developing, and producing the advertisements as well as doing research and choosing media. A full-service agency may also include non-advertising services including public relations and publicity, package design, sales promotions, direct marketing, and interactive capabilities.

Account Services

The ad agency's relationship with its customers is mediated by account services, often known as account management. One or more account executives act as liaisons, depending on the client's advertising budget and size. Understanding the advertiser's marketing and promotion requirements and communicating them to agency staff are the account executive's responsibilities. He or she manages the planning, creation, and production of advertisements by the agency. Additionally, the account executive makes agency suggestions and gets the client's consent. The

account executive serves as the main point of contact between the agency and the client. As such, they are expected to know a lot about the client's business and be able to explain it to other specialists working on the account. The ideal account executive has a solid background in marketing and a comprehensive understanding of all stages of the advertising process.

Marketing Services

The usage of marketing services has significantly expanded during the last 20 years. As agencies become more aware of the need to have a thorough grasp of the target demographic in order to engage with their clients' consumers successfully, research is one service that is receiving more attention. The planning stage of advertising starts with a detailed study of the current situation that is based on data and knowledge of the target market.

The majority of full-service agencies have a research whose job it is to acquire, examine, and evaluate data in order to create ads for their customers. This may be accomplished either by primary research, in which case the research department plans, carries out, and interprets the study, or through the utilization of secondary sources of data. The research division sometimes purchases studies produced by independent syndicated research companies or consultants. After interpreting these reports, the research team disseminates the knowledge to other agency employees working on the relevant case [10].

The research department may also plan and carry out research to gauge the effectiveness of potential advertisements for the agency. For instance, copy testing is often done to ascertain how the intended audience would likely understand the messages generated by the creative professionals. An agency's media department evaluates, chooses, and negotiates for the media time or space that will be utilized to spread the client's advertising message. The media department is tasked with creating a media strategy that will successfully reach the target audience and convey the message. Since media time and/or space make up the majority of the client's advertising budget, this department must create a strategy that communicates with the target demographic while still being economical. Media professionals need to be aware of the media's target markets, rates, and degree of fit with those markets. To create a successful media strategy, the media department analyzes data on demographics, magazine and newspaper readers, radio listeners, and consumer TV watching habits. By acquiring the real time and space, the media buyer puts the media strategy into action.

The media division is playing a more and bigger role in the operations of the agency. As vital as an agency's capacity to produce advertisements is now how well it can negotiate rates, use the wide variety of media vehicles, and engage with customers in other ways. To better serve their customers, several of the larger agencies and/or their parent corporations have established independent media services firms. As a full-service media planning and purchasing firm, for instance, Leo Burnett created Starcom, while McCann Erickson Worldwide created Universal McCann and Foote Cone and Belding Worldwide created Horizon. Although they may also provide media services on their own to other customers, these media firms mainly serve the agency's clients. To reduce costs and boost media effectiveness, a number of major marketers have consolidated their media buying with these formidable media services firms. While Universal McCann of the Interpublic Group manages over \$1 billion in global Nestlé media business, General Motors' \$3.6 billion media business was integrated with Starcom.

The majority of the tasks required for full-service agencies to create and carry out the advertising

campaigns for their customers are handled by the research and media divisions. Some businesses aid their customers in other areas of promotion by providing them with extra marketing services. A company may have a department dedicated to creating competitions, rewards, promotions, point-of-sale materials, and other sales materials called a sales promotion department, or merchandising department. It could have a PR/publicity department, package designers, and direct-marketing experts. For the purpose of building websites for their customers, several firms have established interactive media divisions. Many full-function agencies have developed expertise and made services available in these additional promotional areas as a result of the rising popularity of integrated marketing communications.

Many of the biggest advertising agencies in the world realized in the late 1980s that their customers were diverting an increasing amount of their promotional budgets from traditional media advertising and toward other forms of marketing communication, including direct marketing, public relations, sales promotion, and event sponsorship. In reaction to this development, a lot of these agencies started buying businesses that were experts in these fields, converting them into profit-driven divisions or subsidiaries that often found themselves competing for a client's promotional money. Although the agencies may use these experts to highlight their IMC capabilities, there wasn't much focus on unifying the different communication tasks.

As the new century gets underway, a lot of large advertising firms are making the transition to IMC as they realize they need to adopt a method of doing business that doesn't necessarily entail advertising. With only sporadic usage of print and TV advertising, many businesses are creating campaigns and plans employing event marketing, sponsorships, direct marketing, targeted radio, and the Internet. Because it is not well understood by many agency veterans and is ripping another chunk out of the marketing communications budget pie, the internet offers a special challenge to conventional agencies.

By enhancing its competencies in fields including direct marketing, interactive, customer relationship, management/database, event marketing, and sports marketing, Foote, Cone & Belding is reinventing itself as a New Economy advertising firm. Through its "Model of One," which guarantees that all of these services are flawlessly connected and unified, FCB boasts of being able to provide customers with a wide range of integrated marketing communications services. Every effort is coordinated by a single team and is driven by a single broad creative concept.

Chris Jones, the CEO of J. Walter Thompson, has promoted a concept dubbed Thompson Total Branding that turns JWT into the manager of a client's brand. TTB entails taking what the firm refers to as a "Branding Idea" and creating a comprehensive communications strategy that aids in determining which integrated marketing platforms can express it the most effectively. "Agencies are finally realizing that our job is creating branding solutions and, while those may involve advertising, it's not necessarily about advertising," says one of the corporate executives. That represents a significant shift in how we work. The ability to employ a variety of IMC tools has aided the company in gaining new business and fostering stronger ties with current customers.

While conventional agencies have long advocated integrated marketing, few really put it into practice. However, if these agencies want to remain competitive going forward, they must change their approach. In order to finally get their personnel to concentrate on providing complete communications solutions for their customers' companies, they are retraining them in the usage

and best practices of several IMC technologies. This time, it seems that the shift toward integrated marketing communications is genuine.

Services for the Arts

The department of creative services is in charge of developing and carrying out ads. Copywriters are the people who come up with the concepts for the advertisements and create the headlines, subheads, and body content. They often create a rough first graphic layout for the print advertisement or television commercial. They may also be engaged in deciding the fundamental appeal or topic of the advertising campaign. The art department is in charge of how the advertisement appears, while copywriters are in charge of what the message is. For print advertisements, the art director and graphic designers create layouts, which are renderings of the final artwork for the advertisement. A storyboard, which is a series of frames or panels that show the ad in still form, is the layout used for TV commercials. The creative team collaborates to create advertisements that communicate the core ideas that were chosen as the foundation of the creative strategy for the client's product or service. The creative director of the agency, who is in charge of all the organization's advertising, usually supervises writers and artists. The director establishes the department's creative concept and could even become personally engaged in making advertising for the biggest customers of the firm.

The advertisement is sent to the production department when the text, layout, graphics, and mechanical specifications have been completed and authorized. The majority of agencies outsource the creation of the completed advertising to printers, engravers, photographers, typographers, and other vendors. The accepted storyboard has to be transformed into a finished commercial for broadcast production. The production team may pick an independent production studio and oversee the casting of actors and locations for the sequences in the advertisement. To put the creative idea into an advertisement, the department could engage a freelance director. For instance, a number of businesses, such as Nike and Kmart, have hired filmmaker Spike Lee to helm their advertisements; on the other hand, Airwalk Shoes hired John Glen, who helmed a number of the James Bond films, to helm its TV pieces. When there are significant financial stakes, it's common for copywriters, art directors, account managers, members of research and planning, and clients' representatives to participate in production choices.

It often takes many months and a large team to create an advertising. Coordination of the creative and production processes may be a big issue at big firms with lots of customers. To ensure that the commercials are finished on time and that all deadlines for submitting the advertising to the media are fulfilled, a traffic department organizes every stage of production. The agency's traffic department may be housed there, or it may be distinct and part of the media, account management, or creative services divisions.

Finance and management

An advertising agency, like any other firm, has to be managed and carry out fundamental operational and administrative tasks including accounting, finance, and human resources. It must also make an effort to attract new business. To carry out these tasks, large agencies need administrative, managerial, and clerical personnel. The majority of an agency's revenue is used to pay workers' salaries and benefits. To maximize output from its staff, an agency must properly manage them.

Organization and structure of the agency

Full-service advertising firms must create an organizational structure that will satisfy both their internal demands and those of their customers. The majority of medium-sized and large agencies have a departmental or group organization. Under the departmental system, each agency function is organized as a distinct department that may be accessed as required to carry out its area of expertise and provide services to all of the agency's customers. The creative department is in charge of ad layout, writing, and production, while marketing services is in charge of any research or media choices and purchasing, and account services is in charge of client interaction. Some organizations choose the departmental structure because it allows staff members to get experience in handling a range of client accounts.

The group system is used by many major organizations, where employees from each department collaborate in groups to handle specific accounts. One or more media professionals, including media planners and buyers, a creative team made up of copywriters, art directors, artists, and production staff, one or more account executives, and one or more account supervisors are in charge of each group, which is led by an account executive or supervisor. Individuals from other divisions, such as marketing research, direct marketing, or sales promotion, may also be a member of the group. Depending on the client's billings and the account's significance to the agency, the group's size and makeup might vary. The group members could be given exclusive responsibility for a single customer for particularly critical accounts. They could take care of many minor customers in certain agencies. Because there is consistency in the account's servicing and personnel learn a great deal about the client's business, many agencies favor the group arrangement.

Alternative Organizations and Services

Not all agencies are large full-service ones. Many smaller organizations demand that their staff members do a range of tasks. For instance, account executives may do their own research, plan their own media calendar, and organize the production of advertisements that the creative department has written and developed. Many marketers, including some huge businesses, are just interested in a few of the specialized services that agencies have to offer rather than paying for a full-service agency's services. Several alternatives to full-service agencies have developed over the last couple decades, including creative boutiques and media purchasing businesses.

Unique Boutiques A company that solely offers creative services is known as a creative boutique. These specialist businesses have emerged in response to certain customers' requests to outsource solely the creative services while maintaining internal capabilities. The customer may go outside for creative talent if it feels that more creativity is needed or if it feels that its own personnel lack the necessary qualifications. Some marketers are turning to the film industry instead of conventional agencies for original ideas for their commercials.

Services for buying media

Independent businesses with a focus on purchasing media, particularly radio and television time, are known as media buying services. Typically, agencies and clients create their own media plans and use the purchasing service to carry them out. A few media purchasing businesses do aid marketers in formulating their media plans. Media purchasing services may save a small agency or client money on media purchases since they buy such enormous quantities of time and space and earn such substantial savings. For their efforts, media purchasing services are compensated with a charge or commission.

CONCLUSION

The report finishes by making suggestions on how firms can set up their advertising and marketing plans. These suggestions include choosing the best marketing communication partners based on skill, experience, and cultural fit; encouraging open and collaborative relationships with communication organizations; outlining roles and responsibilities in detail; laying out goals and expectations; and establishing regular communication and reporting mechanisms. This study emphasizes the critical role that advertising agencies and other marketing communication companies play in planning and carrying out advertising and promotion efforts. These organizations support the efficacy and accomplishment of marketing communication initiatives by using their knowledge, resources, and connections to the industry. This aids companies in achieving their marketing goals and forging deep connections with their target consumers. As specialized media have proliferated, the process of buying advertising media has become more complicated. As a result, media buying services have carved out a niche by specializing in the research and acquisition of advertising time and space.

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TOOLS FOR BUSINESS PROCESS MANAGEMENT

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ABSTRACT:

Business Process Management (BPM) is a discipline that focuses on optimizing and managing organizational processes to improve efficiency, effectiveness, and agility. Various tools and technologies are available to support BPM initiatives and facilitate process modeling, analysis, automation, monitoring, and optimization. This study explores the key tools used in Business Process Management, highlighting their functionalities and benefits in enabling organizations to streamline and enhance their processes. Process modeling tools are essential for documenting and visualizing business processes. These tools provide graphical representations, such as flowcharts or process diagrams, to depict the sequence of activities, decision points, and interactions within a process. They enable stakeholders to understand and communicate the structure and flow of processes, facilitating analysis and improvement efforts.

KEYWORDS: *Business Process Modeling, Collaboration Software, Customer Relationship Management (Crm) Systems, Data Analytics, Process Automation.*

INTRODUCTION

Over 100 software companies, including IBM, Oracle, and TIBCO, provide solutions for different BPM-related tasks. These technologies serve organizations in a number of ways, including helping them identify and catalog processes that need improvement, model and enforce business rules for carrying out processes, and integrate current systems to enable new or redesigned processes. Additionally, analytics are offered by BPM software solutions for determining if process performance has improved and for calculating the effect of process changes on important business performance metrics. Some BPM solutions employ software to interact with all of the systems a business uses for a certain process in order to find problem areas while documenting and monitoring business processes to assist businesses in identifying inefficiencies. AIC, a Canadian mutual fund business employed Sajus BPM monitoring software to look for irregularities in its procedure for updating accounts after each customer transaction. Sajus is an expert in goal-based process management, which is concerned with identifying the root causes of organizational issues via process monitoring before implementing tools to remedy those issues[1]–[3].

Another class of tools enforces business standards and automate specific portions of business processes so that staff members carry out those tasks more consistently and effectively. For instance, American National Insurance Company, which provides investment services as well as life, health, property, and casualty insurance, uses Pega BPM workflow software to synchronize customer support procedures across four business units. To help customer support agents navigate a single view of a client's information that was kept in many systems, the program developed rules. The enhanced method raised the workload capacity of customer care representatives by

192% by removing the requirement to switch between many apps at once to address client and agent demands.

A third class of tools aids organizations in integrating their current systems to assist process enhancements. They automatically oversee business-wide operations, gather information from many sources and databases, and produce transactions in a number of connected systems. For instance, the Star Alliance of 15 airlines, which includes United and Lufthansa, utilized BPM to integrate its current systems and build standard procedures that were used by all of its members. One project combined 90 distinct business processes from nine airlines and 27 old systems to develop a new service for frequent flyers on member airlines. The BPM software provided airline management with a new business process model that demonstrated how to communicate data across the different systems by documenting how each airline handled frequent flyer information. The Interactive Session on Organizations gives an example of a corporation that used business process management to gain a competitive advantage. Burton Snowboards discovered that several of its business procedures had become obsolete, as is typical of any firm that quickly grows from a tiny operation to a well-known brand on a worldwide scale. Burton has worked hard to strengthen these procedures and transform their flaws into assets.

Overview of Systems Development

The development of new information systems results from a procedure for resolving organizational issues. A new information system is created to address an issue or group of problems that the company believes it is currently experiencing. The issue might be that management and staff are aware that the organization is not operating as well as it could or that it needs to seize fresh possibilities to improve performance. Systems development refers to the processes involved in creating an information system that addresses a business issue or opportunity.

Small Business Processes Help Burton Snowboards Speed Ahead

We often picture snow-covered slopes, acrobatic jumps, and high-flying amusement when we hear the word "snowboarding." We seldom consider how to make corporate processes more efficient. But for Burton Snowboards, snowboarding is a business. a market leader and industry innovator. Burton is a company that develops, manufactures, and sells snowboarding gear, apparel, and associated accessories. Burton was established in 1977 by Jake Burton Carpenter and has its headquarters in Burlington, Vermont. Burton is a multinational company with operations in Japan, Austria, and the United States. It now serves clients in 27 different countries. In spite of an increasing number of rivals, Burton still dominates the U.S. snowboarding industry, controlling over 40% of it at its height. Burton now has a new set of challenges as it continues to grow into a worldwide corporation, including enhancing its systems for inventory, supply chain, buying, and customer support.

Burton has a challenging dilemma when it comes to stocking and managing inventory since seasonal fluctuations and product line upgrades greatly influence inventory adjustments. Customers' comments are taken seriously by Burton, and the company will act rapidly to address their demands. For instance, Burton's manufacturing line must be capable of making this alteration fast and efficiently if a rider tries a jacket and suggests moving a zipper. A competitive need is being adaptable and active. A SUSE Linux enterprise server, an Oracle database, common hardware, and SAP enterprise software have all been deployed and are being maintained by

Burton. That is a considerable distance from a lone Vermont woodworking business. Burton's information systems were a patchwork of underused, inconsistently installed software before these changes. The business had to manually assign products to orders and consumers. Burton originally used SAP in 1997 to start modernizing its IT environment, and the business has been using SAP ever since. However, Burton needed to improve its system. Burton received assistance from SAP analysts in identifying the top five transactions that were crucial to its business operations and required system improvement. In order to improve the efficiency of its business processes, Burton had to uncover too complex procedures, backlogs, and design flaws. The available-to-promise procedure, for instance, was taking several hours to finish. In order to provide its retail clients and dealers more exact information regarding the availability of items not presently in stock, Burton intended to hasten this process. This procedure currently takes 20 minutes to complete.

DISCUSSION

The handling of overdue purchase orders in the procure-to-pay process, which entails all the steps from buying goods from a supplier to paying the supplier, the order-to-cash process, the electronic data interchange inventory feed extract transaction, and other processes were also in need of improvement. Using EDI technology, Burton's several warehouses automatically transmit inventory data to one another. Each day, hundreds of transactions take place at each warehouse as thousands of products are moved from one to the next. Burton discovered that the inventory reporting procedure was ineffective and that it was difficult for suppliers and customers to get the most recent information about which goods were in stock at which warehouse.

Burton and SAP collaborated to enhance supply chain effectiveness and warehouse communication. A management dashboard created with SAP's assistance demonstrates how efficiently a crucial process is operating at a certain moment. The dashboard's data assists Burton's key users in identifying gaps, irregularities, or other areas that need closer monitoring. All of these procedure updates were particularly helpful during Burton's "reorder" season. Long before winter arrives, Burton's dealers arrange orders to supply their shops. As customers begin purchasing the goods, the retailers place fresh orders with Burton to either restock their inventory or purchase new goods. They may now access more up-to-date information about product availability and process orders more quickly.

Analysis Of Systems

Systems analysis is the study of an issue that a business uses an information system to try to solve. It entails describing the issue, pinpointing the root causes, outlining the remedy, and stating the information needs that a system solution must satisfy. The systems analyst draws out a road map of the current structure and systems, detailing the main data owners and users as well as the hardware and software already in use. The systems analyst then goes into depth about the issues with current systems. The analyst may determine the issue areas and goals a solution will pursue by looking into paperwork, work routines, and system operations as well as by interviewing important system users and witnessing system activities. The answer often entails developing a brand-new information system or upgrading an already existing one.

To ascertain if that solution is practical or reachable from a financial, technological, and organizational aspect, the systems analysis also involves a feasibility assessment. The proposed system's estimated return on investment, if the technology required for it is readily accessible and

manageable by the firm's information systems professionals, and whether the organization can handle the changes the system would bring about are all factors considered in the feasibility study. The systems analysis method often identifies a number of potential alternatives that the business might consider and evaluates their viability. A written systems proposal report outlines the costs and advantages of each option, as well as their pros and cons. Management must decide which combination of costs, advantages, technological characteristics, and organizational implications constitutes the best option. Identifying the precise information needs that must be satisfied by the selected system solution is perhaps the systems analyst's most difficult responsibility. The most fundamental aspect of a new system's information requirements is identifying who, where, when, and how requires what information. The process of developing a thorough description of the tasks that the new system must carry out is known as requirements analysis. It meticulously outlines the goals of the new or changed system. A major factor in system failure and expensive system development costs is poor requirements analysis. A system that is built on the incorrect set of criteria will either need to be abandoned due to poor performance or will need significant changes. Some issues may be resolved without the use of an information system; instead, management must be changed, employees must get more training, or already-existing organizational processes must be improved. Systems analysis may still be necessary to identify the issue and find the best solution if the issue is information-related[4]–[6].

Design of Systems

Systems design demonstrates how the system will achieve this goal, whereas systems analysis outlines what a system should accomplish to satisfy information needs. An information system's design is its overarching framework or model. It comprises of all the parameters that give the system its shape and structure, much as a building or house's plan. The systems designer specifies the components of the system that will carry out the functions found via systems analysis. All of the administrative, organizational, and technical elements of the system solution should be included in these requirements. Information systems may be designed in a variety of ways, much like homes or other structures. Each design is a one-of-a-kind synthesis of all technological and organizational elements. The simplicity and effectiveness with which a design satisfies user needs within a particular set of technical, organizational, budgetary, and temporal restrictions distinguishes it from competing designs.

The Function of Consumers

The whole system-building process is driven by the user information needs. To guarantee that the system represents their business goals and information demands, not the prejudices of the technical personnel, users must have enough authority over the design process. Working on the design improves user comprehension and system acceptance.

Finishing The Process of Systems Development

The subsequent stages of the systems development process convert the solution criteria created during systems analysis and design into an information system that is completely functional. Programming, testing, conversion, production, and maintenance make up these last processes.

Programming

System requirements that were created during the design stage are converted into software program code during the programming step. Many businesses no longer develop new systems

from scratch nowadays. Instead, they buy the software that satisfies the demands of a new system from outside sources, such as software packages from a commercial software vendor, software services from an application service provider, or outsourcing companies that create specialized software for their clients.

Testing

To determine if the system generates the desired outcomes, extensive and exhaustive testing must be done. Will the system achieve the required outcomes under known circumstances? is a question that testing resolves."In systems project planning, the time required to respond to this issue has historically been underestimated. Testing takes time because test data must be meticulously generated, findings must be examined, and system changes must be made. In certain cases, the system may need to have some components redone. There are significant hazards involved with skipping this stage.

Unit testing, system testing, and acceptance testing are the three categories of activities that make up testing an information system. Unit testing, often known as program testing, involves individually evaluating each program in the system. Although this aim is theoretically attainable, it is usually recognized that the point of such testing is to ensure that programs are error-free. Instead, then concentrating on identifying all the methods to make a program fail, testing should be seen as a tool to detect flaws in programs. Problems may be resolved after they have been identified. System testing examines the overall efficiency of the information system. It looks for inconsistencies between how the system really operates and how it was intended, as well as whether separate parts will work together as intended. Performance times, file storage capacity, management of peak loads, restart and recovery capability, and manual processes are some of the areas that are looked at.

The system's readiness for deployment in a production environment is officially confirmed via acceptance testing. Users access system testing, and management examines them. The new system is officially approved for installation when everyone is certain that it satisfies their criteria. A systematic test strategy is developed by the systems development team in collaboration with users. All of the preparations for the tests we just mentioned are included in the test plan. The process of switching from the old system to the new one is known as conversion. The parallel strategy, the straight cutover strategy, the pilot study strategy, and the phased approach strategy are the four basic conversion approaches that may be used.

The old system and its possible successor are used concurrently for a while until everyone is certain that the new one functions properly. The previous system may still be utilized as a backup in the case of mistakes or processing outages, making this the safest conversion method. This strategy, however, is quite costly, and running the additional system can call for more personnel or resources. It is essential to include the numerous conditions to be evaluated, the prerequisites for each condition examined, and the anticipated outcomes when creating a test plan. Information systems experts and end users must both contribute to test strategies. On a designated day, the new system completely replaces the old system using the direct cutover technique. It is a highly hazardous strategy that can end up costing more than operating two systems concurrently if major issues with the new system are discovered. No alternative system exists to fall back on. The cost of corrections, interruptions, and dislocations might be quite high. The new technology is only made available to a small portion of the business, such as a single department or operational unit, as part of the pilot study plan. When the pilot version is finished and functioning well, it is

simultaneously or gradually deployed across the remainder of the company.

The new system is introduced gradually using a phased approach plan, either by organizational units or by functions. A new payroll system can start with hourly employees who are paid weekly then six months later include salaried staff if, for instance, the system is introduced by function. If the system is implemented organizational unit by organizational unit, corporate headquarters may be converted first, followed four months later by outlying operational units. End users must be educated to utilize the new system before switching from the old one. During the conversion period, comprehensive documentation that explains the system's functionality from both a technical and end-user perspective is prepared for use in training and day-to-day operations. This phase of the systems development process is crucial since improper training and documentation may lead to system failure.

Production and Upkeep

The system is referred to as being in production after the new one has been set up and the conversion is finished. The system will be evaluated by users and technical experts at this stage to see how well it has achieved its original goals and to see if any tweaks or alterations are necessary. A formal postimplementation audit document may sometimes be created. The system has to be maintained while it is in use in order to fix mistakes, satisfy requirements, or increase processing efficiency once it has been fine-tuned. Maintenance is the process of making adjustments to a production system's hardware, software, documentation, or processes in order to fix problems, conform to new specifications, or increase processing effectiveness.

Debugging or fixing urgent production issues takes up around 20% of the time spent on maintenance. Another 20% are worried about updates to system software, hardware, reports, files, or data. However, user improvements, better documentation, and system component recoding for increased processing speed make about 60% of all maintenance labor. By using better systems analysis and design techniques, the amount of effort in the third category of maintenance difficulties might be greatly decreased. Alternative modeling and system design approaches exist. The most prevalent are object-oriented development and structured approaches.

Since the 1970s, information systems have been documented, analyzed, and designed using structured approaches. The term "structured" describes the procedures as being step-by-step with each stage building on the one before it. Top-down structured approaches go from the most study to the most particular degree of detail—from the general to the specific. Process-oriented structured development methodologies place a strong emphasis on modeling the processes—that is, the actions—that gather, store, change, and distribute data as it moves through a system. These techniques isolate processes from data. Every time someone wishes to perform an action on a specific piece of data, a new programming method has to be defined. The data that the software sends to the processes for action.

The data flow diagram is the main tool for displaying a system's component activities and the data flow between them. The data flow diagram provides a logical visual representation of information flow by segmenting a system into manageable-sized modules. It is a straightforward data flow diagram for a mail-in university course registration system that precisely defines the operations or transformations that take place inside each module as well as the interfaces that connect them. The rounded boxes depict procedures that show how data is transformed. The square box is a representation of an external entity, or an information source or recipient, who is not a part of the

model-building system. Data stores, which may be either human or automated inventories of data, are represented by the open rectangles. The transfer of data between processes, external entities, and data repositories is shown by the arrows, which stand for data flows. They include data packets, and next to each arrow is a list of the name or content of each data flow[7]–[10].

Students must submit registration forms together with their names, ID numbers, and the course numbers they desire to enroll in, as shown by this data flow diagram. In step one, the system checks the university's course file to make sure each chosen course is still active. The file separates available courses from ones that have been postponed, canceled, or filled. The decisions made by Process 1.0 determine which of the student's choices may be accepted or rejected. Process The student is enrolled in the courses for which they have been accepted by 2.0. It recalculates the class size and changes the student's name and identification number in the university's course file. The course number is shown as closed if the allowed number of students has been met. Additionally, Process 2.0 refreshes the university's student master file with details about new students and address changes. Then, Process 3.0 sends a confirmation of registration letter to each student applicant detailing the courses for which he or she is enrolled and highlighting the course choices that were not possible to complete. The diagrams may be used to represent both lower-level details and higher-level processes. A complicated process may be decomposed into progressively more detailed steps using tiered data flow diagrams. A high-level data flow diagram may be used to separate a whole system into smaller systems. With the use of second-level data flow diagrams, each subsystem may be further broken down into lower-level subsystems, and so on until the lowest level of detail is achieved.

A data dictionary is an additional tool for structured analysis that provides details on both individual data items and data groups within a system. In order for systems architects to fully grasp the types of data that data flows and data storage include; the data dictionary describes their contents. The transformation taking place at the lowest level of the data flow diagrams is described by process specifications. They describe each process's reasoning. Software design is represented using hierarchical structure charts in structured approach. The top-down structure chart demonstrates each level of design, how it relates to other levels, and where it fits into the overall design framework. A program or system's principal function is initially taken into account in the design process. This function is then divided into subfunctions, and each subfunction is then broken down further until the lowest level of detail is achieved.

CONCLUSION

In conclusion, in order for firms to efficiently simplify, optimize, and manage their processes, business process management solutions are essential. Organizations may understand, visualize, automate, and constantly improve their processes by using tools for process modeling, analysis, automation, monitoring, and optimization. Utilizing these technologies helps businesses increase operational effectiveness, customer happiness, and agility, which helps them gain a competitive edge and experience long-term success. However, putting BPM tools into practice calls for careful planning that takes organizational preparedness, process complexity, and technological compatibility into account. To promote broad acceptance, organizations must make sure the tools they choose are compatible with their BPM objectives, interact with current systems, and have user-friendly interfaces.

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OBJECT-ORIENTED DEVELOPMENT: A REVIEW STUDY

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ABSTRACT:

Object-Oriented Development (OOD) is a software development approach that emphasizes the design and implementation of software systems based on the concepts of objects and classes. This study explores the principles, benefits, and challenges associated with Object-Oriented Development, highlighting its significance in building modular, reusable, and maintainable software applications. OOD revolves around the concept of objects, which represent real-world entities or abstractions. Objects encapsulate data and behavior, allowing for modular and independent units of functionality. These objects are organized into classes, which define the common properties and behaviors of a group of objects. Inheritance enables the creation of hierarchical relationships between classes, facilitating code reuse and promoting the concept of polymorphism.

KEYWORDS: *Encapsulation, Inheritance, Message Passing, Modularity.*

INTRODUCTION

Structured approaches work well for modeling business processes, but they struggle with modeling data. Additionally, they consider data and processes as conceptually distinct entities, even if this separation would appear odd in the actual world. Both analysis and design employ several modeling paradigms. These problems are addressed by object-oriented development. The object is the fundamental building block of systems analysis and design in object-oriented programming. This structural diagram offers a comprehensive perspective of the complete payroll system by displaying the highest or most study level of design. Data and the particular methods used to that data are combined into an object. Only the actions, or methods, linked to an object may access and modify data that is contained inside it. Programs deliver a message to an object asking it to do an action that is already incorporated in it, as opposed to giving data to procedures. The system is represented in the model as a set of items and the connections between them. Objects must cooperate with one another in order for the system to function since processing functionality is housed inside objects rather than in distinct software applications[1]–[3].

Class and inheritance are the cornerstones of object-oriented modeling. A class of things, or broad groupings of related objects, share certain characteristics. Classes of objects may add variables and behaviors specific to each item while still inheriting the structure and behavior of a more generic class. Instead of beginning from scratch each time, new classes of objects are formed by selecting an existing class and defining how it varies from the current class. We can see how class and inheritance function in this example, which demonstrates the links between classes in regards to workers and their compensation. The superclass, or common ancestor, of the other three classes is called Employee. Subclasses of Employee include Temporary, Hourly, and Salaried. The top

compartment of each box has the name of the class, the middle compartment contains the characteristics for each class, and the bottom compartment contains the list of actions. Each subclass stores characteristics that are unique to that particular kind of employee, whereas the Employee superclass stores features that are shared by all workers. For instance, hourly wages and overtime rates are specific to hourly workers. A generalization route from the subclass to the superclass is shown by a solid line, indicating that the traits shared by the subclasses Salaried, Hourly, and Temporary may be generalized to the superclass Employee.

Compared to conventional organized development, object-oriented development is more gradual and iterative. Systems builders provide the functional requirements of the system during analysis, outlining its most crucial features and what the suggested system must do. The system's user interactions are examined in order to identify objects, which might be both data and processes. During the object-oriented design phase, the actions and interactions of the objects are described. Classes are collections of related objects that are organized into hierarchies where a subclass inherits the properties and functions of its superclass. The information system is constructed by turning the design into computer code, adding new classes that were developed during the object-oriented design phase, and reusing classes that are already present in a library of reusable software objects. The establishment of an object-originated database may also be part of the implementation process. The final system must undergo extensive testing and evaluation. Reusable objects have the potential to cut down on the time and expense associated with producing software by allowing businesses to utilize previously generated software objects as building blocks for subsequent applications. Utilizing some already-existing elements, altering others, and introducing a few fresh ones allows for the creation of new systems. Object-oriented frameworks have been created to provide reusable, partially completed programs that the company may further modify into full applications[4]–[6].

DISCUSSION

Computer-Aided Software Engineering

Computer-aided software engineering, also known as computer-aided systems engineering, offers software tools to automate the approaches we just mentioned, hence minimizing the developer's need to do repetitive tasks. CASE technologies also make it easier to organize team development activities and provide comprehensive documentation. Accessing one other's files to check or edit one another's work allows team members to readily share their work. The right application of the technologies may also result in modest productivity gains.

With the aid of CASE tools, you may automatically create charts and diagrams, as well as code generators, report generators, data dictionaries, comprehensive reporting capabilities, analysis and validation tools, and documentation generators. CASE tools often aim to boost output and quality via

1. Establishing a uniform development process and design discipline
2. Enhancing dialogue between consumers and technical experts
3. Using a design repository to quickly access, organize, and correlate design components
4. Automating laborious and prone to mistake analytical and design processes
5. Automating the creation, testing, and deployment of code

Design diagrams and specification validation functionalities are available in CASE tools. CASE technologies help iterative design by automating changes and revisions and offering prototype resources. All of the information defined by the analysts during the project is kept in a CASE information repository. The repository contains entity-relationship diagrams, data definitions, process requirements, screen and report formats, notes and comments, and test results. It also contains data flow diagrams and structure charts. CASE tools need organizational discipline to be utilized well. Every participant in a development project is required to follow a development process as well as a shared set of naming conventions and standards. The finest CASE tools impose common practices and standards, which may deter people from using them in circumstances where there is a lack of corporate discipline.

Advanced Systems-Building Methods

Systems vary in terms of their technical complexity, scale, and the organizational issues they are intended to address. To address these disparities, a variety of systems-building strategies have been created. The conventional systems life cycle, prototyping, application software packages, end-user development, and outsourcing are the other approaches that are covered in this section.

Life Cycle of Traditional Systems

The earliest technique for creating information systems is called the systems life cycle. The life cycle methodology divides system development into distinct phases and uses a phased approach to system construction. Although there are differing views among systems development experts on how to divide the phases of systems development, they essentially match to those we have just discussed. A formal division of labor between end users and information systems experts is maintained by the systems life cycle approach. End users are only allowed to provide information needs and approve the technical staff's work; the majority of the systems analysis, design, and implementation work is done by technical professionals like systems analysts and programmers. The life cycle also stresses formal requirements and documentation; therefore, a systems project will produce a lot of papers.

Large sophisticated systems that need a systematic and comprehensive requirements analysis, established specifications, and stringent controls over the system-building process are still built using the systems life cycle. The systems life cycle method, however, may be expensive, time-consuming, and rigid. The systems life cycle is primarily a "waterfall" strategy, where duties in one stage are finished before work for the next stage starts, despite the fact that systems designers may switch between phases as needed. Activities may be repeated, but if requirements or specifications need to be changed, a lot of new papers must be created and the process must be redone. This promotes specification freezing rather early in the development process. Since many tiny desktop systems have a tendency to be less organized and more customized, the life cycle method is also not ideal for them[7]–[9].

Prototyping

Building an experimental solution quickly and affordably for end customers to assess is known as prototyping. Users that engage with the prototype may better understand their information needs. The final system may be built using the prototype that the users approved. The prototype is a functioning model of an information system or a component of the system, however it is just supposed to be a rough sketch. The prototype will be significantly improved when it is put into use until it perfectly satisfies user requirements. The prototype may be transformed into a

polished production system once the design is complete. Iterative systems development refers to the process of creating a preliminary design, testing it, improving it, and attempting it again. This is possible because the actions needed to create a system may be performed again. Compared to the traditional life cycle, prototyping is openly iterative and actively encourages modifications to system design. It has been stated that prototyping substitutes deliberate iteration for unplanned rework, with each version more properly reflecting user needs.

Prototyping Procedures

Step 1: Determine the fundamental needs of the user. Only enough time is spent with the user by the systems designer to identify their fundamental information demands.

Step 2: Create a first prototype. The systems designer uses technologies for swiftly producing software to quickly produce a functioning prototype.

Use the prototype in step three. Users are urged to interact with the system to assess how well the prototype satisfies their requirements and to provide recommendations for its improvement.

Step 4 is to improve and revise the prototype. The system developer takes note of any adjustments the user wants and adjusts the prototype as necessary. The cycle then goes back to Step 3 once the prototype has been altered. Repeat steps 3 and 4 until the user is pleased.

The accepted prototype next turns into an operational prototype and provides the final application parameters after no more iterations are necessary. Sometimes the system's production version is based on the prototype. The benefits and drawbacks of prototyping is most helpful when there is some ambiguity about requirements or design solutions. It is often used to create the user interface for information systems. Prototyping fosters active end-user participation across the whole systems development life cycle, which increases the likelihood that the resulting systems will meet user needs. Rapid prototyping, however, may omit crucial system development processes. If the finished prototype functions relatively well, management may not see the necessity for redesigning, reprogramming, or doing exhaustive testing and documentation to create a polished production system. Some of these hurriedly built systems could find it difficult to handle a big number of users or a lot of data in a production setting.

Development for End-Users

Some information system types may be created by end users with little to no official support from technical experts. End-user development is the term for this occurrence. This is made feasible by a collection of software tools referred to as fourth-generation languages. Fourth-generation languages are software tools that let people build software programs or make reports with little to no technical support. Some of these fourth-generation technologies also increase the productivity of expert programmers.

Fourth-generation programming languages often have less procedural behavior than traditional programming languages. The series of actions, or processes that instruct the computer on what to do and how to accomplish it must be specified in procedural languages. Nonprocedural languages need simply describe what has to be done; they are not required to provide specific instructions on how to do the job. PC software tools, query languages, report generators, graphics languages, application generators, application software packages, and extremely high-level programming languages are the seven categories of fourth-generation languages. The chart displays the tools in order of their usability for non-programmers. The majority of PC software tools and query

languages are more likely to be used by end users. Query languages are software tools that instantly respond online to non-predefined information queries, such as "Who are the best sales representatives? Query languages are often linked to database management systems and data management tools.

Overall, systems produced by end users may be finished more quickly than those developed via the traditional systems life cycle. Giving users the freedom to define their own business requirements enhances requirements gathering and often results in greater user engagement and system satisfaction. Fourth-generation tools, however, are still unable to completely replace traditional tools for certain commercial applications because they are unable to manage the processing of many transactions or applications that need a great deal of procedural logic and updating.

Because end-user computing takes place outside of conventional methods for information systems management and control, it also presents hazards to organizations. Rapid system development without a structured development approach might lead to insufficient testing and documentation. Systems outside of the typical information systems department might make it difficult to maintain control over data. Management should regulate the development of end-user applications by requiring cost justification of end-user information system projects and by establishing hardware, software, and quality standards for user-developed applications in order to assist organizations in maximizing the benefits of end-user application development.

Outsourcing and Application Software Packages

Today's software is often bought from outside sources rather than being created in-house. The software might be rented from a software service provider, purchased from a commercial vendor, or produced specifically for a company by an external outsourcing company. Many systems throughout the course of the last few decades have been constructed using application software packages as a base. Many programs, such as payroll, accounts receivable, general ledger, or inventory management, are used by all business companies. A generalized system will satisfy the needs of numerous companies for such universal functions and regular procedures that do not vary much over time.

The majority of an organization's needs may be met by a software package, eliminating the need for the firm to develop custom software. Utilizing the prewritten, predesigned, and pretested software packages from the bundle allows the business to save time and money. The majority of the system's continuing maintenance and support is provided by package suppliers, including improvements to keep the system abreast of new business and technological advancements. Many packages come with the ability to be customized if an organization has certain needs that the bundle does not cover. A software package may be customized using customization features to match the specific needs of an organization without compromising the bundled program's integrity. Additional programming and modification work may become very costly and time-consuming if a lot of customization is necessary, negating many of the benefits of software packages.

Systems analysis includes a package assessment effort when a system is designed utilizing an application software package. The capabilities offered by the package, flexibility, user-friendliness, hardware and software resources, database needs, installation and maintenance efforts, documentation, vendor quality, and pricing are the most crucial evaluation factors. A

Request for Proposal, which is a comprehensive set of queries sent to packaged-software providers, is often the basis of the package assessment process. The company no longer has complete control over the systems design process after a software package is chosen. The design effort will instead focus on attempting to shape user needs to fit the package's characteristics rather than explicitly adjusting the system design specifications to account for user requirements. If the needs of the organization clash with how the package functions and the package cannot be altered, the company will have to modify its processes to fit the package.

Outsourcing

A company may hire an outside company that specializes in offering these services to create or run information systems if it doesn't want to utilize its own resources for the task. One kind of outsourcing is the use of cloud computing and software as a service provider, which we discussed in number 5. Companies who subscribe to the service utilize the computer hardware and software it offers as the technological foundation for their own systems. An organization may contract with an outside vendor to design and develop the software for its system, but that vendor would run the system on its own computers. This is another example of outsourcing. The outsourcing provider may be local or international. The main reason for domestic outsourcing is because outsourcing companies have assets, resources, and capabilities that their customers do not. A very big organization could need to hire an extra 30 to 50 individuals with specialized knowledge of supply chain management software, licensed from a vendor, in order to implement a new supply chain management system. It makes more logical and is often less costly to outsource this job for a year rather than engage permanent new staff, the majority of whom would require substantial training in the software package, and then release them once the new system is constructed.

When it comes to outsourcing to other countries, cost is usually the deciding factor. A talented programmer in Russia or India makes between \$10,000 and \$20,000 USD annually, vs \$73,000 for a similar programmer in the United States. The cost and complexity of coordinating the work of international teams in distant places have been significantly lowered by the Internet and low-cost communications technologies. Numerous offshore outsourcing companies provide world-class technological resources and expertise in addition to cost reductions. Some of these benefits have lately been diminished by wage inflation abroad, and some jobs have relocated back here. Nevertheless, there is a very good probability that you will collaborate with international teams or offshore outsourcers at some time in your career. If your business takes the time to weigh all the risks and make sure outsourcing is suitable for its unique requirements, it will have the greatest chance of success. Any company that outsources its applications must have a complete understanding of the project, including its needs, implementation strategy, expected outcomes, cost factors, and performance indicators.

Many businesses undervalue the costs of finding and vetting information technology service providers, switching to a new vendor, upgrading in-house software development processes to match those of outsourcing providers, and keeping track of vendors to ensure they are carrying out their contractual obligations. Companies will need to set aside resources for project management, contract negotiations, managing travel expenditures, and documenting needs. According to experts, it might take anywhere between three months and a full year to completely shift work to an offshore partner and ensure that the vendor is well-versed in your industry. Dealing with cultural differences that reduce productivity and handling human resources concerns, such firing or moving local staff, add extra expenses to outsourcing to other countries.

Some of the projected advantages of outsourcing are undermined by all of these unanticipated expenses. Companies should exercise extra caution when hiring an outsourcer to create or manage applications that provide them a competitive edge.

90% of General Motors Corporation's IT services, including those for its data centers and application development, were outsourced. The business recently made the decision to handle just 10% of its IT infrastructure externally, moving 90% of it in-house. Cost-cutting is crucial, but GM's principal motivation for reducing outsourcing is to regain control over its information systems, which the corporation says were holding it back from acting swiftly on business possibilities. By bringing information systems in-house, GM will find it simpler to reduce the number of IT applications on its long list by at least 40%, switch to a more standardized platform, finish cutting-edge IT projects more quickly, and gain better control over customer and production data, which had been spread across too many different systems. The carmaker will operate four software development centers and combine 23 data centers from across the globe into just two, both in Michigan.

Development of Applications for The Digital Firm

In the context of the digital company, companies must be able to swiftly add, modify, and retire their technological capabilities in order to take advantage of new opportunities, such as the need to provide apps for mobile platforms. Businesses are beginning to use quicker, more informal development processes that provide quick answers. Businesses are increasingly relying on fast-cycle methodologies like rapid application development, joint application design, agile development, and reusable standardized software components that can be assembled into a comprehensive set of services for e-commerce and e-business in addition to software packages and outside service providers.

Development of Applications Quickly

Systems developers are able to develop functional systems considerably more quickly than they could with conventional systems-building techniques and software tools because to the use of object-oriented software tools, reusable software, prototyping, and fourth-generation language tools. This approach of developing functional systems in a little amount of time is known as fast application development. Iterative prototyping of important system components, the automation of program code creation, tight collaboration between end users and information systems experts, and the use of visual programming and other tools for creating graphical user interfaces are all possible components of RAD. Frequently, prebuilt components may be used to build simple systems. The process need not be sequential; important stages of development might take place concurrently.

Joint application design is a method that is sometimes used to hasten the creation of information needs and the creation of the first systems design. JAD hosts an interactive session where information systems experts and end users may talk on the design of the system. JAD workshops may greatly speed up the design process and include users at a high level when properly planned and managed. By dividing a major project into a number of smaller subprojects that are finished in a certain amount of time utilizing iteration and constant feedback, agile development focuses on the quick delivery of functional software. A team works on each mini-project as if it were a full project, which includes planning, requirements analysis, design, coding, testing, and documentation. The next iteration will see improvements or the inclusion of additional features as

developers understand the needs. This makes it possible for the project to modify more rapidly and lowers overall risk. Agile approaches emphasize face-to-face contact over written documentation, promoting collaboration and prompt and efficient decision-making.

Development Based on Components and Web Services

Some of the advantages of object-oriented development for creating systems that can adapt to quickly changing business contexts, including Web applications, have previously been discussed. Software components for common operations, such as a graphical user interface or the ability to place orders online, have been created as groupings of objects to speed up the construction of software. These components may be merged to form complex commercial applications. Component-based development is a method of developing software that allows the assembly and integration of pre-existing software components to create a system. These software components are increasingly emerging from cloud services. By integrating commercially available components for shopping carts, user authentication, search engines, and catalogs with software for their own particular business needs, businesses are utilizing component-based development to construct own e-commerce solutions.

Service-Oriented Computing and Web Services

Web services have the ability to carry out a number of tasks on their own and may also work with other web services to carry out more complicated tasks like purchasing, ordering things, or checking credit. Web services are software components that enable communication and data sharing across operating systems, programming languages, and client devices, which may significantly reduce system development costs while generating new potential for business cooperation[10]–[12].

CONCLUSION

A potent strategy for creating modular, reusable, and maintainable software systems is object-oriented development. Using the ideas of objects, classes, inheritance, and polymorphism, programmers may build extensible, adaptable systems that can be extended to meet new needs. OOD has many advantages, but it also requires careful planning and a firm grasp of object-oriented ideas. The full potential of Object-Oriented Development may be realized by developers by using object-oriented tools and languages in the right way to build scalable and resilient software applications. Extensible Markup Language and other open protocols and standards were used to create Web services, which were described as loosely connected, reusable software components that allow applications to interact with one another without the need for specialized development. Web services may be used as tools for developing new information system applications or improving current systems, in addition to facilitating internal and external integration of systems. These software services claim to be more affordable and simpler to integrate than proprietary components since they rely on a common set of standards.

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